Near-optimal Algorithms for Online Linear Programming

Zizhuo Wang

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Joint work with Shipra Agrawal and Yinyu Ye

July 7th, 2014

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Introduction

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For example, in a linear program

$$\begin{array}{ll} \text{maximize}_{\mathbf{X}} & \pi^{T} \mathbf{x} \\ \text{subject to} & A \mathbf{x} = \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0}, \end{array}$$

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Online linear programming problems

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In the online version of the problem: we only know B_i 's at the start.

- The constraint matrix is revealed column by column sequentially along with the corresponding objective coefficient.
- An irrevocable decision must be made as soon as a column arrives without observing or knowing the future data.

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$$\begin{array}{ll} \mathbf{x} & \sum_{t=1}^{n} \pi_t x_t \\ \mathbf{p} & \sum_{t=1}^{n} \mathbf{a}_{it} x_t \leq B_i, \quad \forall i = 1, ..., m \\ & \mathbf{0} \leq x_t \leq 1, \qquad \forall t = 1, ..., n \end{array}$$

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 Applications: revenue management, channel allocation in communication networks, charging allocation for electric vehicles, etc.

Our Objective

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$$\sum_{t=1}^{n} \pi_t x_t$$

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We call the above problem the *offline problem*. And we denote the optimal value of it by *OPT*.

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We call the above problem the *offline problem*. And we denote the optimal value of it by *OPT*.

Our objective: to find a decision rule for the online problem such that it achieves *near-optimal* performance, i.e., an algorithm that can achieve values close to *OPT*.

Model Assumptions

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The algorithm is evaluated on the expected performance over all the permutations comparing to the offline optimal solution, i.e., an algorithm A is *c*-competitive if and only if

$$E_{\sigma}\left[\sum_{t=1}^{n}\pi_{t}x_{t}(\sigma,\mathcal{A})\right]\geq c\cdot OPT$$

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- ► Worst case model: Too conservative, no algorithm can achieve better than O(1/n) approximation of the optimal offline solution [Babaioff et al 2008].

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- i.i.d. model: Need distribution information. Performance might suffer if the actual input distribution is not as assumed.
- Our assumption is strictly weaker than the i.i.d. model

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Theorem

We propose an algorithm such that for any fixed $\epsilon > 0$, our online algorithm is $1 - O(\epsilon)$ competitive for online linear programming on all inputs when

$$B = \min_i B_i \ge \Omega\left(\frac{m\log(n/\epsilon)}{\epsilon^2}\right)$$

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Theorem

For any online algorithm for the online linear program in random permutation model, there exists an instance such that the competitive ratio is less than $1 - O(\epsilon)$ if

$$B = \min_i B_i \le \frac{\log(m)}{\epsilon^2}$$

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Our algorithm is quite different from theirs due to the higher dimension

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- We consider a much more general problem
- ► Their results is weaker by a factor or e and also depend on OPT which is not known until the problem is solved. (Our condition can be verified before solving the problem)

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Dual Optimal Price

For the offline linear program, there exists a dual price vector p[∗] for each goods such that, x[∗]_t = 1 if π_t > a^T_t p[∗] and x[∗]_t = 0 otherwise, is near optimal

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Learning the price:

Our online algorithm works by learning a price vector p̂. The price vector is determined by solving the dual problem using existing arrival data.

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Learning the price:

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We first show a one-time learning algorithm to illustrate this idea. Then we show that we can improve the algorithm by updating the price vector more frequently.

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One-Time Learning Algorithm

1. Set $x_t = 0$ for all $t \le \epsilon n$

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One-Time Learning Algorithm

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- 2. Solve the ϵ part of the problem

$$\begin{array}{ll} \text{maximize}_{\mathbf{X}} & \sum_{t=1}^{\epsilon n} \pi_t x_t \\ \text{subject to} & \sum_{t=1}^{\epsilon n} a_{it} x_t \leq (1-\epsilon)\epsilon B_i \quad i=1,...,m \\ & 0 \leq x_t \leq 1 \qquad \qquad t=1,...,\epsilon n \end{array}$$

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Get the optimal dual solution $\hat{\mathbf{p}}$;

3. Determine the future allocation $x_t(\hat{\mathbf{p}})$ as:

$$x_t(\hat{\mathbf{p}}) = \begin{cases} 0 & \text{if } \pi_t \leq \hat{\mathbf{p}}^T \mathbf{a}_t \\ 1 & \text{if } \pi_t > \hat{\mathbf{p}}^T \mathbf{a}_t \end{cases}$$

If $a_{it}x_t(\hat{\mathbf{p}}) \leq B_i - \sum_{j=1}^{t-1} a_{ij}x_j$, set $x_t = x_t(\hat{\mathbf{p}})$; otherwise, set $x_t = 0$.

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By the complementarity conditions of LP, if we can show that $\sum_{t=1}^{n} a_{it} x_t(\hat{\mathbf{p}}) = B_i$ for each *i*, then $x_t(\hat{\mathbf{p}})$ is the optimal solution to the offline problem.

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Lemma With probability $1 - \epsilon$,

$$(1-3\epsilon)B_i \leq \sum_{t=1}^n a_{it}x_t(\hat{\mathbf{p}}) \leq B_i, \forall i=1,\ldots,m$$

given $B \geq \frac{6m\log(n/\epsilon)}{\epsilon^3}$.

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given $B \geq \frac{6m\log(n/\epsilon)}{\epsilon^3}$.

The proof uses intensively concentration inequalities (Hoeffding-Bernstein Inequalities) and union bound arguments

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Analysis Idea Continued

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Then by the above lemmas, it is easy to show that with high probability $\sum_{t=1}^{n} \pi_t x_t(\hat{\mathbf{p}}) \ge (1 - 3\epsilon) OPT$.

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Analysis Idea Continued

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Lemma

Let OPT(S) denote the optimal value of the linear program

$$\begin{array}{ll} \text{maximize}_{\mathbf{X}} & \sum_{t \in S} \pi_t x_t \\ \text{subject to} & \sum_{t \in S} a_{it} x_t \leq \epsilon B_i, \quad i = 1, ..., m \\ & 0 \leq x_t \leq 1, \qquad t \in S. \end{array}$$

over random sample $S \subset N$ where $|S| = \epsilon |N|$, and OPT(N) denote the optimal value of the original offline linear program. Then,

$E[OPT(S)] \le \epsilon OPT(N)$

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Analysis Idea Continued

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- ► With high probability, the objective value is near-optimal if we include the initial *e* portion
- With high probability, the first e portion of the objective value, a learning cost, doesn't contribute too much.

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Summarizing all the lemmas above:

- With high probability, we never violate the inventory constraint
- With high probability, the objective value is near-optimal if we include the initial e portion
- ► With high probability, the first e portion of the objective value, a learning cost, doesn't contribute too much.

Therefore, we proved that our one-time learning algorithm is $1 - O(\epsilon)$ -competitive if $B \ge \frac{6m \log(n/\epsilon)}{\epsilon^3}$.

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- The one-time learning algorithm only computes the price once.
 - Potential improvement might be made by updating the price dynamically during the process.

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Question

How often should we update the price?

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Dynamic Price Updating Algorithm

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At time $\ell \in \{\epsilon n, 2\epsilon n, ...\}$, the price is the optimal dual solution to the following linear program:

$$\begin{array}{ll} \text{maximize}_{\mathbf{X}} & \sum_{t=1}^{\ell} \pi_t x_t \\ \text{subject to} & \sum_{t=1}^{\ell} a_{it} x_t \leq (1-h_\ell) \frac{\ell}{n} b_i \quad i=1,...,m \\ & 0 \leq x_t \leq 1 \qquad \qquad t=1,...,\ell \end{array}$$

where

$$h_{\ell} = \epsilon \sqrt{\frac{n}{\ell}}$$

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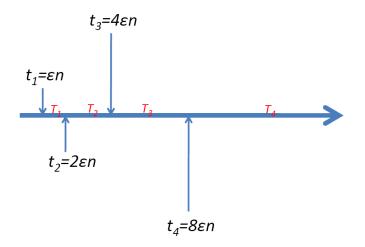
where

$$h_{\ell} = \epsilon \sqrt{\frac{n}{\ell}}$$

And this price is used to determine the allocation for the next immediate period.

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Geometric Pace of Price Updating



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Zizhuo Wang Online Linear Programs, TOLA

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In this algorithm, we update the price log₂ (1/ϵ) times during the entire time horizon.

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Dynamic Price Updating Algorithm

- In this algorithm, we update the price log₂ (1/ϵ) times during the entire time horizon.
- ► The numbers h_ℓ play an important role in improving the condition on B in our main theorem. It balances the probability that the inventory constraint ever gets violated and the lost of objective value due to the factor 1 h_ℓ.

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- In this algorithm, we update the price log₂ (1/ϵ) times during the entire time horizon.
- ► The numbers h_ℓ play an important role in improving the condition on B in our main theorem. It balances the probability that the inventory constraint ever gets violated and the lost of objective value due to the factor 1 h_ℓ.
- Choosing large h_ℓ (more conservative) at the beginning periods and smaller h_ℓ (more risk neutral) at the later periods, we can control the loss of objective value by an ε order while the required size of B can be weakened by an ε factor.

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The proof is similar to the proof of the one-time learning algorithm. We first show the following lemma:

Lemma

For any $\epsilon > 0$, with probability $1 - \epsilon$:

$$\sum_{t=\ell+1}^{2\ell} a_{it} x_t(\hat{\mathbf{p}}^{\ell}) \le \frac{\ell}{n} b_i, \quad \text{for all } i \in \{1, \dots, m\}, \ \ell \in \{\epsilon n, 2\epsilon n, \dots\}$$

given
$$B = \min_i b_i \geq rac{10m\log{(n/\epsilon)}}{\epsilon^2}$$
.

This lemma states that for each time period, with high probability, the inventory consumed by $x(\hat{\mathbf{p}})$ is less than the proportional total inventory.

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Next we need to show that by introducing a factor h_{ℓ} , the loss of objective value is small.

It is easy to see that at period ℓ , the lost of objective value is about $h_{\ell} \cdot \frac{\ell}{n} OPT$. Then the total loss of objective value is about

$$\sum_{\ell \in \{\epsilon n, 2\epsilon n, ...\}} h_{\ell} \frac{\ell}{n} OPT$$

$$= \epsilon \sum_{\ell \in \{\epsilon n, 2\epsilon n, ...\}} \sqrt{\frac{\ell}{n}} OPT$$

$$\leq \epsilon OPT \sum_{i} \sqrt{\frac{1}{2^{i}}}$$

$$\leq O(\epsilon OPT)$$

Therefore, the loss of objective value is very small. And we can conclude that this algorithm gives a near-optimal solution.

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We propose a dynamic near-optimal algorithm for a class of online linear programming problems under the random permutation model

- It solves linear programs for dual price based on revealed data, and uses these prices to make future allocations
- The algorithm has the feature of "learning-while-doing", and the pace the price is updated is neither too fast nor too slow
- The application includes various online resource allocation and revenue management problems

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