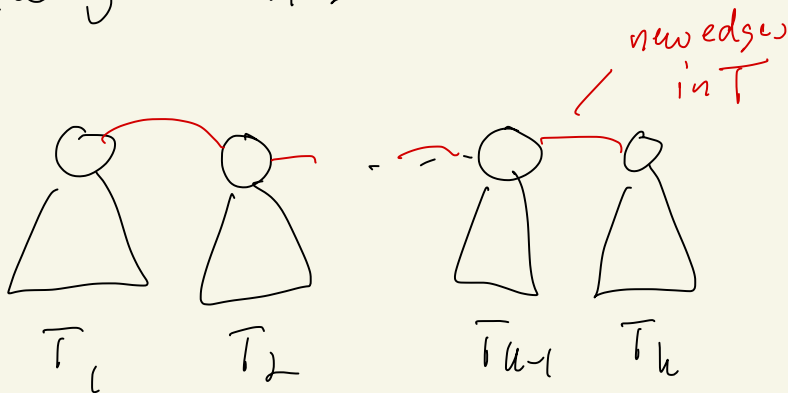


Proposition 10.5 If X is a separator of G and
 $t\omega(G-X) \leq t$ then $tw(G) \leq t + |X|$

Proof:

Let $(\{X_i | i \in I_1\}, T_1) \dots (\{X_i | i \in I_k\}, T_k)$
 be tree-decompositions of the connected
 components G_1, G_2, \dots, G_k of $G-X$

- add the vertices of X to all
 bags in these k tree-decompositions
 and join T_1, T_2, \dots, T_k :



The largest bag in $\{X_i' | i \in I_1 \cup \dots \cup I_k\}$
 has size $|X| + t$ where t is the maximum width
 of the k t.d. above.

Constructing good tree-decomposition

Theorem Deciding for given G, k whether $tw(G) \leq k$ is NP-complete

We know that we can find $tw(G)$ in pol. time when G is chordal as $tw(G) = w(G) - 1$ and we can construct an optimal tree-decomp in pol time.

This follows from the proof of (i) \Rightarrow (iii) in

Theorem 4.8 of Golombic chapter 4

Theorem (Bodlaender 1996) There is an algorithm running in time $O(f(k)(n^m))$ for constructing an optimal t-d of given G when k is fixed

$f(k)$ grows very fast :-)

In practice we just need a heuristic to find a t-d. of G with width close to $tw(G)$ or at least width at most $c \cdot tw(G)$ for some constant c

\exists 4-approximation algorithm for tree-width which runs in time $O(c^{tw(G)})$ for some constant c . so it is exponential in $tw(G)$

General approach for finding a good tree-decomp:

1. If G is chordal, use the algorithm that follows from the proof of Thm 4.8 in Golombic

2. If $G=(V,E)$ is not chordal we try to make it chordal by adding a small set of new edges E' so that $G'=(V,E \cup E')$ is chordal and then proceed as in 1.

Here we used the important property that $\text{tw}(H) \geq \text{tw}(H')$ for every subgraph (induced or not) H' of H :

If $(\{X_i \mid i \in I\}, T)$ is a tree-decomp for H

then $(\{X'_i \mid i \in I\}, T)$ is a tree-decomp for H'

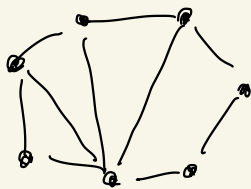
when $X'_i = X_i \cap V(H')$

Important: We don't need an optimal t.d of G
in order for the algorithm we shall see to work.

It is only the running time which gets worse if
the width of our decomposition is larger
(running time grows exponentially with the width)

Planar Graphs (just a few remarks)

a graph G is **outerplanar** if it has a planar
embedding in which every vertex is adjacent to the
outer face

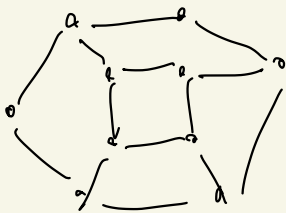


all outerplanar G
are hamiltonian

• r -outerplanar:

• 1-outerplanar = outerplanar

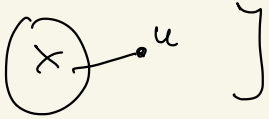
• For $r \geq 1$ G minus vertices on outer cycle
is $(r-1)$ -outerplanar



2-outerplanar

Known fact:

For a planar graph G , the size of a minimum vertex cover, the size of a minimum dominating set and $tw(G)$ are linearly related

$[X \subseteq V(G)$ is a dominating set if each vertex $u \in V - X$ is adjacent to X ]

Theorem 10.13 Let G be a planar graph
If G has a vertex cover or a dominating set of size k then $tw(G) \in O(\sqrt{k})$

This is best possible in terms of the exponent:

For the $k \times k$ -grid we saw that the tree-width is k while we clearly have that min VC and min dom. set are both of size $O(k^2)$

10.4 Dynamic programming for vertex cover

The algorithm below finds an optimal vertex cover of G no matter which tree-decomposition of G we use. It is only the running time which depends on the width of the tree-decomposition we use.

The running time of the algorithm depends exponentially on the width of the decomposition but if this is small the algorithm works fine even for large graphs!

Theorem 10.14 Given $G=(V,E)$ and a tree-decomposition $(\{X_i \mid i \in I\}, T)$ of G which has width w , we can find an optimal vertex cover in time $O(2^w \cdot w \cdot |I|)$

Proof:

Central fact: There are at most $2^{|X_i|}$ possible vertex covers of $G[X_i]$ for each bag X_i

goal: Combine these vertex covers (efficiently!) via T

For each X_i we associate a table A_i

A_i has 2^{n_i} rows when $n_i = |X_i|$

Then rows corresponds to all the different subsets of X_i

$$X_i = \{X_{i,1}, X_{i,2}, \dots, X_{i,n_i}\}$$

The j 'th row corresponds to
the j 'th subset X_i^j of X_i \rightarrow

For each row j we also associate
a number $m_i(X_i^j)$ when

row	$X_{i,1}$	$X_{i,2}$	$X_{i,3}$	\dots	X_{i,n_i}
1	0	0	0	\dots	1
2	0	0	0	\dots	0
\vdots	\vdots	\vdots	\vdots	\dots	\vdots
j	\vdots	\vdots	\vdots	\dots	\vdots
2^{n_i}	1	1	1	\dots	1

$$m_i(X_i^j) = \min \{ |V'| \mid V' \subseteq V \text{ is a vertex cover of } G \text{ and } V' \cap X_i = X_i^j \}$$

So $m_i(X_i^j)$ is the size of a smallest VC of G
whose intersection with X_i is precisely X_i^j .

Clearly if X_i^j is not a vertex cover of $G[X_i]$, then there is no such V' above and
hence we set $m_i(X_i^j) = \infty$

Step 1 table initialization (setting values of $m_j(c_i)$'s)

For every $i \in I$ and every row j of A_i :

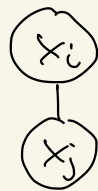
$$m_i(X_i^j) := \begin{cases} |X_i^j| & \text{if } X_i^j \text{ is a VC of } G[x_i] \\ \infty & \text{otherwise} \end{cases}$$

Note that once an ' ∞ ' appears this subnt can never be used

Step 2 Dynamic programming

method: process decomposition tree ($\{X_i | i \in I\}, T$)
from leaves toward the root (root T arbitrarily)

with updating data for X_i via a child X_j :



Rename such that $X_i = \{z_1, z_2, \dots, z_s, v_1, v_2, \dots, v_{t_i}\}$

$X_j = \{z_1, z_2, \dots, z_s, u_1, u_2, \dots, u_{t_j}\}$

where $X_i \cap X_j = \{z_1, z_2, \dots, z_s\}$

Consider a mapping $C: Z \rightarrow \{0,1\}$ and say that
a mapping C_p (from X_i or X_j to $\{0,1\}$) agrees with C
on Z if $C_p(w) = C(w) \quad \forall w \in Z$

In terms of subnts: the subnt X_i^p of X_i agrees with the
subnt Z' of Z if and only if $X_i^p \cap Z = Z'$

$\forall \text{ subnt } Z' \subseteq Z:$

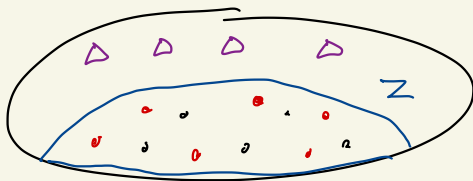
$\forall \text{ subnt } X_i^p \subseteq X_i \text{ s.t. } X_i \cap Z = Z'$

$$m_i(X_i^p) := m_i(X_i^p) + \min \{ m_j(X_j^q) \mid X_j^q \cap Z = Z' \} - |Z'|$$

$\Delta = \text{vertices of } X_i^p - X_j$

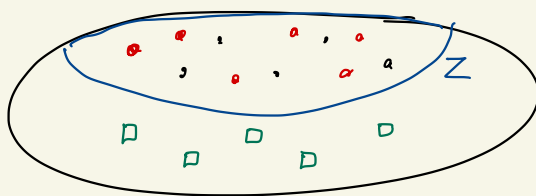
$$\begin{aligned} \odot &= X_i^p \cap Z \\ &= Z' \\ &= X_j^q \cap Z \end{aligned}$$

$\square = \text{vertices of } X_j^q - X_i$



X_i

$Z' = \odot$



X_j

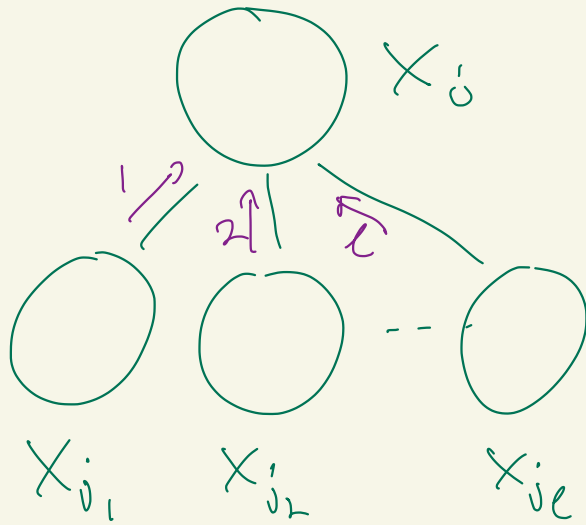
We count red vertices twice in $m_i(X_i^p) + m_j(X_j^q)$
so we subtract $|Z'|$

Notes:

- We can use a vector to keep track of subnts of X_i, X_j and Z

- We can save a pointer to the row of A_j which give the minimum above

When X_i has children $X_{j_1}, X_{j_2}, \dots, X_{j_\ell}$
we update A_i against each of
 $A_{j_1}, A_{j_2}, \dots, A_{j_\ell}$ successively:



Step 2 continues until the
root has been completely updated

Step 3 Constructing a minimum vertex cover

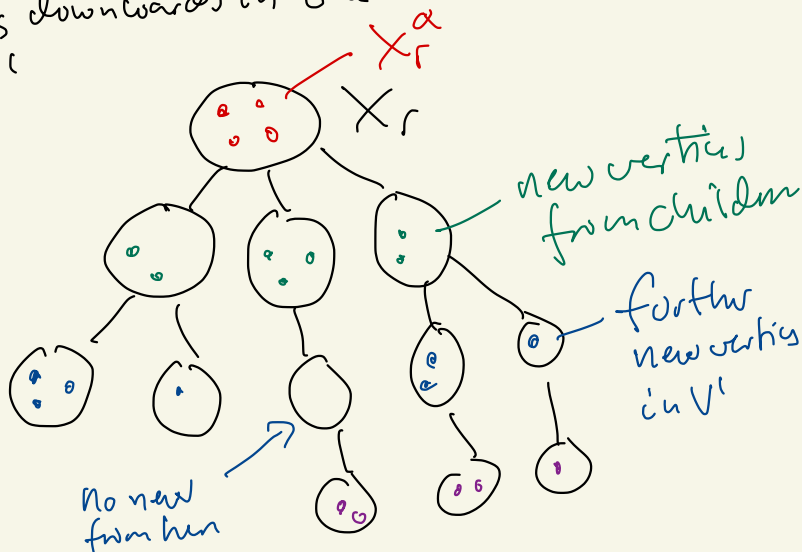
The size of a minimum vertex cover can be found from $\min \{m_r(X_r^\alpha) \mid \alpha \text{ row of } A_r\}$ where X_r is the root bas of T

We can construct a minimum VC V' as follows

- Start by setting $V' = X_r^\alpha$ where row α of A_r gave the minimum above

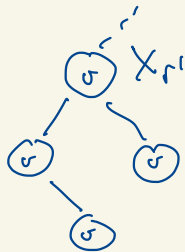
- Using the pointers which show which cover for each child caused an update of $m_r(X_r^\alpha)$ we can collect all vertices of V' that are in the children of X_r

- Continuing downwards in the tree we collect all of V'



Correctness:

- a) As $V = \bigcup_{i \in I} X_i$ every vertex of G has been considered for inclusion in V'
- b) $\forall e \in E$ we have $e \in X_i$ for some i so every edge is covered as we only deal with substs X_i^p of X_i for which $m_i(X_i^p) < \infty$
- c) By the consistency property, the bags of T which contain a vertex v form a subtree T_v of T and via the roots of T in v we get a unique rooting of T_v



Hence v is in V' precisely when $v \in X_{r1}^q$ where this was the root of A_{r1} and to update the parent of X_{r1}

By step 2 the value of $m_{r1}(X_{r1}^q)$ is updated precisely from those substs of the children of X_{r1} which contain v so v ends up in V' only if it is in all the updating substs of T_v

Running time

updates A_i via A_j :

First find $Z = X_i \cap X_j$ and sort elements of X_i, X_j such that $X_i = \{z_1, z_2, \dots, z_s, v_1, v_2, \dots, v_{t_i}\}$ $Z = \{z_1, \dots, z_s\}$

$$X_j = \{z_1, z_2, \dots, z_s, u_1, u_2, \dots, u_{t_j}\}$$

By lexicographic sorting we can order A_i and A_j such that

A_i :

0110101	all rows with this prefix

A_j :

0110101	all rows with this prefix

Go through A_i from row 1 to row $2^{|X_i|}$

For each set of rows whose prefix is the same subset Z' of Z

Go through the rows of A_j whose Z -prefix correspond to Z' and find best subset (row) X_j^g (the one with the lowest $m_j(X_j^g)$)

For every subset (row) X_i^p of X_i with prefix Z' set $m_i(X_i^p) = m_i(X_i^p) + m_j(X_j^g) - |Z'|$

This takes time $O(2^w w)$:

- We can use sorting to arrange A_i and A_j as we wanted them in time $O(2^w w)$ as $|X_i|, |X_j| \leq w+1$ and $|A_i| = 2^{|X_i|}$ $|A_j| = 2^{|X_j|}$
- After sorting we just visit each row of A_i, A_j once to collect first X_j^Z and then update $m_i(X_i^p)$ for all p such that $X_i^p \cap Z = X_j^Z \cap Z$.

T has $|I|-1$ edges so the total time is $O(2^w |I|)$
□.