

DM545  
Linear and Integer Programming

Lecture 12  
**Cutting Plane Algorithms**  
**Branch and Bound**

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1. Cutting Plane Algorithms

2. Branch and Bound

# Common Comments to Assignment 1

- ▶ do not repeat the text of the assignment
- ▶ do not report source code
- ▶ do not make statements without evidence supporting them
- ▶ summarize and comment the results/plots
- ▶ “IP is hard because more basic solutions must be seen“ Not true
- ▶  $\leq 10$  wrong,  $\leq 9$  right
- ▶ several reports did not presented how many assets are to be bought in task 1 and 2
- ▶ meaning of plot in task 3 missing: negative value indicate a loss
- ▶ try to use single letter for name of variables
- ▶ use  $\leq$ , not  $\leq =$
- ▶  $<$  is not allowed in LP
- ▶  $x[t]$  is programming language,  $x_t$  is math language
- ▶  $f(t)$  is a function, not an indexed variable/parameter
- ▶ define all variables, eg,  $y \in \mathbb{R}$
- ▶ use precise language and focus your description on the important aspects
- ▶  $\forall t$  must be completed by the domain of  $t$ , eg,  $t = 1..3$ ,  $t \in T$

# Common Comments to Assignment 1

- ▶ “IP requires exponential run time“, true only in worst case
- ▶ print your reports in double sided papers
- ▶ comments on the plot arguing that there is a linear or exponential growth do not have much sense
- ▶ In LaTeX use `\begin{array}` or `\begin{align}` to write your models

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# Valid Inequalities

- ▶ IP:  $z = \max\{c^T x : x \in X\}$ ,  $X = \{x : Ax \leq b, x \in \mathbb{Z}_+^n\}$
- ▶ Proposition:  $\text{conv}(X) = \{x : \tilde{A}x \leq \tilde{b}, x \geq 0\}$  is a polyhedron
- ▶ LP:  $z = \max\{c^T x : \tilde{A}x \leq \tilde{b}, x \geq 0\}$  would be the best formulation
- ▶ Key idea: try to approximate the best formulation.

## Definition (Valid inequalities)

$ax \leq b$  is a **valid inequality** for  $X \subseteq \mathbb{R}^n$  if  $ax \leq b \forall x \in X$

Which are useful inequalities? and how can we find them?  
How can we use them?

# Example: Pre-processing

- ▶  $X = \{(x, y) : x \leq 999y; 0 \leq x \leq 5, y \in \mathbb{B}^1\}$

$$x \leq 5y$$

- ▶  $X = \{x \in \mathbb{Z}_+^n : 13x_1 + 20x_2 + 11x_3 + 6x_4 \geq 72\}$

$$2x_1 + 2x_2 + x_3 + x_4 \geq \frac{13}{11}x_1 + \frac{20}{11}x_2 + x_3 + \frac{6}{11}x_4 \geq \frac{72}{11} = 6 + \frac{6}{11}$$

$$2x_1 + 2x_2 + x_3 + x_4 \geq 7$$

- ▶ Capacitated facility location:

$$\sum_{i \in M} x_{ij} \leq b_j y_j \quad \forall j \in N$$

$$x_{ij} \leq b_j y_j$$

$$\sum_{j \in N} x_{ij} = a_i \quad \forall i \in M$$

$$x_{ij} \leq a_i$$

$$x_{ij} \geq 0, y_j \in \mathbb{B}^n$$

$$x_{ij} \leq \min\{a_i, b_j\} y_j$$

# Chvátal-Gomory cuts

- ▶  $X \in P \cap \mathbb{Z}_+^n$ ,  $P = \{x \in \mathbb{R}_+^n : Ax \leq b\}$ ,  $A \in \mathbb{R}^{n \times m}$
- ▶  $u \in \mathbb{R}_+^n$ ,  $\{a_1, a_2, \dots, a_n\}$  columns of  $A$

CG procedure to construct valid inequalities

$$1) \quad \sum_{j=1}^n ua_j x_j \leq ub \quad \text{valid: } u \geq 0$$

$$2) \quad \sum_{j=1}^n \lfloor ua_j \rfloor x_j \leq ub \quad \text{valid: } x \geq 0 \text{ and } \sum \lfloor ua_j \rfloor x_j \leq \sum ua_j x_j$$

$$3) \quad \sum_{j=1}^n \lfloor ua_j \rfloor x_j \leq \lfloor ub \rfloor \quad \text{valid for } X \text{ since } x \in \mathbb{Z}^n$$

## Theorem

*Every valid inequality for  $X$  can be obtained by applying the CG procedure a finite number of times*

However often the family of valid inequalities is large and makes the LP hard



# Cutting Plane Algorithms

- ▶  $X \in P \cap \mathbb{Z}_+^n$
- ▶ a family of valid inequalities  $\mathcal{F} : a^T x \leq b, (a, b) \in \mathcal{F}$  for  $X$
- ▶ we do not find them all a priori, only interested in those close to optimum

## Cutting Plane Algorithm

Init.:  $t = 0, P^0 = P$

Iter.  $t$ : Solve  $\bar{z}^t = \max\{c^T x : x \in P^t\}$

let  $x^t$  be an optimal solution

if  $x^t \in \mathbb{Z}^n$  stop,  $x^t$  is opt to the IP

if  $x^t \notin \mathbb{Z}^n$  solve separation problem for  $x^t$  and  $\mathcal{F}$

if  $(a^t, b^t)$  is found with  $a^t x^t > b^t$  that cuts off  $x^t$

$$P^{t+1} = P \cap \{x : a^i x \leq b^i, i = 1, \dots, t\}$$

else stop ( $P^t$  is in any case an improved formulation)

# Gomory's fractional cutting plane algorithm

Cutting plane algorithm + Chvátal-Gomory cuts

- ▶  $\max\{c^T x : Ax = b, x \geq 0, x \in \mathbb{Z}^n\}$
- ▶ Solve LPR to optimality

$$\left[ \begin{array}{c|c|c|c} I & \bar{A}_N = A_B^{-1}A_N & 0 & \bar{b} \\ \hline \bar{c}_B & \bar{c}_N (\leq 0) & 1 & -\bar{d} \end{array} \right] \quad \begin{array}{l} x_u = \bar{b}_u - \sum_{j \in N} \bar{a}_{uj} x_j, \quad u \in B \\ z = \bar{d} + \sum_{j \in N} \bar{c}_j x_j \end{array}$$

- ▶ If basic optimal solution to LPR is not integer then  $\exists$  some row  $u$ :  $\bar{b}_u \notin \mathbb{Z}^1$ .

The Chvátal-Gomory cut applied to this row is:

$$x_{B_u} + \sum_{j \in N} \lfloor \bar{a}_{uj} \rfloor x_j \leq \lfloor \bar{b}_u \rfloor$$

( $B_u$  is the index in the basis  $B$  corresponding to the row  $u$ ) (cntd)

- ▶ Eliminating  $x_{B_u} = \bar{b}_u - \sum_{j \in N} \bar{a}_{uj} x_j$  in the CG cut we obtain:

$$\sum_{j \in N} \underbrace{(\bar{a}_{uj} - \lfloor \bar{a}_{uj} \rfloor)}_{0 \leq f_{uj} < 1} x_j \geq \underbrace{\bar{b}_u - \lfloor \bar{b}_u \rfloor}_{0 < f_u < 1}$$

$$\sum_{j \in N} f_{uj} x_j \geq f_u$$

$f_u > 0$  or else  $u$  would not be row of fractional solution. It implies that  $x^*$  in which  $x_N^* = 0$  is cut out!

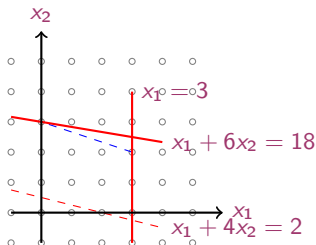
- ▶ Moreover: when  $x$  is integer, since all coefficient in the CG cut are integer the slack variable of the cut is also integer:

$$s = -f_u + \sum_{j \in N} f_{uj} x_j$$

(theoretically it terminates after a finite number of iterations, but in practice not successful.)

# Example

$$\begin{aligned} \max \quad & x_1 + 4x_2 \\ \text{s.t.} \quad & x_1 + 6x_2 \leq 18 \\ & x_1 \leq 3 \\ & x_1, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{aligned}$$



	x1	x2	x3	x4	-z	b
	1	6	1	0	0	18
	1	0	0	1	0	3
	1	4	0	0	1	0

	x1	x2	x3	x4	-z	b
	0	1	1/6	-1/6	0	15/6
	1	0	0	1	0	3
	0	0	-2/3	-1/3	1	-13

$x_2 = 5/2, x_1 = 3$   
Optimum, not integer

- ▶ We take the first row:

$$| \quad | \quad 0 \quad | \quad 1 \quad | \quad 1/6 \quad | \quad -1/6 \quad | \quad 0 \quad | \quad 15/6 \quad |$$

- ▶ CG cut  $\sum_{j \in N} f_{uj}x_j \geq f_u \rightsquigarrow \frac{1}{6}x_3 + \frac{5}{6}x_4 \geq \frac{1}{2}$

- ▶ Let's see that it leaves out  $x^*$ : from the CG proof:

$$\begin{array}{r} 1/6 (x_1 + 6x_2 \leq 18) \\ 5/6 (x_1 \leq 3) \\ \hline x_1 + x_2 \leq 3 + 5/2 = 5.5 \end{array}$$

since  $x_1, x_2$  are integer  $x_1 + x_2 \leq 5$

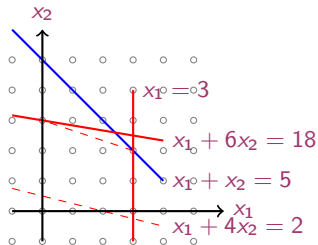
- ▶ Let's see how it looks in the space of the original variables: from the first tableau:

$$x_3 = 18 - 6x_2 - x_1$$

$$x_4 = 3 - x_1$$

$$\frac{1}{6}(18 - 6x_2 - x_1) + \frac{5}{6}(3 - x_1) \geq \frac{1}{2} \quad \rightsquigarrow \quad x_1 + x_2 \leq 5$$

► Graphically:



► Let's continue:

	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$-z$	$b$
	0	0	-1/6	-5/6	1	0	-1/2
	0	1	1/6	-1/6	0	0	5/2
	1	0	0	1	0	0	3
	0	0	-2/3	-1/3	0	1	-13

We need to apply dual-simplex  
(will always be the case, why?)

ratio rule:  $\min \left| \frac{c_j}{a_{ij}} \right|$

- After the dual simplex iteration:

	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$-z$	$b$
	0	0	$1/5$	1	$-6/5$	0	$3/5$
	0	1	$1/5$	0	$-1/5$	0	$13/5$
	1	0	$-1/5$	0	$6/5$	0	$12/5$
	0	0	$-3/5$	0	$-2/5$	1	$-64/5$

- In the space of the original variables:

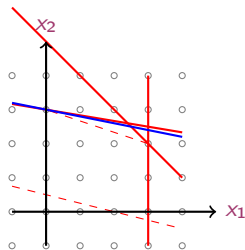
$$4(18 - x_1 - 6x_2) + (5 - x_1 - x_2) \geq 2$$

$$x_1 + 5x_2 \leq 15$$

We can choose any of the three rows.

Let's take the third: CG cut:

$$\frac{4}{5}x_3 + \frac{1}{5}x_5 \geq \frac{2}{5}$$



► ...

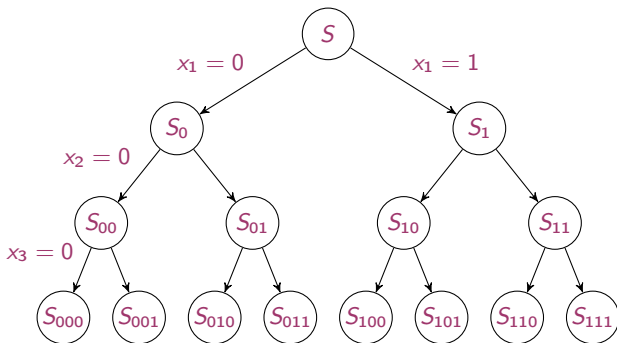
1. Cutting Plane Algorithms

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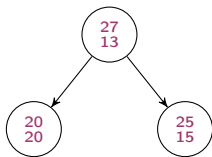
- ▶ Consider the problem  $z = \max\{c^T x : x \in S\}$
- ▶ Divide and conquer: let  $S = S_1 \cup \dots \cup S_k$  be a decomposition of  $S$  into smaller sets, and let  $z^k = \max\{c^T x : x \in S_k\}$  for  $k = 1, \dots, K$ . Then  $z = \max_k z^k$

For instance if  $S \subseteq \{0, 1\}^3$  the enumeration tree is:



# Bounding

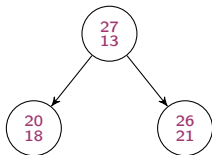
- ▶ Let  $\bar{z}^k$  be an upper bound on  $z^k$
- ▶ Let  $\underline{z}^k$  be a lower bound on  $z^k$
- ▶  $(\underline{z}^k \leq z^k \leq \bar{z}^k)$
- ▶  $\bar{z} = \max_k \bar{z}^k$  is an upper bound on  $z$
- ▶  $\underline{z} = \max_k \underline{z}^k$  is a lower bound on  $z$



$$\bar{z} = 25$$

$$\underline{z} = 20$$

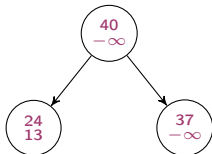
pruned by optimality



$$\bar{z} = 26$$

$$\underline{z} = 21$$

pruned by bounding



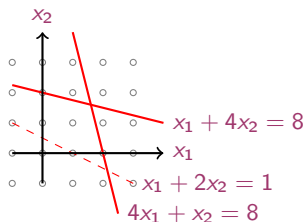
$$\bar{z} = 37$$

$$\underline{z} = 13$$

nothing to prune

# Example

$$\begin{aligned} \max \quad & x_1 + 2x_2 \\ & x_1 + 4x_2 \leq 8 \\ & 4x_1 + x_2 \leq 8 \\ & x_1, x_2 \geq 0, \text{ integer} \end{aligned}$$



► Solve LP

	$x_1$	$x_2$	$x_3$	$x_4$	$-z$	$b$
	1	4	1	0	0	8
	4	1	0	1	0	8
	1	2	0	0	1	0

	$x_1$	$x_2$	$x_3$	$x_4$	$-z$	$b$
I' = I - II'	0	15/4	1	-1/4	0	6
II' = 1/4 II	1	1/4	0	1/4	0	2
III' = III - II'	0	7/4	0	-1/4	0	-2

► continuing

	$x_1$	$x_2$	$x_3$	$x_4$	$-z$	$b$
I' = $4/15$ I	0	1	$4/15$	$-1/15$	0	$24/15$
II' = II - $1/4$ I'	1	0	$-1/15$	$4/15$	0	$24/15$
III' = III - $7/4$ I'	0	0	$-7/15$	$-3/5$	1	$-2 - 14/5$

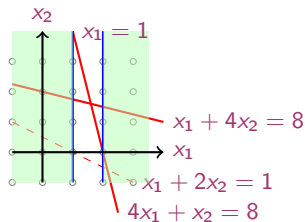
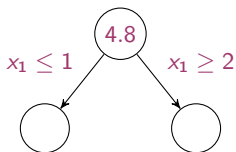
$$x_2 = 1 + 3/5 = 1.6$$

$$x_1 = 8/5$$

The optimal solution  
will not be more than

$$2 + 14/5 = 4.8$$

► Both variables are fractional, we pick one of the two:



- Let's consider first the left branch:

	x1	x2	x3	x4	x5	b	-z
	1	0	0	0	1	0	1
	0	1	4/15	-1/15	0	0	24/15
	1	0	-1/15	4/15	0	0	24/15
	0	0	-7/15	-3/5	0	1	-24/5

	x1	x2	x3	x4	x5	b	-z
I' = I - III	0	0	1/15	-4/15	1	0	-9/15
	0	1	4/15	-1/15	0	0	24/15
	1	0	-1/15	4/15	0	0	24/15
	0	0	-7/15	-3/5	0	1	-24/5

	x1	x2	x3	x4	x5	b	-z
	0	0	-1/4	1	-15/4	0	9/4
	0	1	15/60	0	-1/4	0	7/4
	1	0	0	0	1	0	1
	0	0	-37/60	0	-9/4	1	-90/20

always a  $b$  term  
negative after

branching:

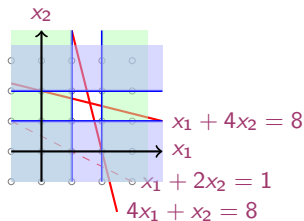
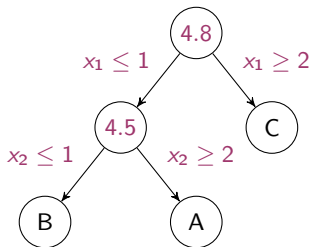
$$\bar{b}_1 = \lfloor \bar{b}_3 \rfloor$$

$$\bar{b}_1 = \lfloor \bar{b}_3 \rfloor - b_3 < 0$$

Dual simplex:

$$\min_j \left| \frac{c_j}{a_{ij}} \right|$$

- Let's branch again



We have three open problems. Which one we choose next?  
Let's take A.

	x1	x2	x3	x4	x5	x6	b	-z
	0	-1	0	0	0	1	0	-2
	0	0	-1/4	1	-15/4		0	9/4
	0	1	15/60	0	-1/4		0	7/4
	1	0	0	0	1		0	1
	0	0	-37/60	0	-9/4		1	-9/2

	x1	x2	x3	x4	x5	x6	b	-z
III+I	0	0	1/4	0	-1/4	1	0	-1/4
	0	0	-1/4	1	-15/4		0	9/4
	0	1	15/60	0	-1/4		0	7/4
	1	0	0	0	1		0	1
	0	0	-37/60	0	-9/4		1	-9/2

continuing we find:

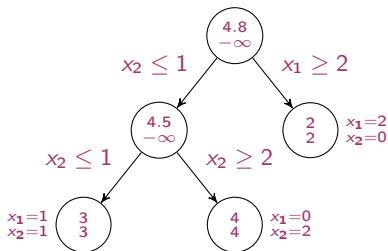
$$x_1 = 0$$

$$x_2 = 2$$

$$OPT = 4$$



The final tree:



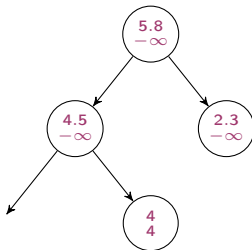
The optimal solution is 4.

Pruning:

1. by optimality:  $z^k = \max\{c^T x : x \in S^k\}$

2. by bound  $\bar{z}^k \leq \underline{z}$

Example:



3. by infeasibility  $S^k = \emptyset$

# B&B Components

## Bounding:

1. LP relaxation
2. Lagrangian relaxation
3. Combinatorial relaxation
4. Duality

## Branching:

$$S_1 = S \cap \{x : x_j \leq \lfloor \bar{x}_j \rfloor\}$$

$$S_2 = S \cap \{x : x_j \geq \lceil \bar{x}_j \rceil\}$$

thus the current optimum is not feasible either in  $S_1$  or in  $S_2$ .

Which variable to choose?

Eg: Most fractional variable  $\arg \max_{j \in C} \min\{f_j, 1 - f_j\}$

**Choosing Node: Examination:** nodes to be examined, active (or open):

- ▶ Depth First Search (a good primal sol. is good for pruning + easier to reoptimize by just adding a new constraint)
- ▶ Best Bound First: (eg. largest upper:  $\bar{z}^s = \max_k \bar{z}^k$ )
- ▶ Mixed strategies

**Reoptimizing:** dual simplex

**Updating the Incumbent:** when new best feasible solution is found:

$$\underline{z} = \max\{\underline{z}, 4\}$$

**Store the active nodes:** bounds + optimal basis (remember the revised simplex!)

# Enhancements

- ▶ Preprocessor: constraint/problem/structure specific tightening bounds  
redundant constraints  
variable fixing: eg:  $\max\{c^T x : Ax \leq b, l \leq x \leq u\}$   
fix  $\forall a_{ij} > 0, c_j < 0, x_j = l_j; a_{ij} < 0, c_j > 0, x_j = u_j$
- ▶ Priorities: establish the next variable to branch
- ▶ Special ordered sets SOS (or generalized upper bound GUB)

$$\sum_{j=1}^k x_j = 1 \quad x_j \in \{0, 1\}$$

instead of:  $S_0 = S \cap \{x : x_j = 0\}$  and  $S_1 = S \cap \{x : x_j = 1\}$   
 $\{x : x_j = 0\}$  leaves  $k - 1$  possibilities  
 $\{x : x_j = 1\}$  leaves only 1 possibility  
 hence tree unbalanced

here:  $S_1 = S \cap \{x : x_{j_i} = 0, i = 1..r\}$  and  
 $S_2 = S \cap \{x : x_{j_i} = 0, i = r + 1, \dots, k\}, r = \min\{t : \sum_{i=1}^t x_{j_i}^* \geq \frac{1}{2}\}$

- ▶ Cutoff value: a user-defined primal bound to pass to the system.
- ▶ Simplex strategies: simplex is good for reoptimizing but for large models interior points methods may work best.
- ▶ Strong branching: extra work to decide more accurately on which variable to branch:
  1. choose a set  $C$  of fractional variables
  2. reoptimize for each them (in case for limited iterations)
  3.  $\bar{z}_j^D, \bar{z}_j^U$  (UB of down and up branch)

$$j^* = \arg \min_{j \in C} \max\{z_j^D, z_j^U\}$$

ie, choose variable with largest decrease of dual bound, UB

- ▶ If not finished after a certain time, possible reasons:
  - ▶ no feasible solution is found
  - ▶ the gap best feasible-dual bound is large

$$\text{gap} = \frac{|\text{Primal bound} - \text{Dual bound}|}{\text{Primal bound} + \epsilon} \cdot 100$$

- ▶ runs out of memory
- ▶ heuristics for finding feasible solutions (generally NP-complete problem)
- ▶ find better lower bounds if they are weak: addition of cuts, stronger formulation, **branch and cut**
- ▶ Branch and cut: a B&B algorithm with cut generation at all nodes of the tree. (instead of reoptimizing, do as much work as possible to tighten)

Cut pool: stores all cuts centrally

Store for active node: bounds, basis, pointers to constraints in the cut pool that apply at the node

# Relative Optimality Gap

In CPLEX:

$$\text{gap} = \frac{|\text{best node} - \text{best integer}|}{|\text{best integer} + 10^{-11}|}$$

In SCIP and MIPLIB standard:

$$\text{gap} = \frac{pb - db}{\inf\{|z|, z \in [db, pb]\}} \cdot 100 \quad \text{for a minimization problem}$$

(if  $pb \geq 0$  and  $db \geq 0$  then  $\frac{pb-db}{db}$ )

if  $db = pb = 0$  then  $\text{gap} = 0$

if no feasible sol found or  $db \leq 0 \leq pb$  then the gap is not computed.



Last standard avoids problem of non decreasing gap if we go through zero

3186	2520	-666.6217	4096	956.6330	-667.2010	1313338	169.74%	
3226	2560	-666.6205	4097	956.6330	-667.2010	1323797	169.74%	
3266	2600	-666.6201	4095	956.6330	-667.2010	1335602	169.74%	
Elapsed real time = 2801.61 sec. (tree size = 77.54 MB, solutions = 2)								
*	3324+	2656		-125.5775	-667.2010	1363079	431.31%	
	3334	2668	-666.5811	4052	-125.5775	-667.2010	1370748	431.31%
	3380	2714	-666.5799	4017	-125.5775	-667.2010	1388391	431.31%
	3422	2756	-666.5791	4011	-125.5775	-667.2010	1403440	431.31%

We did not treat:

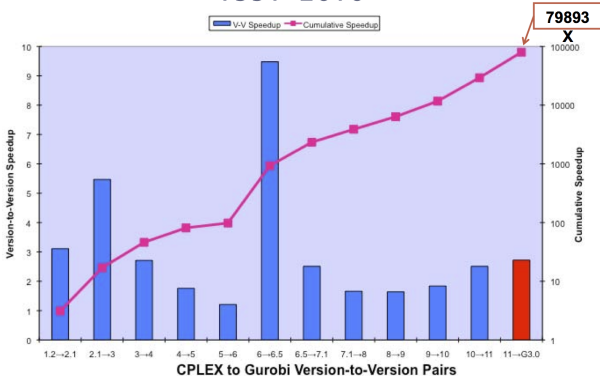
- ▶ LP: Dantzig Wolfe decomposition
- ▶ LP: Column generation
- ▶ LP: Delayed column generation
- ▶ IP: Branch and Price
- ▶ LP: Benders decompositions
- ▶ LP: Lagrangian relaxation

# MILP Solvers Breakthroughs

We have seen Fractional Gomory cuts.

The introduction of Mixed Integer Gomory cuts in CPLEX was the major breakthrough of CPLEX 6.5 and produced the version-to-version speed-up given by the blue bars in the chart below

## MIP Performance Improvements 1991-2010



(source: R. Bixby. Mixed-Integer Programming: It works better than you may think. 2010. Slides on the net)

1. Cutting Plane Algorithms

2. Branch and Bound