

EX 7. Ass. 1

- a) 4 variables, hence  $2^4 = 16$  models
- b) An implication is false if premise is true and conclusion false. There are 4 models where  $R \wedge C$  is ~~false~~ true. The negated conclusion is  $\neg(\neg A \wedge \neg B)$  which is just  $A \vee B$ , and this is true in 3 of the 4 models.
- c) Yes. It is equivalent to  $R \wedge C \Rightarrow \neg A$  and  $R \wedge C \Rightarrow \neg B$   
 In clause form, these become  $\neg R \vee \neg C \vee \neg A$  and  $\neg R \vee \neg C \vee \neg B$ .  
 These clause have zero positive literals, and hence are Horn.
- d) To prove that A does not entail B, one simply has to provide a model where A is true and B is false. The model is  $R, C, \neg B, O$

EX 9 Ass. 1

a) Prove  $A \Rightarrow B$  and  $B \Rightarrow A$ .  
 In both cases put in CNF and use resolution by unification.

<p>b) A: <math>\forall x [\exists y P(x,y)] \Rightarrow Q(x)</math>  <math>\forall x \neg [\exists y P(x,y)] \vee Q(x)</math>  <math>\forall x [\forall y \neg P(x,y)] \vee Q(x)</math>  <math>\forall x, y \neg P(x,y) \vee Q(x)</math>  <math>\neg P(x,y) \vee Q(x)</math></p>	<p>B: <math>\forall x, y P(x,y) \Rightarrow Q(x)</math>  <math>\forall x, y \neg P(x,y) \vee Q(x)</math>  <math>\neg P(x,y) \vee Q(x)</math>  <math>\neg B: \neg [\forall x, y P(x,y) \Rightarrow Q(x)]</math>  <math>\neg [\forall x, y \neg P(x,y) \vee Q(x)]</math>  <math>\exists x, y \neg [\neg P(x,y) \vee Q(x)]</math>  <math>\exists x, y [P(x,y) \wedge \neg Q(x)]</math>  <math>P(a, H) \wedge \neg Q(a)</math></p>
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$A \equiv B \rightsquigarrow A \wedge \neg B$   
 $\downarrow$   
 conjunction of 3 clauses  $\rightarrow$  resolution

$\frac{\neg P(x,y) \vee Q(x)}{P(a,H)} \quad \therefore Q(a) \quad \sigma = \{x/a, y/H\}$	$\frac{\neg P(x,y) \vee Q(x)}{\neg Q(a)} \quad \therefore \neg P(a,y) \quad \sigma = \{x/a\}$	$\frac{\neg Q(a)}{Q(a)} \quad \therefore \emptyset$
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$A \wedge \neg B$  is FALSE hence  $A \equiv B$

Ex 1 Ass. 2

a)  $P(\text{Tootache}) = 0,108 + 0,012 + 0,016 + 0,064 = 0,120 + 0,08 = 0,2$

b)  $P(\text{Cavity}) = \langle 0,108 + 0,012 + 0,072 + 0,008; 0,016 + 0,064 + 0,144 + 0,576 \rangle = \langle 0,2; 0,8 \rangle$

c)  $P(\text{Tootache} | \text{cavity}) = \langle \frac{0,108 + 0,012}{0,2}; \frac{0,072 + 0,008}{0,2} \rangle = \langle \frac{0,120}{0,2}; \frac{0,080}{0,2} \rangle = \langle 0,6; 0,4 \rangle$   
 $\frac{P(\text{Tootache}, \text{cavity})}{P(\text{cavity})} = \langle 0,6; 0,4 \rangle$

d)  $P(\text{Cavity} | \text{Tootache} \vee \text{catch}) = \frac{P(\text{Cavity}, \text{Tootache} \vee \text{catch})}{P(\text{Tootache} \vee \text{catch})} = \langle 0,4615; 0,5384 \rangle$

EX. 2 Ass. 2

$P(A, B | C) = P(A | C) P(B | C)$  cond. independence hence:

$P(A | B, C) = P(A | C)$  and  $P(B | A, C) = P(B | C)$

However, also:

SH. this has no sense:  
 $P(A, B | C) = P(A | C, B) = P(A | C) P(B | C)$

$\frac{P(A, B, C)}{P(B, C)} = P(A | B, C) \stackrel{\downarrow \text{product rule}}{=} P(A | C) P(B | C)$

$\frac{P(A, B, C)}{P(B, C)} \stackrel{\downarrow \text{Cond. prob.}}{=} \frac{P(A, B | C) P(C)}{P(B, C)} \stackrel{\downarrow \text{by hypothesis}}{=} \frac{P(A | C) P(B | C) P(C)}{P(B, C)} \stackrel{\downarrow \text{prod. rule inverse}}{=} \frac{P(A | C) P(B | C)}{P(B | C)}$

EX. 3 Ass. 2

a)  $P(x, y | e) = P(x | y, e) P(y | e)$

$P(x, y | e) = \frac{P(x, y, e)}{P(e)} = \frac{P(x | y, e) P(y, e)}{P(e)} = P(x | y, e) P(y | e)$

b)  $P(y | x, e) = \frac{P(x | y, e) P(y | e)}{P(x | e)}$

$P(y | x, e) = \frac{P(y, x, e)}{P(x, e)} = \frac{P(x | y, e) P(y, e)}{P(x, e)}$

cond. prob.

$= \frac{P(x | y, e) \cdot P(y | e) P(e)}{P(x | e) \cdot P(e)} \stackrel{\downarrow \text{Cond. prob.}}{=} \frac{P(x | y, e) P(y | e)}{P(x | e)}$

Ex. 4 Ass. 2

$$P(s|m) = 0,5$$

$$P(m) = 1/50000$$

$$P(s) = 1/20$$

$$P(m|s) = \frac{P(s|m) \cdot P(m)}{P(s)}$$

$$P(H|s) = \alpha \langle P(s|m) \cdot P(m), P(s|n) \cdot P(n) \rangle =$$

$$= \alpha \langle 0,5 \cdot \frac{1}{50000}; 0,05 \left(1 - \frac{1}{50000}\right) \rangle =$$

$$= \alpha \langle 1 \cdot 10^{-5}; 0,05 \cdot 0,99998 \rangle =$$

$$= \langle 0,0002; 0,9998 \rangle$$

Ex. 5 Ass. 2

$E_A$  A is executed

$F_B$  B is freed, the guard brings him the message

$$P(E_A | F_B) \stackrel{\text{Bayes}}{=} \frac{P(F_B | E_A) \cdot P(E_A)}{P(F_B)} \rightarrow \frac{\frac{1}{2} \cdot \frac{1}{3}}{\frac{1}{3}} = \frac{1}{2}$$

$$P(F_B | E_k) = \begin{cases} 0 & i=k \\ \frac{1}{2} & i \neq k \\ 1 & i=B, k=C \end{cases}$$

$$P(F_B) = P(F_B, E_A) + P(F_B, E_B) + P(F_B, E_C) =$$

$$= P(F_B | E_A) P(E_A) + P(F_B | E_B) P(E_B) + P(F_B | E_C) P(E_C)$$

$$= \frac{1}{2} \cdot \frac{1}{3} + 0 + 1 \cdot \frac{1}{3} = \frac{1}{2}$$

$$1 = P(E_A | F_B) + P(E_B | F_B) + P(E_C | F_B) \cdot$$

$$\frac{1}{3} \cdot \frac{P(F_B | E_B) \cdot P(E_B)}{P(F_B)} = 0$$

$$P(E_C | F_B) = \frac{2}{3}$$

EX. 6. ASS. 2.

$P(d_1) = 0,2$

$P(d_2) = 0,4$

$P(d_3) = 0,4$

$P(a_1|d_1) = 0,2$

$P(a_1|d_2) = 0,4$

$P(a_1|d_3) = 0,3$

$$P(d_2|a_1) = \frac{P(a_1|d_2) P(d_2)}{P(a_1)} = \frac{0,16}{0,32} = 0,5$$

$$P(a_1) = \sum_i P(a_1|d_i) P(d_i) = \sum P(a_1|d_i) P(d_i)$$
  
 ↓ marginal.                      ↓ cond. probs.

EX 7. ASS 2

a) i) incorrect: n° of stars not indep. of the focus given the measurements

ii) correct

iii) incorrect:  $M_1 \rightarrow M_2$  ? However, could still be plausible

b) ii) it has less parameters than iii) and is correct

c)  $P(M_1|N)$                        $N \in \{1, 2, 3\}$                        $M_1 \in \{0, 1, 2, 3, 4\}$

$$P(M_1|N) = \overset{\text{marg. + Cond. prob.}}{\cancel{P(M_1|N)}} P(M_1|N, \neg F_1) P(\neg F_1) + P(M_1|N, F_1) P(F_1)$$

f prob. of counting -3 because out of focus  
 e prob. of counting  $\pm 1$  if in focus  
 1-2e count is accurate

	$N=1$	$N=2$	$N=3$	$N=4$	$N=5$
$M_1=0$	$e(1-f) + f^2$	f	f		
$M_1=1$	$(1-2e)(1-f)$	$e(1-f)$	0		
$M_1=2$	$e(1-f)$	$(1-2e)(1-f)$	$e(1-f)$		
$M_1=3$	0	$e(1-f)$	$(1-2e)(1-f)$		
$M_1=4$	0	0	$e(1-f)$		
	$\Sigma = 1$	$\Sigma = 1$	$\Sigma = 1$		

d) Try all  $N=1, 2, \dots, n$  and see for which  $M_1=1$  and  $M_2=3$  are consistent. Or, try all possible focus states and deduce values for  $N$ . Answer:  $N=2, 4$  and  $\geq 6$

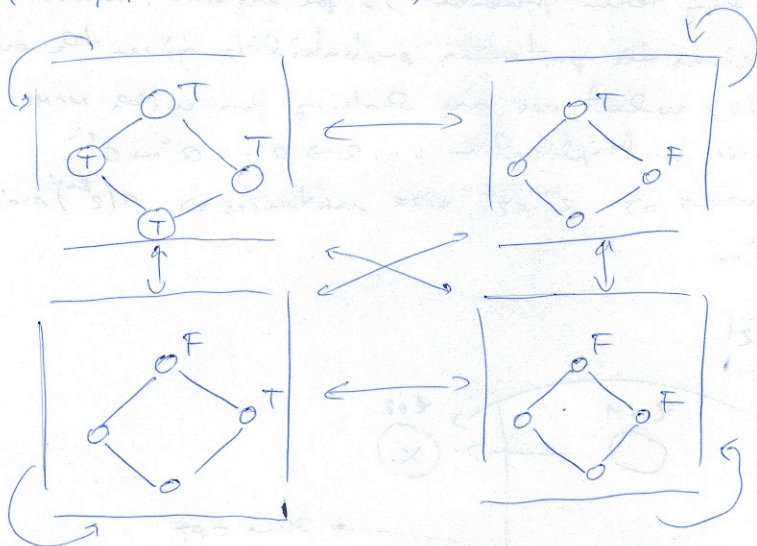
e) we need to know  $P(N)$ .  

$$P(N|M_1=1, M_2=3) = \frac{P(M_1=1, M_2=3|N) P(N)}{P(M_1=1) P(M_2=3)}$$

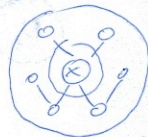
Ex-8 Dss. 2

$P(\text{Rain} | \text{Sprinkler} = T, \text{Wet} = T)$

a) 4:



b) Sampling distr. conditional to Markov blanket



$$P(C|R,S) = \alpha P(C)P(S|C)P(R|C) = \langle 0,5; 0,5 \rangle \langle 0,1; 0,5 \rangle \langle 0,8; 0,2 \rangle = \langle 4/9; 5/9 \rangle$$

$$P(C|R,S) = \alpha P(C)P(S|C)P(R|C) = \langle 1/21; 20/21 \rangle$$

$$P(R|C,S,W) = \alpha P(R|C)P(W|S,R) = \langle \quad \rangle \langle \quad \rangle = \langle 22/27, 5/27 \rangle$$

$$P(R|C,S,W) = \alpha P(R|C)P(W|S,R) = \langle \quad \rangle \langle \quad \rangle = \langle 11/54; 40/54 \rangle$$

Transition matrix

equal. prob. of sampling either of the two var.

loop  $q((C,R) \rightarrow (C,R)) = 0,5P(C|R,S) + 0,5P(R|C,S,W) = 17/27$

one var. changes  $q((C,R) \rightarrow (C, \neg R)) = 0,5P(\neg R|C,S,W) = 5/54$

both var. changes  $q((C,R) \rightarrow (\neg C, \neg R)) = 0$  cannot occur

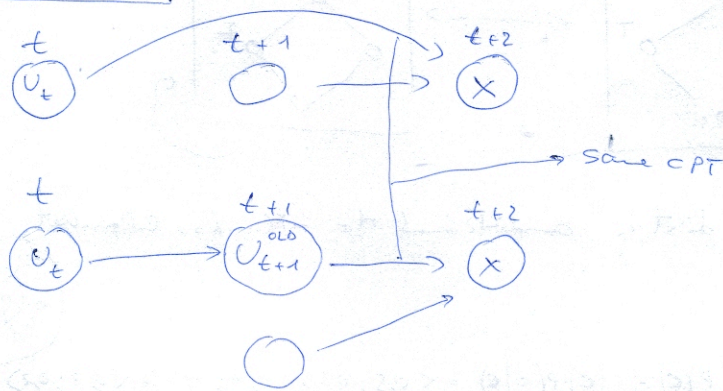
	(C,R)	(C,¬R)	(¬C,R)	(¬C,¬R)
(C,R)	17/27	5/54	5/54	0
(C,¬R)	11/54	22/54	0	;
(¬C,R)	;	0	;	;
(¬C,¬R)	0	;	;	;

c)  $Q^2$  prob. of going from each state to any other in 2 steps.

d)  $a^n$   $n \rightarrow \infty$  long term probability, for ergodic process this gives the posterior probability given the evidence, ie, what we are looking for with HMM

e) can do matrix multiplication:  $Q \rightarrow Q^2 \rightarrow Q^4 \rightarrow Q^{2^k}$   
 but if  $n$  vars  $\Rightarrow 2^n \times 2^n$  size matrices  $\Rightarrow O(2^{3n})$  matrix multiplication

Ex. 15.1 = 9 Ass. 2



introduce a new var in  $t+1$ ,  $U_{t+1}^{old}$  with CPT  $\begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix}$   
 with respect to  $U_t$ , ie,  $p(U_{t+1}^{old} | U_t)$

no effective increase in parameters.

Ex 10 Ass 2

$\Delta$  = activity

$P(\Delta = \text{walk}) = 0.5$

$w$  = weather

$$P(x|y,e) = \frac{P(x,y,e)}{P(y,e)} = \frac{P(x,y|e) \cdot P(e)}{P(y,e)} = \frac{P(x,y|e)}{P(y,e)}$$

$P(W_2 = \text{Rainy} | W_1 = \text{Sunny}, A_2 = \text{Read}) =$

$= \frac{P(W_2 = R, W_1 = S | A_2 = R)}{P(W_1 = S | A_1 = R)} =$   $W_1 \& A_1$  are indep.

$= \frac{P(W_2 = R, W_1 = S | A_2 = R)}{P(W_1 = S)} =$  Bayes

$= \frac{P(A_2 = R | W_1 = S, W_2 = R) \cdot P(W_2 = R, W_1 = S)}{P(W_1 = S) \cdot P(A_2 = R)} =$  Markov

$= \frac{P(A_2 = R | W_2 = R) \cdot P(W_2 = R, W_1 = S)}{P(W_1 = S) \cdot P(A_2 = R)} =$   $P(A,B) = P(A|B)P(B)$

$= \frac{P(W_2 = R | W_1 = S) \cdot P(W_1 = S)}{P(W_1 = S) \cdot P(A_2 = R)} =$

$= \frac{0.8 \cdot 0.05}{0.5} = 0.08$

5)  $P(W_3 = F | W_1 = F, A_2 = R, A_3 = W) =$

$= P(W_2 = F, W_3 = F | W_1 = F, A_2 = R, A_3 = W) +$   
 $+ P(W_2 = S, W_3 = F | W_1 = F, A_2 = R, A_3 = W) +$   
 $+ P(W_2 = R, W_3 = F | \dots)$  = by similar passages as above

$= \frac{P(A_3 = W | W_3 = F) \cdot P(A_2 = R | W_2 = F) \cdot P(W_3 = F | W_2 = F) \cdot P(W_2 = F | W_1 = F) \cdot P(W_1 = F)}{P(A_3 = W) \cdot P(A_2 = R) \cdot P(W_1 = F)} +$

+ similar passages for the other 2 terms.

$= \frac{0.7 \cdot 0.8 + 0.5 \cdot 0.15}{0.5 + 0.5 + 1} + \dots + \dots$

$= 0.119$