

DM87
SCHEDULING,
TIMETABLING AND ROUTING

Lecture 7

Constraint Programming in Practice

Marco Chiarandini

Outline

1. An Overview of Software for CP
2. CP Modelling Techniques
 - Propagators
 - Global Constraints
 - Symmetry Breaking
 - Reification
 - CP in Scheduling
3. Exercise

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Constraint Programming Systems

CP systems must provide reusable services for:

- ▶ Variable domains
 - finite domain integer, finite sets, multisets, intervals, ...
- ▶ Constraints
 - distinct, arithmetic, scheduling, graphs, ...
- ▶ Solving
 - propagation, branching, exploration, ...
- ▶ Modelling
 - variables, values, constraints, heuristics, symmetries, ...

CP modelling

Greater expressive power than mathematical programming

- ▶ constraints involving disjunction can be represented directly
- ▶ constraints can be encapsulated (as predicates) and used in the definition of further constraints

However, CP models can often be translated into MIP model by

- ▶ eliminating disjunctions in favor of auxiliary Boolean variables
- ▶ unfolding predicates into their definitions

CP System Interfaces

Two possible interfaces:

- ▶ host language
- ▶ libraries

Modelling Language

- ▶ Fundamental difference to LP
 - ▶ language has structure (global constraints)
 - ▶ different solvers support different constraints
- ▶ In its infancy
- ▶ Key questions:
 - ▶ what level of abstraction?
 - ▶ solving approach independent: LP, CP, ...?
 - ▶ how to map to different systems?
 - ▶ Modelling is very difficult for CP
 - ▶ requires lots of knowledge and tinkering

Modelling Languages

- ▶ Prolog
 - ▶ B-Prolog (Prolog based, proprietary)
 - ▶ CHIP V5 (Prolog based, also includes C++ and C libraries, proprietary)
 - ▶ Ciao Prolog (Prolog based, Free software: GPL/LGPL)
 - ▶ ECLiPSe (Prolog based, open source)
 - ▶ SICStus (Prolog based, proprietary)
 - ▶ GNU Prolog
- ▶ OPL
- ▶ Zinc, MiniZinc, FlatZinc

CP Systems

▶ Library-based

- ▶ CHOCO (free) <http://choco.sourceforge.net/>
- ▶ Kaolog (commercial) <http://www.kaolog.com/php/index.php>
- ▶ Gecode (free) www.gecode.org
Programming interfaces Java and MiniZinc, library C++

CP Systems

▶ Language-based

- ▶ SICStus Prolog (commercial) www.sics.se/sicstus
Prolog language, library
- ▶ ECLiPSe (free) www.eclipse-clp.org
Prolog language, library
- ▶ Mozart (free) <http://www.mozart-oz.org>
Oz language
- ▶ ILOG CP Optimizer <http://www.ilog.com/products/>
OPL Language, libraries C/C++/
- ▶ CHIP (commercial) <http://www.cosytec.com>
Prolog language, library C/C++
- ▶ G12 Project <http://www.g12.cs.mu.oz.au/>

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Solving CP

- ▶ Compute with possible values
rather than enumerating assignments
- ▶ Prune inconsistent values
constraint propagation
- ▶ Search
 - branch: define search tree
 - explore: explore search tree for solution
 - branching heuristics
 - best solution search (in optimization)

Propagators

CP Systems do not compute constraints extensionally (as a collection of assignments):

- ▶ impractical (space)
- ▶ would make difficult to take advantage of **structure**

A Constraint c is **implemented** by a set of **propagators** (also known as **filtering algorithms** and narrowing operators).

A propagator p is a function that maps domains to domains. They are **decreasing** and **monotonic**.

A set of propagators **implements** a constraint c if all $p \in P$ are **correct** for c and P is **checking** for c . Notation: $P = \text{prop}(c)$

Execution of Propagators

- ▶ Execution of propagator p
 - ▶ narrows domains of variables in $\text{var}(p)$
 - ▶ signals failure
- ▶ Execution computes largest simultaneous fixpoint
 - ▶ fixpoint: propagators cannot narrow any further
 - ▶ largest: no solutions lost
- ▶ Propagator is either
 - fix: has reached fixpoint
 - runnable: not known to have reached fixpoint
- ▶ Propagation execution maintains propagator sets
- ▶ Propagators know their variables
 - ▶ to perform domain modifications
 - ▶ passed as parameters to propagator creation
- ▶ Variables know dependent propagators
 - ▶ to perform efficient computation of dependent propagators

Global Constraints

- ▶ Classic example: $x, y, z \in \{1, 2\}, \quad x \neq y, x \neq z, y \neq z$
- ▶ No solution!
- ▶ But: each individual constraint still satisfiable!
no propagation possible!
- ▶ Solution: look at several constraints at once
 $\text{distinct}(x, y, z)$
- ▶ Specialization

Kinds of symmetries

- ▶ Variable symmetry:
permuting variables keeps solutions invariant
 $\{x_i \rightarrow v_i\} \in \text{sol}(P) \Leftrightarrow \{x_{\pi(i)} \rightarrow v_i\} \in \text{sol}(P)$
- ▶ Value symmetry: permuting values keeps solutions invariant
 $\{x_i \rightarrow v_i\} \in \text{sol}(P) \Leftrightarrow \{x_i \rightarrow \pi(v_i)\} \in \text{sol}(P)$
- ▶ Variable/value symmetry:
permute both variables and values
 $\{x_i \rightarrow v_i\} \in \text{sol}(P) \Leftrightarrow \{x_{\pi(i)} \rightarrow \pi(v_i)\} \in \text{sol}(P)$

Symmetry

- ▶ inherent in the problem (sudoku, queens)
- ▶ artefact of the model (order of groups)

How can we avoid it?

- ▶ ... by model reformulation (eg, use set variables,
- ▶ ... by adding constraints to the model (ruling out symmetric solutions)
- ▶ ... during search
- ▶ ... by dominance detection

Reified constraints

- ▶ Constraints are in a big conjunction
- ▶ How about disjunctive constraints?

$$A + B = C \quad \vee \quad C = 0$$

- ▶ Solution: reify the constraints:

$$\begin{aligned} (A + B = C &\Leftrightarrow b_0) \wedge \\ (C = 0 &\Leftrightarrow b_1) \wedge \\ (b_0 \vee b_1 &\Leftrightarrow \text{true}) \end{aligned}$$

Scheduling Models

- ▶ Variable for start-time of task a $start(a)$
- ▶ Precedence constraint:
 $start(a) + dur(a) \leq start(b)$ (a before b)
- ▶ Disjunctive constraint:
 $start(a) + dur(a) \leq start(b)$ (a before b)
or
 $start(b) + dur(b) \leq start(a)$ (b before a)
Solved by reification
- ▶ Cumulative Constraints (renewable resources)
For tasks a and b on resource R
 $use(a) + use(b) \leq cap(R)$
or $start(a) + dur(a) \leq start(b)$
or $start(b) + dur(b) \leq start(a)$

Propagators for Scheduling

Serialization: ordering of tasks on one machine

- ▶ Consider all tasks on one resource
- ▶ Deduce their order as much as possible
- ▶ Propagators:
 - ▶ Timetabling: look at free/used time slots
 - ▶ Edge-finding: which task first/last?
 - ▶ Not-first / not-last

Job Shop Problem

- ▶ Hard problem!
- ▶ 6x6 instance solvable using Gecode
 - ▶ disjunction by reification
 - ▶ normal branching
- ▶ Classic 10x10 instance not solvable using Gecode!
 - ▶ specialized propagators (edge-finding) and branchings needed

References

- ▶ Lecture notes by Christian Schulte for courses at KTH, Sweden
- ▶ Lecture notes by Marco Kuhlmann and Guido Tack for courses at Saarland University

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Exercise

Write a MiniZinc model for the instance of Resource Constraint Project Scheduling Problem and solve the instance made available.

An installation of `minizinc-0.7` might be sufficient (uses G12 to solve the problem)

```
> mzn2fzn --data rcpsp.data rcpsp.mzn
> flatzinc jobshop.fzn
```

Otherwise, it is possible to use the interface `gecode-flatzinc-1.1` for `gecode-2.0.1`

```
> mzn2fzn --data rcpsp.data rcpsp.mzn
> fz jobshop.fzn
```