DM545/DM871
Linear and Integer Programming

# Lecture 3 <br> The Simplex Method 

Marco Chiarandini

Department of Mathematics \& Computer Science
University of Southern Denmark

## Outline

## 1. Simplex Method

Standard Form
Basic Feasible Solutions
Algorithm
Tableaux and Dictionaries

## Outline

\author{

1. Simplex Method
}

Standard Form<br>Basic Feasible Solutions<br>Algorithm<br>Tableaux and Dictionaries

## A Numerical Example

$$
\begin{aligned}
\max \sum_{j=1}^{n} c_{j} x_{j} & \\
\sum_{j=1}^{n} a_{i j} x_{j} & \leq b_{i}, \quad i=1, \ldots, m \\
x_{j} & \geq 0, \quad j=1, \ldots, n
\end{aligned}
$$

$$
\begin{aligned}
\max \mathbf{c}^{T} \mathbf{x} & \\
A \mathbf{x} & \leq \mathbf{b} \\
\mathbf{x} & \geq \mathbf{0}
\end{aligned}
$$

$\max 6 x_{1}+8 x_{2}$

$$
5 x_{1}+10 x_{2} \leq 60
$$

$$
4 x_{1}+4 x_{2} \leq 40
$$

$$
x_{1}, x_{2} \geq 0
$$

$$
\max \left[\begin{array}{ll}
6 & 8
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right]
$$

$$
\left[\begin{array}{cc}
5 & 10 \\
4 & 4
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right] \leq\left[\begin{array}{l}
60 \\
40
\end{array}\right]
$$

$$
x_{1}, x_{2} \geq 0
$$

## Outline

1. Simplex Method

Standard Form
Basic Feasible Solutions
Algorithm
Tableaux and Dictionaries

## Standard Form

Every LP problem can be converted in the standard form:

$$
\begin{aligned}
\max \mathbf{c}^{T} \mathbf{x} & \\
A \mathbf{x} & \leq \mathbf{b} \\
\mathbf{x} & \in \mathbb{R}^{n}
\end{aligned}
$$

$$
\mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m}
$$

and then be put in equational standard form:

```
\(\max \mathbf{c}^{\top} \mathbf{x}\)
        \(A \mathbf{x}=\mathbf{b}\)
        \(x \geq 0\)
\(\mathbf{x} \in \mathbb{R}^{n}, \mathbf{c} \in \mathbb{R}^{n}, A \in \mathbb{R}^{m \times n}, \mathbf{b} \in \mathbb{R}^{m}\)
```

- if equations, then put two constraints, $\mathrm{a} x \leq b$ and $\mathbf{a} x \geq b$
- if $\mathbf{a} x \geq b$ then $-\mathbf{a} x \leq-b$
- if $\min \mathbf{c}^{T} \mathbf{x}$ then $\max \left(-\mathbf{c}^{T} \mathbf{x}\right)$

1. " $=$ " constraints
2. $x \geq 0$ nonnegativity constraints
3. $(b \geq 0)$
4. $\max$

## Transformation to Std Form

Every LP problem can be transformed in eq. std. form

1. introduce slack variables (or surplus)

$$
\begin{aligned}
& 5 x_{1}+10 x_{2}+x_{3}=60 \\
& 4 x_{1}+4 x_{2}+x_{4}=40
\end{aligned}
$$

2. if $x_{1} \gtreqless 0$ then $\begin{aligned} & x_{1}= \\ & x_{1}^{\prime} \geq 0 \\ & x_{1}^{\prime \prime}\end{aligned}$

$$
x_{1}^{\prime \prime} \geq 0
$$

3. $(b \geq 0)$
4. $\min c^{T} x \equiv \max \left(-c^{T} x\right)$

LP in $m \times n$ converted into LP with at most $(m+2 n)$ variables and $m$ equations ( $n$ \# original variables, $m$ \# constraints)

## Geometry of LP in Eq. Std. Form

$$
\max \left\{\mathbf{c}^{T} \mathbf{x} \mid A \mathbf{x}=\mathbf{b}, \mathbf{x} \geq \mathbf{0}\right\}
$$

From linear algebra:

- the set of solutions of $A \mathbf{x}=\mathbf{b}$ is an affine space (hyperplane not passing through the origin).
- $\mathrm{x} \geq 0$ nonegative orthant (octant in $\mathbb{R}^{3}$ ) In $\mathbb{R}^{3}$ :

- $A \mathbf{x}=\mathbf{b}$ is a system of equations that we can solve by Gaussian elimination
- Elementary row operations of $[A \mid \mathbf{b}]$ do not affect set of feasible solutions
- multiplying all entries in some row of $[A \mid \mathbf{b}]$ by a nonzero real number $\lambda$
- replacing the $i$ th row of $[A \mid b]$ by the sum of the $i$ th row and $j$ th row for some $i \neq j$
- Let $n^{\prime}$ be the number of vars in eq. std. form.
we assume $n^{\prime} \geq m$ and $\operatorname{rank}([A \mid \mathbf{b}])=\operatorname{rank}(A)=m$
ie, rows of $A$ are linearly independent otherwise, remove linear dependent rows


## Outline

1. Simplex Method

Standard Form
Basic Feasible Solutions
Algorithm
Tableaux and Dictionaries

## Basic Feasible Solutions

Basic feasible solutions are the vertices of the feasible region:


More formally:
Let $B=\{1 \ldots m\}, N=\left\{m+1 \ldots n+m=n^{\prime}\right\}$ be subsets partitioning the columns of $A$ : $A_{B}$ be made of columns of $A$ indexed by $B$ :

Definition
$\mathbf{x} \in \mathbb{R}^{n}$ is a basic feasible solution of the linear program $\max \left\{\mathbf{c}^{T} \mathbf{x} \mid A \mathbf{x}=\mathbf{b}, \mathbf{x} \geq \mathbf{0}\right\}$ for an index set $B$ if:

- $x_{j}=0 \forall j \notin B$
- the square matrix $A_{B}$ is nonsingular, ie, all columns indexed by $B$ are lin. indep.
- $\mathrm{x}_{B}=A_{B}^{-1} \mathbf{b}$ is nonnegative, ie, $\mathrm{x}_{B} \geq 0$ (feasibility)

We call $x_{j}$ for $j \in B$ basic variables and remaining variables nonbasic variables.
Theorem
$A$ basic feasible solution is uniquely determined by the set $B$.
Proof:

$$
\begin{aligned}
A \mathbf{x}= & A_{B} \mathbf{x}_{B}+A_{N} \mathbf{x}_{N}=b \\
& \mathbf{x}_{B}+A_{B}^{-1} A_{N} \mathbf{x}_{N}=A_{B}^{-1} b \\
& \mathbf{x}_{B}=A_{B}^{-1} b
\end{aligned}
$$

$$
A_{B} \text { is nonsingular hence one solution }
$$

Note: we call $B$ a (feasible) basis

Extreme points and basic feasible solutions are geometric and algebraic manifestations of the same concept:

Theorem
Let $P$ be a (convex) polyhedron from LP in eq. std. form. For a point $v \in P$ the following are equivalent:
(i) $v$ is an extreme point (vertex) of $P$
(ii) $v$ is a basic feasible solution of $L P$

Proof: see text book [MG] sec. 4.4.
Theorem
Let $L P=\max \left\{\mathbf{c}^{\top} \mathbf{x} \mid A \mathbf{x}=\mathbf{b}, \mathbf{x} \geq \mathbf{0}\right\}$ be feasible and bounded, then the optimal solution is a basic feasible solution.

Proof. consequence of previous theorem and fundamental theorem of linear programming

Note, a similar theorem is valid for arbitrary linear programs (not in eq. form)
Definition
A basic feasible solution of a linear program with $n$ variables is a feasible solution for which some $n$ linearly independent constraints hold with equality.

However, an optimal solution does not need to be basic:

$$
\max x_{1}+x_{2} \text { subject to } x_{1}+x_{2} \leq 1
$$

- Idea for solution method:
- examine all basic solutions.
- There are finitely many: $\binom{m+n}{m}$.
- However, if $n=m$ then $\binom{2 m}{m} \approx 4^{m}$.


## Outline

1. Simplex Method

Standard Form
Basic Feasible Solutions

## Algorithm

Tableaux and Dictionaries

## Simplex Method

$$
\begin{aligned}
& \max \quad z=\left[\begin{array}{ll}
6 & 8
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2}
\end{array}\right] \\
& {\left[\begin{array}{llll}
5 & 10 & 1 & 0 \\
4 & 4 & 0 & 1
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2} \\
x_{3} \\
x_{4}
\end{array}\right] }=\left[\begin{array}{l}
60 \\
40
\end{array}\right] \\
& x_{1}, x_{2}, x_{3}, x_{4} \geq 0
\end{aligned}
$$

Canonical eq. std. form: one decision variable is isolated in each constraint with coefficient 1 and does not appear in the other constraints nor in the obj. func. and $b$ terms are positive

It gives immediately a basic feasible solution:

$$
x_{1}=0, x_{2}=0, x_{3}=60, x_{4}=40
$$

Is it optimal? Look at signs in $z \rightsquigarrow$ if positive then an increase would improve.

Let's try to increase a promising variable, ie, $x_{1}$, one with positive coefficient in $z$

$$
\begin{aligned}
& 5 x_{1}+x_{3}=60 \\
& x_{1}=\frac{60}{5}-\frac{x_{3}}{5} \\
& x_{3}=60-5 x_{1} \geq 0
\end{aligned}
$$

$$
\text { If } x_{1}>12 \text { then } x_{3}<0
$$



$$
\begin{aligned}
& 4 x_{1}+x_{4}=40 \\
& x_{1}=\frac{40}{4}-\frac{x_{4}}{4} \\
& x_{4}=40-4 x_{1} \geq 0
\end{aligned}
$$

If $x_{1}>10$ then $x_{4}<0$
we can take the minimum of the two $\rightsquigarrow x_{1}$ increased to 10

$x_{4}$ exits the basis and $x_{1}$ enters

## Simplex Tableau

First simplex tableau:

$$
\begin{aligned}
& \begin{array}{c:cccc} 
& x_{1} & x_{2} & x_{3} & x_{4}
\end{array}-z \quad b \\
& x_{4}: \begin{array}{lllllll}
4 & 4 & 0 & 1 & 0 & 40 \\
\hdashline 6 & 8 & 0 & 0 & 1 & 0
\end{array}
\end{aligned}
$$

we want to reach this new tableau

$$
\begin{array}{l:lll} 
& x_{1} & x_{2} & x_{3}
\end{array} x_{4}-z \quad b
$$

Pivot operation:

1. Choose pivot:
column: one $s$ with positive coefficient in obj. func.
row: ratio between coefficient $b$ and pivot column: choose the one with smallest ratio:

$$
\theta=\min _{i}\left\{\frac{b_{i}}{a_{i s}}: a_{i s}>0\right\}, \quad \begin{aligned}
& \theta \text { increase value } \\
& \text { of entering var. }
\end{aligned}
$$

2. elementary row operations to update the tableau

- $x_{4}$ leaves the basis, $x_{1}$ enters the basis
- Divide pivot row by pivot
- Send to zero the coefficient in the pivot column of the first row
- Send to zero the coefficient of the pivot column in the third (cost) row


From the last row we read: $2 x_{2}-3 / 2 x_{4}-z=-60$, that is: $z=60+2 x_{2}-3 / 2 x_{4}$. Since $x_{2}$ and $x_{4}$ are nonbasic we have $z=60$ and $x_{1}=10, x_{2}=0, x_{3}=10, x_{4}=0$.

- Done? No! Let $x_{2}$ enter the basis


Definition (Reduced costs)
We call reduced costs the coefficients in the objective function of the nonbasic variables, $\bar{c}_{N}$

## Proposition (Optimality Condition)

The basic feasible solution is optimal when the reduced costs in the corresponding simplex tableau are nonpositive, ie, such that:

$$
\bar{c}_{N} \leq 0
$$

Proof: Let $z_{0}$ be the obj value when $\bar{c}_{N} \leq 0$. For any other feasible solution $\tilde{x}$ we have:

$$
\tilde{\mathbf{x}}_{N} \geq 0 \quad \text { and } \quad \mathbf{c}^{T} \tilde{\mathbf{x}}=z_{0}+\overline{\mathbf{c}}_{N}^{T} \tilde{\mathbf{x}}_{N} \leq z_{0}
$$

## Graphical Representation




## Outline

1. Simplex Method

Standard Form
Basic Feasible Solutions
Algorithm
Tableaux and Dictionaries

## Tableaux and Dictionaries

$$
\begin{aligned}
\max \sum_{j=1}^{n} c_{j} x_{j} & \\
\sum_{j=1}^{n} a_{i j} x_{j} & \leq b_{i}, \quad i=1, \ldots, m \\
x_{j} & \geq 0, \quad j=1, \ldots, n
\end{aligned}
$$

$$
\begin{aligned}
& x_{n+i}=b_{i}-\sum_{j=1}^{n} a_{i j} x_{j}, \quad i=1, \ldots, m \\
& z=\sum_{j=1}^{n} c_{j} x_{j}
\end{aligned}
$$

Tableau

$$
\left[\begin{array}{c:c:c:c}
1 & \bar{A}_{N} & 0 & \bar{b} \\
\hdashline 0 & \overline{\bar{c}}_{N} & 1 & -\bar{d}
\end{array}\right]
$$

Dictionary

$$
\begin{aligned}
& x_{r}=\bar{b}_{r}-\sum_{s \notin B} \bar{a}_{r s} x_{s}, \quad r \in B \\
& z=\bar{d}+\sum_{s \notin B} \bar{c}_{s} x_{s}
\end{aligned}
$$

pivot operations in dictionary form:
choose col $s$ with r.c. $>0$
choose row with $\min \left\{-\bar{b}_{i} / \bar{a}_{i s} \mid a_{i s}<0, i=1, \ldots, m\right\}$ update: express entering variable and substitute in other rows

## Example

$$
\begin{array}{rlll}
\max 6 x_{1}+8 x_{2} \\
5 x_{1}+10 x_{2} & \leq & 60 \\
4 x_{1}+4 x_{2} & \leq 40 \\
x_{1}, x_{2} & \geq 0
\end{array}
$$

$$
\begin{aligned}
& x_{3}=60-5 x_{1}-10 x_{2} \\
& x_{4}=40-4 x_{1}-4 x_{2} \\
& -z=+6 x_{1}+8 x_{2}
\end{aligned}
$$

After 2 iterations:

$$
\begin{aligned}
& x_{1}: \begin{array}{llll}
1 & 0 & -1 / 5 & 1 / 2 \\
0 & 0 & 8 \\
\hdashline & -2 / 5 & -1 & -64
\end{array} \\
& x_{2}=2-1 / 5 x_{3}+1 / 4 x_{4}
\end{aligned}
$$

## Summary

## 1. Simplex Method

Standard Form
Basic Feasible Solutions
Algorithm
Tableaux and Dictionaries

