

DM811  
Heuristics for Combinatorial Optimization

Lecture 13  
Examples

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1. Recap.

2. Other Combinatorial Optimization Problems

GCP

SAT

p-median Problem

Covering and Partitioning

## 1. Recap.

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# Summary: Local Search Algorithms

(as in [Hoos, Stützle, 2005])

Recap.  
Other COPs

For given problem instance  $\pi$ :

1. search space  $S_\pi$
2. neighborhood relation  $\mathcal{N}_\pi \subseteq S_\pi \times S_\pi$
3. evaluation function  $f_\pi : S \rightarrow \mathbf{R}$
4. set of memory states  $M_\pi$
5. initialization function  $\text{init} : \emptyset \rightarrow S_\pi \times M_\pi$
6. step function  $\text{step} : S_\pi \times M_\pi \rightarrow S_\pi \times M_\pi$
7. termination predicate  $\text{terminate} : S_\pi \times M_\pi \rightarrow \{\top, \perp\}$

After implementation and test of the above components, improvements in efficiency (ie, computation time) can be achieved by:

- A. fast delta evaluation
- B. neighborhood pruning
- C. clever use of data structures

Improvements in quality can be achieved by:

- D. application of a metaheuristic
- E. definition of a larger neighborhood

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Approach:  $K$ -fixed / complete / improper

## Local Search

- Solution representation:  $\text{var}\{\text{int}\} a[|V|](1..K)$
- Evaluation function: conflicting edges
- Neighborhood: one-exchange
- Pivoting rule: best neighbor



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## Local Search

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Naive approach:  $O(n^2k)$

Neighborhood examination

**for all**  $v \in V$  **do**

```
| for all  $k \in 1..k$  do  
| | compute  $\Delta(v, k)$ 
```

Better approach:

- $V^c$  set of vertices involved in a conflict
- $adj\_in\_class[n][K]$  stores number of vertices adjacent in each color class

### Initialize:

- compute  $adj\_in\_class[n][K]$  and  $V^c$  in  $O(n^2)$

### Neighborhood examination:

for all  $v \in V^c$  do

    for all  $k \in 1..k$  do

        compute  $\Delta(v, k) = adj\_in\_class[v][k] - adj\_in\_class[v][a(v)]$

### Update:

- change  $adj\_in\_class[n][K]$  and  $V^c$  in  $O(n^2)$

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- $n$  0-1 variables  $x_j$ ,  $j \in N = \{1, 2, \dots, n\}$ ,
- $m$  clauses  $C_i$ ,  $i \in M$ , and weights  $w_i$  ( $\geq 0$ ),  $i \in M = \{1, 2, \dots, m\}$
- $\max_{\mathbf{a} \in \{0,1\}^n} \sum \{w_i \mid i \in M \text{ and } C_i \text{ is satisfied in } \mathbf{a}\}$
- $\bar{x}_j = 1 - x_j$
- $L = \bigcup_{j \in N} \{x_j, \bar{x}_j\}$  set of literals
- $C_i \subseteq L$  for  $i \in M$  (e.g.,  $C_i = \{x_1, \bar{x}_3, x_8\}$ ).

Let's take the case  $w_j = 1$  for all  $j \in N$

- Assignment:  $\mathbf{a} \in \{0, 1\}^n$
- Evaluation function:  $f(\mathbf{a}) = \#$  unsatisfied clauses
- Neighborhood: one-flip
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A better approach:

- $C(x_j) = \{i \in M \mid x_j \in C_i\}$  (i.e., clauses dependent on  $x_j$ )
- $L(x_j) = \{l \in N \mid \exists i \in M \text{ with } x_l \in C_i \text{ and } x_j \in C_i\}$
- $f(a(x_j)) = \#$  unsatisfied clauses
- Score of  $x_j$ :  $\Delta(x_j) = f(a(x_j)) - f(1 - a(x_j))$

Initialize:

- compute  $f$ , score of each variable and list unsat clauses in  $O(mk)$
- init  $C(x_j)$  for all variables

Examine

- choose the var with best score

Update:

- change the score of variables affected, that is, look in  $L(\cdot)$  and  $C(\cdot)$

Even better approach:

↪ after the flip of  $x_j$  only the score of variables in  $L(x_j)$  that critically depend on  $x_j$  actually changes

- Clause  $C_i$  is critically satisfied by a variable  $x_j$  in  $\mathbf{a}$  iff:
  - $x_j$  is in  $C_i$
  - $C_i$  is satisfied in  $\mathbf{a}$  and flipping  $x_j$  makes  $C_i$  unsatisfied (e.g.,  $1 \vee 0 \vee 0$  but not  $1 \vee 1 \vee 0$ )

Keep a list of such clauses for each var

- $x_j$  is critically dependent on  $x_l$  under  $\mathbf{a}$  iff:  
there exists  $C_i \in C(x_j) \cap C(x_l)$  and such that flipping  $x_j$ :
  - $C_i$  changes satisfaction status
  - $C_i$  changes satisfied /critically satisfied status

Initialize:

- compute score of variables;
- init  $C(x_j)$  for all variables
- init status criticality for all clauses

Update:

change sign to score of  $x_j$

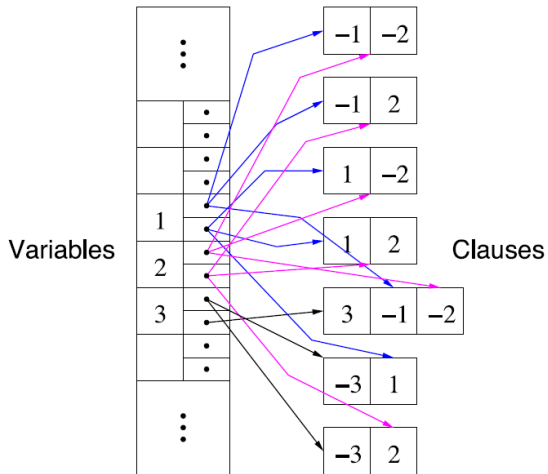
for all  $C_i$  in  $C(x_j)$  do

┌ for all  $x_l \in C_i$  do

└ ┌ update score  $x_l$  depending on its critical status before flipping  $x_j$



## Data Structure



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**p-median Problem**

Covering and Partitioning

# The $p$ -median Problem

**Given:**

a set  $F$  of locations of  $m$  facilities

a set  $U$  of locations for  $n$  users

a distance matrix  $D = [d_{ij}] \in \mathbf{R}^{n \times m}$

**Task:** Select  $p$  locations of  $F$  where to install facilities such that the sum of the distances of each user to its closest installed facility is minimized, *i.e.*,

$$\min \left\{ \sum_{i \in U} \min_{j \in J} d_{ij} \mid J \subseteq F \text{ and } |J| = p \right\}$$

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Max Independent Set (aka, stable set problem or vertex packing problem)

**Given:** an undirected graph  $G(V, E)$  and a non-negative weight function  $\omega$  on  $V$  ( $\omega : V \rightarrow \mathbf{R}$ )

**Task:** A largest weight **independent set** of vertices, i.e., a subset  $V' \subseteq V$  such that no two vertices in  $V'$  are joined by an edge in  $E$ .

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Maximum Clique

**Given:** an undirected graph  $G(V, E)$

**Task:** A maximum cardinality **clique**, i.e., a subset  $V' \subseteq V$  such that every two vertices in  $V'$  are joined by an edge in  $E$

Vertex Cover

**Given:** an undirected graph  $G(V, E)$  and a non-negative weight function  $\omega$  on  $V$  ( $\omega : V \rightarrow \mathbf{R}$ )

**Task:** A smallest weight **vertex cover**, i.e., a subset  $V' \subseteq V$  such that each edge of  $G$  has at least one endpoint in  $V'$ .

Compare with Dominating Set

Set Covering

$$\begin{aligned} \min \quad & \sum_{j=1}^n c_j x_j \\ & \sum_{j=1}^n a_{ij} x_j \geq 1 \quad \forall i \\ & x_j \in \{0, 1\} \end{aligned}$$

Set Partitioning

$$\begin{aligned} \min \quad & \sum_{j=1}^n c_j x_j \\ & \sum_{j=1}^n a_{ij} x_j = 1 \quad \forall i \\ & x_j \in \{0, 1\} \end{aligned}$$

Set Packing

$$\begin{aligned} \max \quad & \sum_{j=1}^n c_j x_j \\ & \sum_{j=1}^n a_{ij} x_j \leq 1 \quad \forall i \\ & x_j \in \{0, 1\} \end{aligned}$$

The independent set problem is equivalent to the [set packing](#).  
Vertex cover problem is a strict special case of [set covering](#).