

DM545
Linear and Integer Programming

Lecture 13
Cutting Planes and
Branch and Bound

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1. Cutting Plane Algorithms

2. Branch and Bound

1. Cutting Plane Algorithms

2. Branch and Bound

Valid Inequalities

- IP: $z = \max\{\mathbf{c}^T \mathbf{x} : \mathbf{x} \in X\}$, $X = \{\mathbf{x} : \mathbf{A}\mathbf{x} \leq \mathbf{b}, \mathbf{x} \in \mathbb{Z}_+^n\}$
- Proposition: $\text{conv}(X) = \{\mathbf{x} : \tilde{\mathbf{A}}\mathbf{x} \leq \tilde{\mathbf{b}}, \mathbf{x} \geq \mathbf{0}\}$ is a polyhedron
- LP: $z = \max\{\mathbf{c}^T \mathbf{x} : \tilde{\mathbf{A}}\mathbf{x} \leq \tilde{\mathbf{b}}, \mathbf{x} \geq \mathbf{0}\}$ would be the best formulation
- Key idea: try to approximate the best formulation.

Definition (Valid inequalities)

$\mathbf{a}\mathbf{x} \leq \mathbf{b}$ is a **valid inequality** for $X \subseteq \mathbb{R}^n$ if $\mathbf{a}\mathbf{x} \leq \mathbf{b} \forall \mathbf{x} \in X$

Which are useful inequalities? and how can we find them?
How can we use them?

Example: Pre-processing

- $X = \{(x, y) : x \leq 999y; 0 \leq x \leq 5, y \in \mathbb{B}^1\}$

$$x \leq 5y$$

- $X = \{x \in \mathbb{Z}_+^n : 13x_1 + 20x_2 + 11x_3 + 6x_4 \geq 72\}$

$$2x_1 + 2x_2 + x_3 + x_4 \geq \frac{13}{11}x_1 + \frac{20}{11}x_2 + x_3 + \frac{6}{11}x_4 \geq \frac{72}{11} = 6 + \frac{6}{11}$$

$$2x_1 + 2x_2 + x_3 + x_4 \geq 7$$

- Capacitated facility location:

$$\sum_{i \in M} x_{ij} \leq b_j y_j \quad \forall j \in N$$

$$x_{ij} \leq b_j y_j$$

$$\sum_{j \in N} x_{ij} = a_i \quad \forall i \in M$$

$$x_{ij} \leq a_i$$

$$x_{ij} \geq 0, y_j \in \mathbb{B}^n$$

$$x_{ij} \leq \min\{a_i, b_j\} y_j$$

Chvátal-Gomory cuts

- $X \in P \cap \mathbb{Z}_+^n$, $P = \{\mathbf{x} \in \mathbb{R}_+^n : A\mathbf{x} \leq \mathbf{b}\}$, $A \in \mathbb{R}^{m \times n}$
- $\mathbf{u} \in \mathbb{R}_+^m$, $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\}$ columns of A

CG procedure to construct valid inequalities

$$1) \quad \sum_{j=1}^n \mathbf{u} \mathbf{a}_j x_j \leq \mathbf{u} \mathbf{b} \quad \text{valid: } \mathbf{u} \geq \mathbf{0}$$

$$2) \quad \sum_{j=1}^n \lfloor \mathbf{u} \mathbf{a}_j \rfloor x_j \leq \mathbf{u} \mathbf{b} \quad \text{valid: } \mathbf{x} \geq \mathbf{0} \text{ and } \sum \lfloor \mathbf{u} \mathbf{a}_j \rfloor x_j \leq \sum \mathbf{u} \mathbf{a}_j x_j$$

$$3) \quad \sum_{j=1}^n \lfloor \mathbf{u} \mathbf{a}_j \rfloor x_j \leq \lfloor \mathbf{u} \mathbf{b} \rfloor \quad \text{valid for } X \text{ since } \mathbf{x} \in \mathbb{Z}^n$$

Theorem

by applying this CG procedure a finite number of times every valid inequality for X can be obtained

Cutting Plane Algorithms

- $X \in P \cap \mathbb{Z}_+^n$
- a family of valid inequalities $\mathcal{F} : \mathbf{a}^T \mathbf{x} \leq b, (\mathbf{a}, b) \in \mathcal{F}$ for X
- we do not find them all a priori, only interested in those close to optimum

Cutting Plane Algorithm

Init.: $t = 0, P^0 = P$

Iter. t : Solve $\bar{z}^t = \max\{\mathbf{c}^T \mathbf{x} : \mathbf{x} \in P^t\}$

let \mathbf{x}^t be an optimal solution

if $\mathbf{x}^t \in \mathbb{Z}^n$ stop, \mathbf{x}^t is opt to the IP

if $\mathbf{x}^t \notin \mathbb{Z}^n$ solve separation problem for \mathbf{x}^t and \mathcal{F}

if (\mathbf{a}^t, b^t) is found with $\mathbf{a}^t \mathbf{x}^t > b^t$ that cuts off \mathbf{x}^t

$$P^{t+1} = P \cap \{\mathbf{x} : \mathbf{a}^i \mathbf{x} \leq b^i, i = 1, \dots, t\}$$

else stop (P^t is in any case an improved formulation)

Gomory's fractional cutting plane algorithm

Cutting plane algorithm + Chvátal-Gomory cuts

- $\max\{\mathbf{c}^T \mathbf{x} : \mathbf{Ax} = \mathbf{b}, \mathbf{x} \geq 0, \mathbf{x} \in \mathbb{Z}^n\}$
- Solve LPR to optimality

$$\left[\begin{array}{c|c|c|c} I & \bar{A}_N = A_B^{-1}A_N & 0 & \bar{\mathbf{b}} \\ \hline \bar{\mathbf{c}}_B & \bar{\mathbf{c}}_N (\leq 0) & 1 & -\bar{\mathbf{d}} \end{array} \right]$$

$$x_u = \bar{b}_u - \sum_{j \in N} \bar{a}_{uj} x_j, \quad u \in B$$
$$z = \bar{d} + \sum_{j \in N} \bar{c}_j x_j$$

- If basic optimal solution to LPR is not integer then \exists some row u :
 $\bar{b}_u \notin \mathbb{Z}^1$.

The Chvátal-Gomory cut applied to this row is:

$$x_{B_u} + \sum_{j \in N} \lfloor \bar{a}_{uj} \rfloor x_j \leq \lfloor \bar{b}_u \rfloor$$

(B_u is the index in the basis B corresponding to the row u)

(cntd)

- Eliminating $x_{B_u} = \bar{b}_u - \sum_{j \in N} \bar{a}_{uj} x_j$ in the CG cut we obtain:

$$\sum_{j \in N} \underbrace{(\bar{a}_{uj} - \lfloor \bar{a}_{uj} \rfloor)}_{0 \leq f_{uj} < 1} x_j \geq \underbrace{\bar{b}_u - \lfloor \bar{b}_u \rfloor}_{0 < f_u < 1}$$

$$\sum_{j \in N} f_{uj} x_j \geq f_u$$

$f_u > 0$ or else u would not be row of fractional solution. It implies that x^* in which $x_N^* = 0$ is cut out!

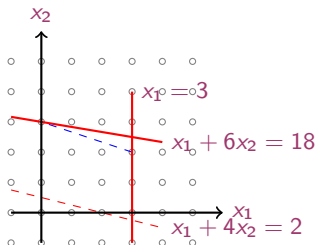
- Moreover: when x is integer, since all coefficient in the CG cut are integer the slack variable of the cut is also integer:

$$s = -f_u + \sum_{j \in N} f_{uj} x_j$$

(theoretically it terminates after a finite number of iterations, but in practice not successful.)

Example

$$\begin{aligned} \max \quad & x_1 + 4x_2 \\ \text{s.t.} \quad & x_1 + 6x_2 \leq 18 \\ & x_1 \leq 3 \\ & x_1, x_2 \geq 0 \\ & x_1, x_2 \text{ integer} \end{aligned}$$



	x1	x2	x3	x4	-z	b
	1	6	1	0	0	18
	1	0	0	1	0	3
	1	4	0	0	1	0

	x1	x2	x3	x4	-z	b
	0	1	1/6	-1/6	0	15/6
	1	0	0	1	0	3
	0	0	-2/3	-1/3	1	-13

$x_2 = 5/2, x_1 = 3$
Optimum, not integer

- We take the first row:

$$| \quad | \quad 0 \quad | \quad 1 \quad | \quad 1/6 \quad | \quad -1/6 \quad | \quad 0 \quad | \quad 15/6 \quad |$$

- CG cut $\sum_{j \in N} f_{uj}x_j \geq f_u \rightsquigarrow \frac{1}{6}x_3 + \frac{5}{6}x_4 \geq \frac{1}{2}$
- Let's see that it leaves out x^* : from the CG proof:

$$\begin{array}{r} 1/6 (x_1 + 6x_2 \leq 18) \\ 5/6 (x_1 \leq 3) \\ \hline x_1 + x_2 \leq 3 + 5/2 = 5.5 \end{array}$$

since x_1, x_2 are integer $x_1 + x_2 \leq 5$

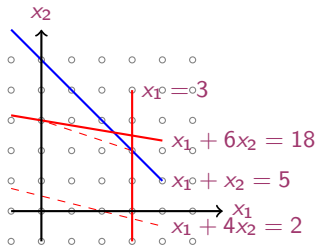
- Let's see how it looks in the space of the original variables: from the first tableau:

$$x_3 = 18 - 6x_2 - x_1$$

$$x_4 = 3 - x_1$$

$$\frac{1}{6}(18 - 6x_2 - x_1) + \frac{5}{6}(3 - x_1) \geq \frac{1}{2} \quad \rightsquigarrow \quad x_1 + x_2 \leq 5$$

- Graphically:



- Let's continue:

	x_1	x_2	x_3	x_4	x_5	$-z$	b
	0	0	$-1/6$	$-5/6$	1	0	$-1/2$
	0	1	$1/6$	$-1/6$	0	0	$5/2$
	1	0	0	1	0	0	3
	0	0	$-2/3$	$-1/3$	0	1	-13

We need to apply dual-simplex
(will always be the case, why?)

ratio rule: $\min\left\{\left|\frac{c_j}{a_{ij}}\right| : a_{ij} < 0\right\}$

- After the dual simplex iteration:

	x_1	x_2	x_3	x_4	x_5	$-z$	b
	0	0	$1/5$	1	$-6/5$	0	$3/5$
	0	1	$1/5$	0	$-1/5$	0	$13/5$
	1	0	$-1/5$	0	$6/5$	0	$12/5$
	0	0	$-3/5$	0	$-2/5$	1	$-64/5$

- In the space of the original variables:

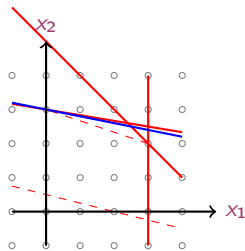
$$4(18 - x_1 - 6x_2) + (5 - x_1 - x_2) \geq 2$$

$$x_1 + 5x_2 \leq 15$$

We can choose any of the three rows.

Let's take the third: CG cut:

$$\frac{4}{5}x_3 + \frac{1}{5}x_5 \geq \frac{2}{5}$$



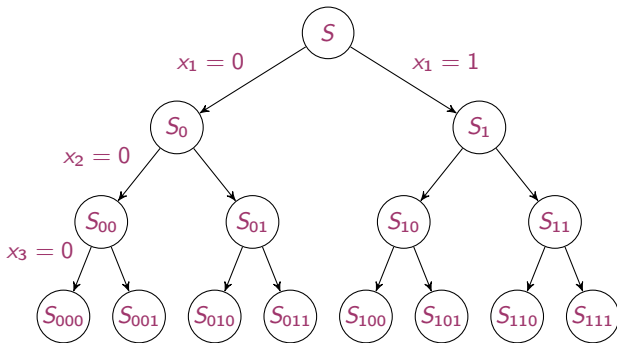
- ...

1. Cutting Plane Algorithms

2. Branch and Bound

- Consider the problem $z = \max\{c^T x : x \in S\}$
- Divide and conquer: let $S = S_1 \cup \dots \cup S_k$ be a decomposition of S into smaller sets, and let $z^k = \max\{c^T x : x \in S_k\}$ for $k = 1, \dots, K$. Then $z = \max_k z^k$

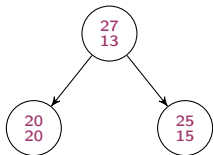
For instance if $S \subseteq \{0, 1\}^3$ the enumeration tree is:



Let's consider a maximization problem (gurobi's default is minimization)

- Let \bar{z}^k be an upper bound on z^k (dual bound)
- Let \underline{z}^k be a lower bound on z^k (primal bound)
- $(\underline{z}^k \leq z^k \leq \bar{z}^k)$
- $\underline{z} = \max_k \underline{z}^k$ is a lower bound on z
- $\bar{z} = \max_k \bar{z}^k$ is an upper bound on z

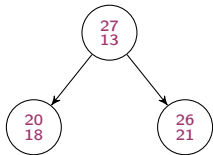
Pruning



$$\bar{z} = 25$$

$$\underline{z} = 20$$

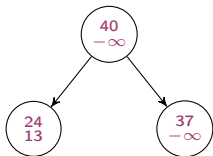
pruned by optimality



$$\bar{z} = 26$$

$$\underline{z} = 21$$

pruned by bounding

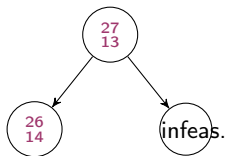


$$\bar{z} = 37$$

$$\underline{z} = 13$$

nothing to prune

Pruning



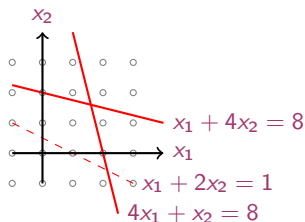
$$\bar{z} = 26$$

$$\underline{z} = 14$$

pruned by infeasibility

Example

$$\begin{aligned} \max \quad & x_1 + 2x_2 \\ & x_1 + 4x_2 \leq 8 \\ & 4x_1 + x_2 \leq 8 \\ & x_1, x_2 \geq 0, \text{ integer} \end{aligned}$$



- Solve LP

	x_1	x_2	x_3	x_4	$-z$	b
I	1	4	1	0	0	8
II	4	1	0	1	0	8
III	1	2	0	0	1	0

	x_1	x_2	x_3	x_4	$-z$	b
I' = I - II'	0	15/4	1	-1/4	0	6
II' = 1/4 II	1	1/4	0	1/4	0	2
III' = III - II'	0	7/4	0	-1/4	0	-2

- continuing

	x_1	x_2	x_3	x_4	$-z$	b
I' = 4/15I	0	1	4/15	-1/15	0	24/15
II' = II - 1/4I'	1	0	-1/15	4/15	0	24/15
III' = III - 7/4I'	0	0	-7/15	-3/5	1	-2-14/5

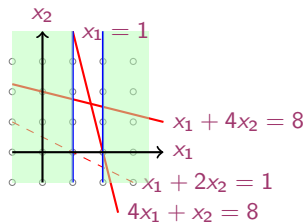
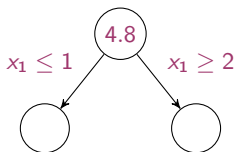
$$x_2 = 1 + 3/5 = 1.6$$

$$x_1 = 8/5$$

The optimal solution
will not be more than

$$2 + 14/5 = 4.8$$

- Both variables are fractional, we pick one of the two:



- Let's consider first the left branch:

	x1	x2	x3	x4	x5	-z	b
	1	0	0	0	1	0	1
	0	1	4/15	-1/15	0	0	24/15
	1	0	-1/15	4/15	0	0	24/15
	0	0	-7/15	-3/5	0	1	-24/5

	x1	x2	x3	x4	x5	b	-z
I' = I - III	0	0	1/15	-4/15	1	0	-9/15
	0	1	4/15	-1/15	0	0	24/15
	1	0	-1/15	4/15	0	0	24/15
	0	0	-7/15	-3/5	0	1	-24/5

	x1	x2	x3	x4	x5	b	-z
I' = -15/4I	0	0	-1/4	1	-15/4	0	9/4
II' = II - 1/4I	0	1	15/60	0	-1/4	0	7/4
III' = III + I	1	0	0	0	1	0	1
	0	0	-37/60	0	-9/4	1	-90/20

always a b term
negative after
branching:

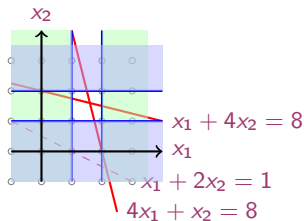
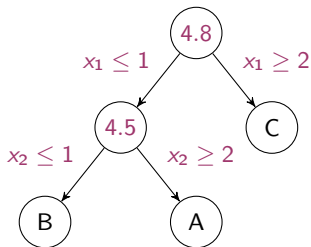
$$b_1 = \lfloor \bar{b}_3 \rfloor$$

$$\bar{b}_1 = \lfloor \bar{b}_3 \rfloor - b_3 < 0$$

Dual simplex:

$$\min_j \left\{ \left| \frac{c_j}{a_{ij}} \right| : a_{ij} < 0 \right\}$$

- Let's branch again



We have three open problems. Which one we choose next?
Let's take A.

	x1	x2	x3	x4	x5	x6	b	-z
	0	-1	0	0	0	1	0	-2
	0	0	-1/4	1	-15/4		0	9/4
	0	1	15/60	0	-1/4		0	7/4
	1	0	0	0	1		0	1
	0	0	-37/60	0	-9/4		1	-9/2

	x1	x2	x3	x4	x5	x6	b	-z
III+I	0	0	1/4	0	-1/4	1	0	-1/4
	0	0	-1/4	1	-15/4		0	9/4
	0	1	15/60	0	-1/4		0	7/4
	1	0	0	0	1		0	1
	0	0	-37/60	0	-9/4		1	-9/2

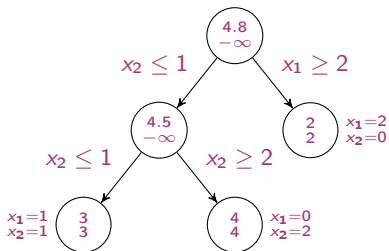
continuing we find:

$$x_1 = 0$$

$$x_2 = 2$$

$$OPT = 4$$

The final tree:



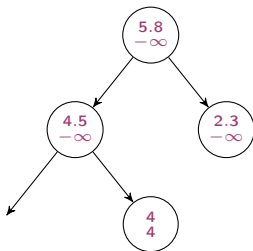
The optimal solution is 4.

Pruning:

1. by optimality: $z^k = \max\{c^T x : x \in S^k\}$

2. by bound $\bar{z}^k \leq \underline{z}$

Example:



3. by infeasibility $S^k = \emptyset$

B&B Components

Bounding:

1. LP relaxation
2. Lagrangian relaxation
3. Combinatorial relaxation
4. Duality

Branching:

$$S_1 = S \cap \{x : x_j \leq \lfloor \bar{x}_j \rfloor\}$$

$$S_2 = S \cap \{x : x_j \geq \lceil \bar{x}_j \rceil\}$$

thus the current optimum is not feasible either in S_1 or in S_2 .

Which variable to choose?

Eg: Most fractional variable $\arg \max_{j \in C} \min\{f_j, 1 - f_j\}$

Choosing Node for Examination from the list of active (or open):

- Depth First Search (a good primal sol. is good for pruning + easier to reoptimize by just adding a new constraint)
- Best Bound First: (eg. largest upper: $\bar{z}^s = \max_k \bar{z}^k$ or largest lower - to die fast)
- Mixed strategies

Reoptimizing: dual simplex

Updating the Incumbent: when new best feasible solution is found:

$$\underline{z} = \max\{\underline{z}, 4\}$$

Store the active nodes: bounds + optimal basis (remember the revised simplex!)

Enhancements

- Preprocessor: constraint/problem/structure specific tightening bounds
redundant constraints
variable fixing: eg: $\max\{\mathbf{c}^T \mathbf{x} : \mathbf{A}\mathbf{x} \leq \mathbf{b}, \mathbf{l} \leq \mathbf{x} \leq \mathbf{u}\}$
fix $x_j = l_j$ if $c_j < 0$ and $a_{ij} > 0$ for all i
fix $x_j = u_j$ if $c_j > 0$ and $a_{ij} < 0$ for all i
- Priorities: establish the next variable to branch
- Special ordered sets SOS (or generalized upper bound GUB)

$$\sum_{j=1}^k x_j = 1 \quad x_j \in \{0, 1\}$$

instead of: $S_0 = S \cap \{\mathbf{x} : x_j = 0\}$ and $S_1 = S \cap \{\mathbf{x} : x_j = 1\}$
 $\{\mathbf{x} : x_j = 0\}$ leaves $k - 1$ possibilities
 $\{\mathbf{x} : x_j = 1\}$ leaves only 1 possibility
 hence tree unbalanced

here: $S_1 = S \cap \{\mathbf{x} : x_{j_i} = 0, i = 1..r\}$ and
 $S_2 = S \cap \{\mathbf{x} : x_{j_i} = 0, i = r + 1, \dots, k\}$, $r = \min\{t : \sum_{i=1}^t x_{j_i}^* \geq \frac{1}{2}\}$

- Cutoff value: a user-defined primal bound to pass to the system.
- Simplex strategies: simplex is good for reoptimizing but for large models interior points methods may work best.
- Strong branching: extra work to decide more accurately on which variable to branch:
 1. choose a set C of fractional variables
 2. reoptimize for each of them (in case for limited iterations)
 3. $\bar{z}_j^\downarrow, \bar{z}_j^\uparrow$ (dual bound of down and up branch)

$$j^* = \arg \min_{j \in C} \max\{\bar{z}_j^\downarrow, \bar{z}_j^\uparrow\}$$

ie, choose variable with largest decrease of dual bound, eg UB for max

There are four common reasons because integer programs can require a significant amount of solution time:

1. There is lack of node throughput due to troublesome linear programming node solves.
2. There is lack of progress in the best integer solution, i.e., the upper bound.
3. There is lack of progress in the best lower bound.
4. There is insufficient node throughput due to numerical instability in the problem data or excessive memory usage.

For 2) or 3) the gap best feasible-dual bound is large:

$$\text{gap} = \frac{|\text{Primal bound} - \text{Dual bound}|}{\text{Primal bound} + \epsilon} \cdot 100$$

- heuristics for finding feasible solutions (generally NP-complete problem)
- find better lower bounds if they are weak: addition of cuts, stronger formulation, **branch and cut**
- Branch and cut: a B&B algorithm with cut generation at all nodes of the tree. (instead of reoptimizing, do as much work as possible to tighten)

Cut pool: stores all cuts centrally

Store for active node: bounds, basis, pointers to constraints in the cut pool that apply at the node

We did not treat:

- LP: Dantzig Wolfe decomposition
- LP: Column generation
- LP: Delayed column generation
- IP: Branch and Price
- LP: Benders decompositions
- LP: Lagrangian relaxation

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