

DM811
Heuristics for Combinatorial Optimization

Lecture 12
Efficient Local Search

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Local Search for Graph coloring

Different choices for the **candidate solutions**, **neighborhood structures** and **evaluation function** define different approaches to the problem

k -fixed	complete	proper
k -fixed	partial	proper
k -fixed	complete	improper
k -fixed	partial	improper
k -variable	complete	proper
k -variable	partial	proper
k -variable	complete	improper
k -variable	partial	improper

Course Overview

- ✓ Combinatorial Optimization, Methods and Models
- ✓ CH and LS: overview
- ✓ Working Environment and Solver Systems
- ~ Methods for the Analysis of Experimental Results
- ✓ Construction Heuristics
- ✓ Local Search: Components, Basic Algorithms
 - Local Search: Neighborhoods and Search Landscape
 - Efficient Local Search: Incremental Updates and Neighborhood Pruning
- ~ Stochastic Local Search & Metaheuristics
 - Configuration Tools: F-race
 - Very Large Scale Neighborhoods

Examples: GCP, CSP, TSP, SAT, MaxIndSet, SMTWP, Steiner Tree, Unrelated Parallel Machines, p-median, set covering, QAP, ...

1. Efficient Local Search

2. Examples

SAT

TSP

1. Efficient Local Search

2. Examples

SAT

TSP

Summary: Local Search Algorithms

(as in [Hoos, Stützle, 2005])

For given problem instance π :

1. search space S_π
2. neighborhood relation $\mathcal{N}_\pi \subseteq S_\pi \times S_\pi$
3. evaluation function $f_\pi : S \rightarrow \mathbf{R}$
4. set of memory states M_π
5. initialization function $\text{init} : \emptyset \rightarrow S_\pi \times M_\pi$
6. step function $\text{step} : S_\pi \times M_\pi \rightarrow S_\pi \times M_\pi$
7. termination predicate $\text{terminate} : S_\pi \times M_\pi \rightarrow \{\top, \perp\}$

After implementation and test of the above components, improvements in **efficiency** (ie, computation time) can be achieved by:

- A. fast incremental evaluation (ie, delta evaluation)
- B. neighborhood pruning
- C. clever use of data structures

Improvements in **effectiveness**, ie, quality, can be achieved by:

- D. application of a metaheuristic
- E. definition of a larger neighborhood

1. Efficient Local Search

2. Examples

SAT

TSP

Notation:

- n 0-1 variables x_j , $j \in N = \{1, 2, \dots, n\}$,
- m clauses C_i , $i \in M$, and weights $w_i (\geq 0)$, $i \in M = \{1, 2, \dots, m\}$
- $\max_{\mathbf{a} \in \{0,1\}^n} \sum \{w_i \mid i \in M \text{ and } C_i \text{ is satisfied in } \mathbf{a}\}$
- $\bar{x}_j = 1 - x_j$
- $L = \bigcup_{j \in N} \{x_j, \bar{x}_j\}$ set of literals
- $C_i \subseteq L$ for $i \in M$ (e.g., $C_i = \{x_1, \bar{x}_3, x_8\}$).

Let's take the case $w_j = 1$ for all $j \in N$

- Assignment: $\mathbf{a} \in \{0, 1\}^n$
- Evaluation function: $f(\mathbf{a}) = \#$ unsatisfied clauses
- Neighborhood: one-flip
- Pivoting rule: best neighbor

Naive approach: exhaustive neighborhood examination in $O(nmk)$ (k size of largest C_i)

A better approach:

- $C(x_j) = \{i \in M \mid x_j \in C_i\}$ (i.e., clauses dependent on x_j)
- $L(x_j) = \{l \in N \mid \exists i \in M \text{ with } x_l \in C_i \text{ and } x_j \in C_i\}$
- $f(\mathbf{a}) = \#$ unsatisfied clauses
- $\Delta(x_j) = f(\mathbf{a}) - f(\mathbf{a}')$, $\mathbf{a}' = \delta_{1E}^{x_j}(\mathbf{a})$ (score of x_j)

Initialize:

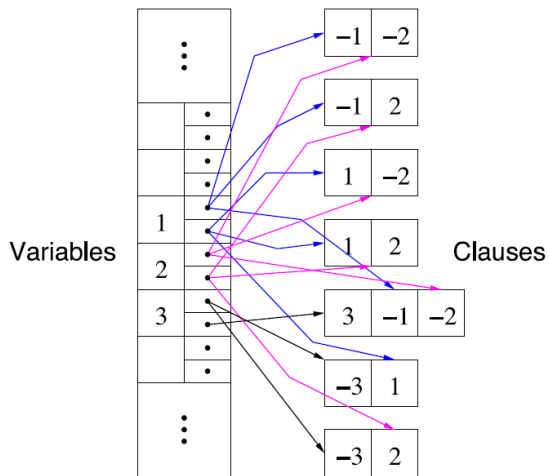
- compute f , score of each variable and list unsat clauses in $O(mk)$
- init $C(x_j)$ for all variables

Examine

- choose the var with best score

Update:

- change the score of variables affected, that is, look in $L(\cdot)$ and $C(\cdot)$ $O(mk)$

$C(x_j)$ Data Structure

Even better approach (though same asymptotic complexity):

↪ after the flip of x_j only the score of variables in $L(x_j)$ that **critically depend** on x_j actually changes

- Clause C_i is **critically satisfied** by a variable x_j in \mathbf{a} iff:
 - x_j is in C_i
 - C_i is satisfied in \mathbf{a} and flipping x_j makes C_i unsatisfied (e.g., $1 \vee 0 \vee 0$ but not $1 \vee 1 \vee 0$)

Keep a list of such clauses for each var

- x_j is **critically dependent** on x_l under \mathbf{a} iff:
there exists $C_i \in C(x_j) \cap C(x_l)$ and such that flipping x_j :
 - C_i changes satisfaction status
 - C_i changes satisfied /critically satisfied status

Initialize:

- compute score of variables;
- init $C(x_j)$ for all variables
- init status criticality for each clause

Update:

change sign to score of x_j

for all C_i in $C(x_j)$ do

┌ for all $x_l \in C_i$ do

└ update score x_l depending on its critical status before flipping x_j

Efficient implementations of 2-opt, 2H-opt and 3-opt local search.

- A. Delta evaluation already in $O(1)$
- B. Fixed radius search + DLB
- C. Data structures

Details at black board and references [Bentley, 1992; Johnson and McGeoch, 2002; Applegate et al., 2006]

- Applegate D.L., Bixby R.E., Chvátal V., and Cook W.J. (2006). **The Traveling Salesman Problem: A Computational Study**. Princeton University Press.
- Bentley J. (1992). **Fast algorithms for geometric traveling salesman problems**. *ORSA Journal on Computing*, 4(4), pp. 387–411.
- Johnson D.S. and McGeoch L.A. (2002). **Experimental analysis of heuristics for the STSP**. In *The Traveling Salesman Problem and Its Variations*, edited by G. Gutin and A. Punnen, pp. 369–443. Kluwer Academic Publishers, Boston, MA, USA.