# DM554/DM545 <br> Linear and Integer Programming 

# Lecture 10 <br> IP Modeling <br> Formulations, Relaxations 

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## Outline

1. Modeling

Graph Problems
Modeling Tricks
2. Formulations

Uncapacited Facility Location
Alternative Formulations

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## Review

- Assignment Problem
- Set Problems: Knapsack problem, facility location problem


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## Matching

Definition (Matching Theory Terminology)
Matching: set of pairwise non adjacent edges
Covered (vertex): a vertex is covered by a matching $M$ if it is incident to an edge in $M$
Perfect (matching): if $M$ covers each vertex in $G$
Maximal (matching): if $M$ cannot be extended any further
Maximum (matching): if $M$ covers as many vertices as possible
Matchable (graph): if the graph $G$ has a perfect matching

$$
\begin{aligned}
& \max \sum_{v \in V} w_{e} x_{e} \\
& \sum_{e \in E: v \in e} x_{e} \leq 1 \quad \forall v \in V \\
& x_{e} \in\{0,1\} \quad \forall e \in E
\end{aligned}
$$

Special case: bipartite matching $\equiv$ assignment problems

## Vertex Cover

Select a subset $S \subseteq V$ such that each edge has at least one end vertex in $S$.

$$
\min \quad \begin{aligned}
\sum_{v \in V} x_{v} & \\
x_{v}+x_{u} & \geq 1 \quad \forall u, v \in V, u v \in E \\
x_{v} & \in\{0,1\} \quad \forall v \in V
\end{aligned}
$$

Approximation algorithm: set $S$ derived from the LP solution in this way:

$$
S_{L P}=\left\{v \in V: x_{v}^{*} \geq 1 / 2\right\}
$$

(it is a cover since $x_{v}^{*}+x_{u}^{*} \geq 1$ implies $x_{v}^{*} \geq 1 / 2$ or $x_{u}^{*} \geq 1 / 2$ )

## Proposition

The LP rounding approximation algorithm gives a 2-approximation:
$\left|S_{L P}\right| \leq 2\left|S_{\text {OPT }}\right|$ (at most as bad as twice the optimal solution)
Proof: Let $\bar{x}$ be opt to IP. Then $\sum x_{v}^{*} \leq \sum \bar{x}_{v}$.
$\left|S_{L P}\right|=\sum_{v \in S_{L P}} 1 \leq \sum_{v \in V} 2 x_{v}^{*}$ since $x_{v}^{*} \geq 1 / 2$ for each $v \in S_{L P}$
$\left|S_{L P}\right| \leq 2 \sum_{v \in V} x_{v}^{*} \leq 2 \sum_{v \in V} \bar{x}_{v}=2\left|S_{O P T}\right|$

## Maximum Independent Set

Find the largest subset $S \subseteq V$ such that the induced graph has no edges

$$
\begin{aligned}
\max \sum_{v \in V} x_{v} & \\
x_{v}+x_{u} & \leq 1 \quad \forall u, v \in V, u v \in E \\
x_{v} & =\{0,1\} \quad \forall v \in V
\end{aligned}
$$

Optimal sol of LP relaxation sets $x_{v}=1 / 2$ for all variables and has value $|V| / 2$.

What is the value of an optimal IP solution of a complete graph?
LP relaxation gives an $O(n)$-approximation (almost useless)

## Traveling Salesman Problem

- Find the cheapest movement for a drilling, welding, drawing, soldering arm as, for example, in a printed circuit board manufacturing process or car manufacturing process
- $n$ locations, $c_{i j}$ cost of travel

Variables:

$$
x_{i j}=\left\{\begin{array}{l}
1 \\
0
\end{array}\right.
$$

## Objective:

$$
\sum_{i=1}^{n} \sum_{j=1}^{n} c_{i j} x_{i j}
$$

## Constraints:

$$
\begin{aligned}
& \sum_{j: j \neq i} x_{i j}=1 \\
& \sum_{i: i \neq j} x_{i j}=1
\end{aligned}
$$

$$
\begin{aligned}
& \forall i=1, \ldots, n \\
& \forall j=1, \ldots, n
\end{aligned}
$$

- cut set constraints

$$
\sum_{i \in S} \sum_{j \notin S} x_{i j} \geq 1
$$

$$
\forall S \subset N, S \neq \emptyset
$$

- subtour elimination constraints

$$
\sum_{i \in S} \sum_{j \in S} x_{i j} \leq|S|-1
$$

$$
\forall S \subset N, 2 \leq|S| \leq n-1
$$

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## Modeling Tricks

Objective function and/or constraints do not appear to be linear?

- Absolute values
- Minimize the largest function value
- Maximize the smallest function value
- Constraints include variable division
- Constraints are either/or
- A variable must take one of several candidate values


## Modeling Tricks I

Minimize the largest of a number of function values:

$$
\min \max \left\{f\left(x_{1}\right), \ldots, f\left(x_{n}\right)\right\}
$$

- Introduce an auxiliary variable $z$ :

$$
\begin{aligned}
& \min \quad z \\
& \text { s. t. } f\left(x_{1}\right) \leq z \\
& f\left(x_{2}\right) \leq z
\end{aligned}
$$

## Modeling Tricks II

Constraints include variable division:

- Constraint of the form

$$
\frac{a_{1} x+a_{2} y+a_{3} z}{d_{1} x+d_{2} y+d_{3} z} \leq b
$$

- Rearrange:

$$
a_{1} x+a_{2} y+a_{3} z \leq b\left(d_{1} x+d_{2} y+d_{3} z\right)
$$

which gives:

$$
\left(a_{1}-b d_{1}\right) x+\left(a_{2}-b d_{2}\right) y+\left(a_{3}-b d_{3}\right) z \leq 0
$$

## III "Either/Or Constraints"

In conventional mathematical models, the solution must satisfy all constraints.
Suppose that your constraints are "either/or":

$$
\begin{array}{ll}
a_{1} x_{1}+a_{2} x_{2} \leq b_{1} & \text { or } \\
d_{1} x_{1}+d_{2} x_{2} \leq b_{2} &
\end{array}
$$

Introduce new variable $y \in\{0,1\}$ and a large number $M$ :

$$
\begin{array}{ll}
a_{1} x_{1}+a_{2} x_{2} \leq b_{1}+M y & \text { if } y=0 \text { then this is active } \\
d_{1} x_{1}+d_{2} x_{2} \leq b_{2}+M(1-y) & \text { if } y=1 \text { then this is active }
\end{array}
$$

## III "Either/Or Constraints"

Binary integer programming allows to model alternative choices:

- Eg: 2 feasible regions, ie, disjunctive constraints, not possible in LP. introduce $y$ auxiliary binary variable and $M$ a big number:

$$
\begin{aligned}
A x & \leq b+M y \\
A^{\prime} x & \leq b^{\prime}+M(1-y)
\end{aligned}
$$

$$
\text { if } y=0 \text { then this is active }
$$

$$
\text { if } y=1 \text { then this is active }
$$

## IV "Either/Or Constraints"

Generally:

$$
\begin{gathered}
a_{11} x_{1}+a_{12} x_{2}+a_{13} x_{3}+\ldots+a_{1 m} x_{m} \leq d_{1} \\
a_{21} x_{1}+a_{22} x_{2}+a_{23} x_{3}+\ldots+a_{2 m} x_{m} \leq d_{2} \\
\vdots \\
a_{m 1} x_{1}+a_{N 2} x_{2}+a_{N 3} x_{3}+\ldots+a_{N m} x_{m} \leq d_{N}
\end{gathered}
$$

Exactly $K$ of the $N$ constraints must be satisfied. Introduce binary variables $y_{1}, y_{2}, \ldots, y_{N}$ and a large number $M$

$$
\begin{gathered}
a_{11} x_{1}+a_{12} x_{2}+a_{13} x_{3}+\ldots+a_{1 m} x_{m} \leq d_{1}+M y_{1} \\
a_{21} x_{1}+a_{22} x_{2}+a_{23} x_{3}+\ldots+a_{2 m} x_{m} \leq d_{2}+M y_{2} \\
\vdots \\
a_{m 1} x_{1}+a_{N 2} x_{2}+a_{N 3} x_{3}+\ldots+a_{N m} x_{m} \leq d_{N}+M y_{N} \\
y_{1}+y_{2}+\ldots y_{N}=N-K
\end{gathered}
$$

$K$ of the $y$-variables are 0 , so $K$ constraints must be satisfied

## IV "Either/Or Constraints"

At least $h \leq k$ of $\sum_{j=1}^{n} a_{i j} x_{j} \leq b_{i}, i=1, \ldots, k$ must be satisfied introduce $y_{i}, i=1, \ldots, k$ auxiliary binary variables

$$
\begin{gathered}
\sum_{j=1}^{n} a_{i j} x_{j} \leq b_{i}+M y_{i} \\
\sum_{i} y_{i} \leq k-h
\end{gathered}
$$

## V "Possible Constraints Values"

A constraint must take on one of $N$ given values:

$$
\begin{gathered}
a_{1} x_{1}+a_{2} x_{2}+a_{3} x_{3}+\ldots+a_{m} x_{m}=d_{1} \text { or } \\
a_{1} x_{1}+a_{2} x_{2}+a_{3} x_{3}+\ldots+a_{m} x_{m}=d_{2} \text { or } \\
\vdots \\
a_{1} x_{1}+a_{2} x_{2}+a_{3} x_{3}+\ldots+a_{m} x_{m}=d_{N}
\end{gathered}
$$

Introduce binary variables $y_{1}, y_{2}, \ldots, y_{N}$ :

$$
\begin{gathered}
a_{1} x_{1}+a_{2} x_{2}+a_{3} x_{3}+\ldots+a_{m} x_{m}=d_{1} y_{1}+d_{2} y_{2}+\ldots d_{N} y_{N} \\
y_{1}+y_{2}+\ldots y_{N}=1
\end{gathered}
$$

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## Uncapacited Facility Location (UFL)

## Given:

- depots $N=\{1, \ldots, n\}$
- clients $M=\{1, \ldots, m\}$
- $f_{j}$ fixed cost to use depot $j$
- transport cost for all orders $c_{i j}$

Task: Which depots to open and which depots serve which client

Variables: $y_{j}=\left\{\begin{array}{ll}1 & \text { if depot open } \\ 0 & \text { otherwise }\end{array}, x_{i j}\right.$ fraction of demand of $i$ satisfied by $j$ Objective:

$$
\min \sum_{i \in M} \sum_{j \in N} c_{i j} x_{i j}+\sum_{j \in N} f_{j} y_{j}
$$

## Constraints:

$$
\begin{array}{ll}
\sum_{j=1}^{n} x_{i j}=1 & \forall i=1, \ldots, m \\
\sum_{i \in M} x_{i j} \leq m y_{j} & \forall j \in N
\end{array}
$$

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## Good and Ideal Formulations

Definition (Formulation)
A polyhedron $P \subseteq \mathbb{R}^{n+p}$ is a formulation for a set $X \subseteq \mathbb{Z}^{n} \times \mathbb{R}^{p}$ if and only if $X=P \cap\left(\mathbb{Z}^{n} \times \mathbb{R}^{p}\right)$

That is, if it does not leave out any of the solutions of the feasible region $X$.
There are infinite formulations
Definition (Convex Hull)
Given a set $X \subseteq \mathbb{Z}^{n}$ the convex hull of $X$ is defined as:

$$
\begin{aligned}
\operatorname{conv}(X)= & \left\{\mathbf{x}: \mathbf{x}=\sum_{i=1}^{t} \lambda_{i} \mathbf{x}^{i}, \sum_{i=1}^{t} \lambda_{i}=1, \lambda_{i} \geq 0, \text { for } i=1, \ldots, t,\right. \\
& \text { for all finite subsets } \left.\left\{\mathbf{x}^{1}, \ldots, \mathbf{x}^{t}\right\} \text { of } X\right\}
\end{aligned}
$$

## Proposition

```
\(\operatorname{conv}(X)\) is a polyhedron (ie, representable as \(A \mathbf{x} \leq \mathbf{b}\) )
```

Proposition
Extreme points of conv $(X)$ all lie in $X$
Hence:

$$
\max \left\{\mathbf{c}^{\top} \mathbf{x}: \mathbf{x} \in X\right\} \equiv \max \left\{\mathbf{c}^{\top} \mathbf{x}: \mathbf{x} \in \operatorname{conv}(X)\right\}
$$

However it might require exponential number of inequalities to describe conv $(X)$
What makes a formulation better than another?

$$
X \subseteq \operatorname{conv}(X) \subseteq P_{2} \subset P_{1}
$$

$P_{2}$ is better than $P_{1}$
Definition
Given a set $X \subseteq \mathbb{R}^{n}$ and two formulations $P_{1}$ and $P_{2}$ for $X, P_{2}$ is a better formulation than $P_{1}$ if $P_{2} \subset P_{1}$

Example
$P_{1}=\mathrm{UFL}$ with $\sum_{i \in M} x_{i j} \leq m y_{j} \quad \forall j \in N$
$P_{2}=$ UFL with $x_{i j} \leq y_{j} \quad \forall i \in M, j \in N$

$$
P_{2} \subset P_{1}
$$

- $P_{2} \subseteq P_{1}$ because summing $x_{i j} \leq y_{j}$ over $i \in M$ we obtain $\sum_{i \in M} x_{i j} \leq m y_{j}$
- $P_{2} \subset P_{1}$ because there exists a point in $P_{1}$ but not in $P_{2}$ : $m=6=3 \cdot 2=k \cdot n$

$$
\begin{array}{ll}
x_{10}=1, x_{20}=1, x_{30}=1, & \sum_{i} x_{i 0} \leq 6 y_{0} \\
y_{0}=1 / 2 \\
x_{41}=1, x_{51}=1, x_{61}=1 & \sum_{i} x_{i 1} \leq 6 y_{1} \quad y_{1}=1 / 2
\end{array}
$$

## Resume

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