

DM812
METAHEURISTICS

Lecture 13
Heuristic Methods for Continuous
Optimization

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Outline

An Example
Heuristics for Continuous Optimization

1. An Application Example in Econometrics
2. Heuristics for Continuous Optimization

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Capital Asset Pricing Model

An Example
Heuristics for Continuous Optimization

Tool for pricing an individual asset i

Individual security's
reward-to-risk ratio $= \beta_i \cdot$ Market's securities
reward-to-risk ratio

$$(E(R_i) - R_f) = \beta_i \cdot (E(R_m) - R_f)$$

β_i sensitivity of the asset returns to market returns

Under normality assumption and least squares method:

$$\beta_i = \frac{\text{Cov}(R_i, R_m)}{\text{Var}(R_m)}$$

Alternatively:

$$R_{it} - R_{ft} = \beta_0 + \beta_1 \cdot (R_{mt} - R_{ft})$$

Use more robust techniques than least squares to determine β_0 and β_1
[Winker, Lyra, Sharpe, 2008]

$$Y_t = \beta_0 + \beta_1 X_t + \epsilon_t$$

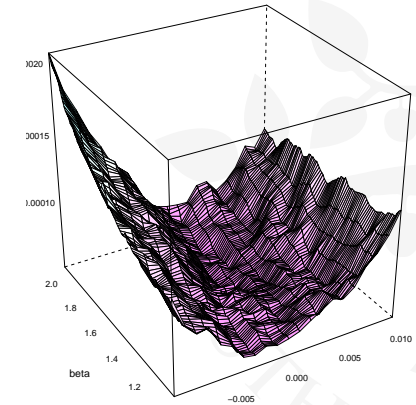
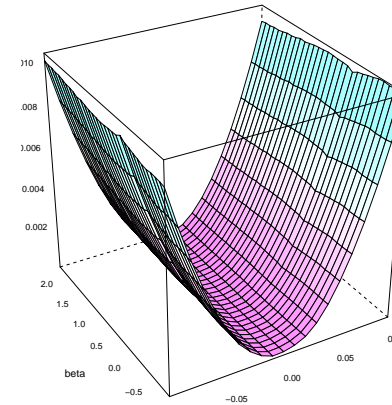
$$\epsilon_t^2 = (Y_t - \beta_0 - \beta_1 X_t)^2$$

least squares method:

$$\min \sum_{t=1}^n \epsilon_t^2$$

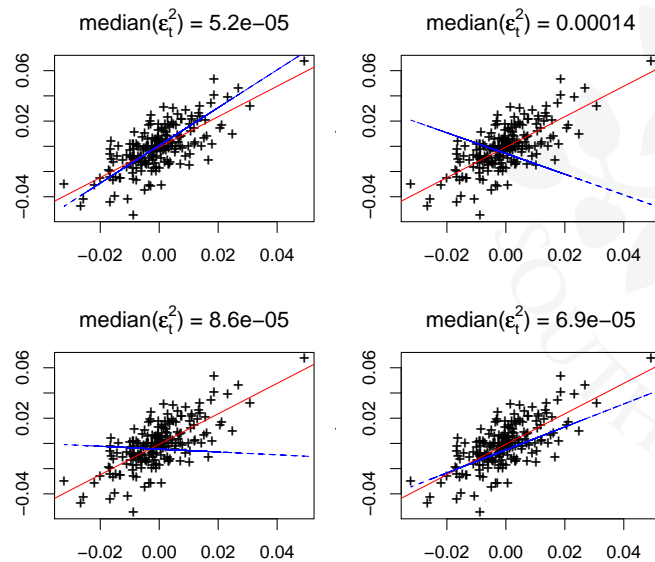
least median of squares method:

$$\min \{ \text{median} [\epsilon_t^2] \}$$



Outline

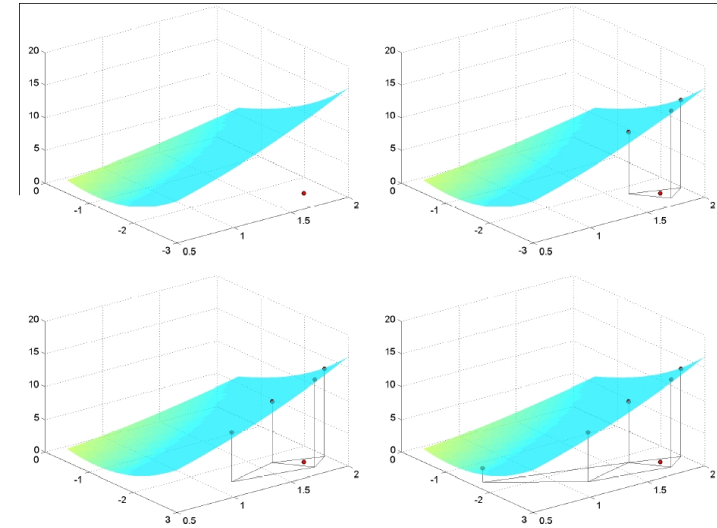
Four solutions corresponding to four different local optima
(red line: least squares; blue line: least median of squares)



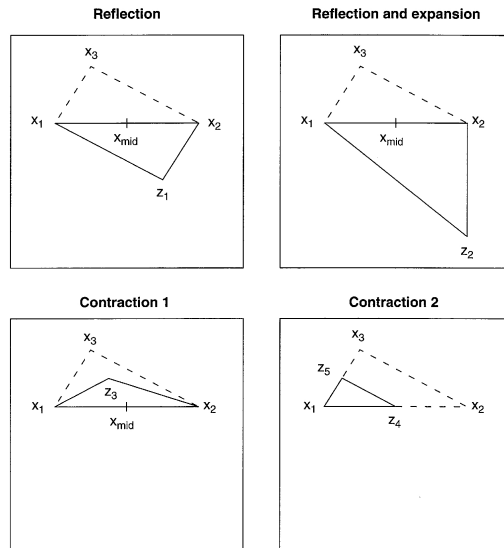
1. An Application Example in Econometrics
2. Heuristics for Continuous Optimization

- Nelder-Mead
- Simulated Annealing
- Differential Evolution
- Particle Swarm Optimization
- Genetic Algorithm
- Ant Colony Optimization

Simplex based method [Spendley et al. (1962)]



Nelder-Mead (cont.)



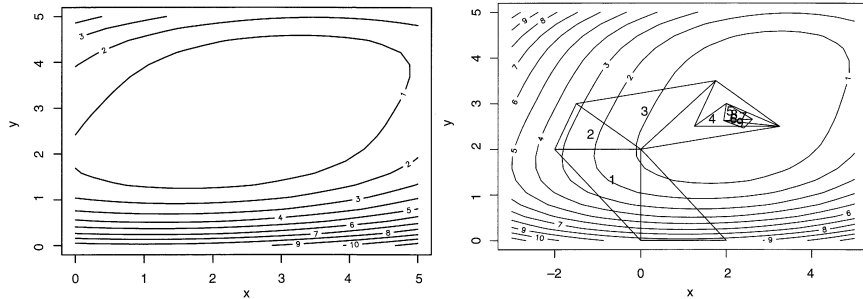
Nelder-Mead (cont.)

Nelder-Mead simplex method [Nelder and Mead, 1965]:

Algorithm 5 Simplex search.

- 1: Construct vertices $x^{(1)}, \dots, x^{(n+1)}$ of starting simplex
- 2: **repeat**
- 3: Rename vertices such that $f(x^{(1)}) \leq \dots \leq f(x^{(n+1)})$
- 4: **if** $f(x^R) < f(x^{(1)})$ **then**
- 5: **if** $f(x^E) < f(x^R)$ **then** $x^* = x^E$ **else** $x^* = x^R$
- 6: **else**
- 7: **if** $f(x^R) < f(x^{(n)})$ **then**
- 8: $x^* = x^R$
- 9: **else**
- 10: **if** $f(x^R) < f(x^{(n+1)})$ **then**
- 11: **if** $f(x^O) < f(x^{(n+1)})$ **then** $x^* = x^O$ **else shrink**
- 12: **else**
- 13: **if** $f(x^I) < f(x^{(n+1)})$ **then** $x^* = x^I$ **else shrink**
- 14: **end if**
- 15: **end if**
- 16: **end if**
- 17: **if not shrink then** $x^{(n+1)} = x^*$ (Replace worst vertex by x^*)
- 18: **until** stopping criteria verified

Example:

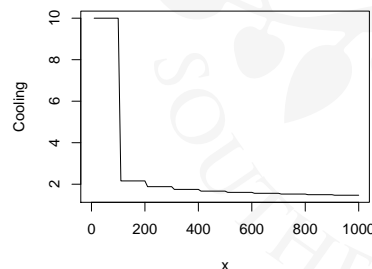
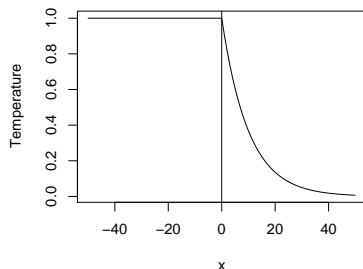


Simulated Annealing

Annealing schedule

- logarithmic cooling schedule [Belisle (1992)]

$$T = \frac{T_0}{\ln(\lfloor \frac{i-1}{I_{max}} \rfloor I_{max} + e)}$$



- threshold accepting [Dueck and Scheuer (1990)]
accept if $\Delta < \tau$

Simulated Annealing

Simulated Annealing (SA):

determine initial candidate solution s

set initial temperature $T = T_0$

while termination condition is not satisfied do

while keep T constant, that is, T_{max} iterations not elapsed do

probabilistically choose a neighbor s' of s

using proposal mechanism

accept s' as new search position with probability:

$$p(T, s, s') := \begin{cases} 1 & \text{if } f(s') \leq f(s) \\ \exp \frac{f(s) - f(s')}{T} & \text{otherwise} \end{cases}$$

update T according to annealing schedule

Proposal mechanism

The next candidate point is generated from a Gaussian Markov kernel with scale proportional to the actual temperature.

Differential Evolution

Differential Evolution (DE)

determine initial population P

while termination criterion is not satisfied do

for each solution x of P do

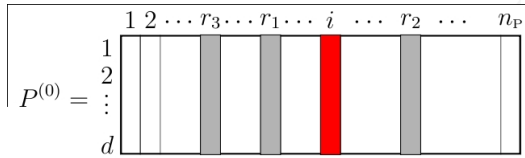
generate solution u from three solutions of P by mutation

generate solution v from u by recombination with solution x

select between x and v solutions

Differential Evolution (cont.)

An Example Heuristics for Continuous Optimization



- Solution representation: $x = (x_1, x_2, \dots, x_p)$
- Mutation:

$$u = r_1 + F \cdot (r_2 - r_3) \quad F \in [0, 2] \text{ and } (r_1, r_2, r_3) \in P$$

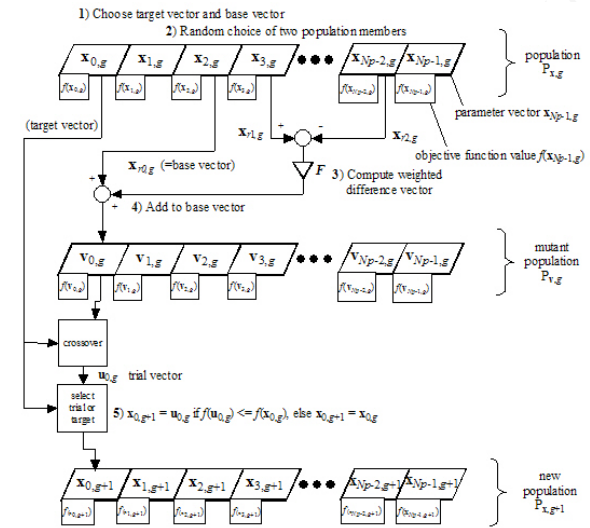
- Recombination:

$$v_j = \begin{cases} u_j & \text{if } p < CR \text{ or } j = r \\ x_j & \text{otherwise} \end{cases} \quad j = 1, 2, \dots, p$$

- Selection: replace x with v if $f(v)$ is better

Differential Evolution (cont.)

An Example Heuristics for Continuous Optimization



[<http://www.icsi.berkeley.edu/~storn/code.html>]
K. Price and R. Storn, 1995]

Particle Swarm Optimization

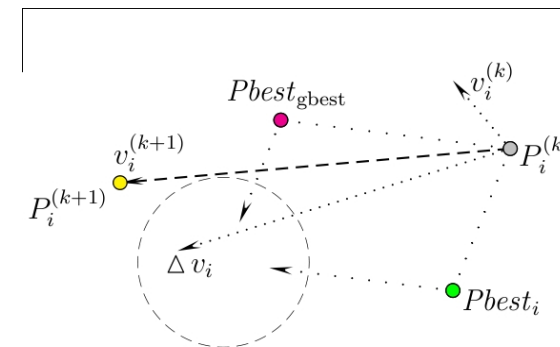
An Example Heuristics for Continuous Optimization

Particle Swarm Optimization

- 1: Initialize parameters n_P, n_G and c
- 2: Initialize particles $P_i^{(0)}$ and velocity $v_i^{(0)}, i = 1, \dots, n_P$
- 3: Evaluate objective function $F_i = f(P_i^{(0)}), i = 1, \dots, n_P$
- 4: $Pbest = P^{(0)}, Fbest = F, Gbest = \min_i(F_i), gbest = \operatorname{argmin}_i(F_i)$
- 5: **for** $k = 1$ to n_G **do**
- 6: **for** $i = 1$ to n_P **do**
- 7: $\Delta v_i = cu(Pbest_i - P_i^{(k-1)}) + cu(Pbest_{gbest} - P_i^{(k-1)})$
- 8: $v_i^{(k)} = v_i^{(k-1)} + \Delta v_i$
- 9: $P_i^{(k)} = P_i^{(k-1)} + v_i^{(k)}$
- 10: **end for**
- 11: Evaluate objective function $F_i = f(P_i^{(k)}), i = 1, \dots, n_P$
- 12: **for** $i = 1$ to n_P **do**
- 13: **if** $F_i < Fbest_i$ **then** $Pbest_i = P_i^{(k)}$ and $Fbest_i = F_i$
- 14: **if** $F_i < Gbest$ **then** $Gbest = F_i$ and $gbest = i$
- 15: **end for**
- 16: **end for**

Particle Swarm Optimization

An Example Heuristics for Continuous Optimization



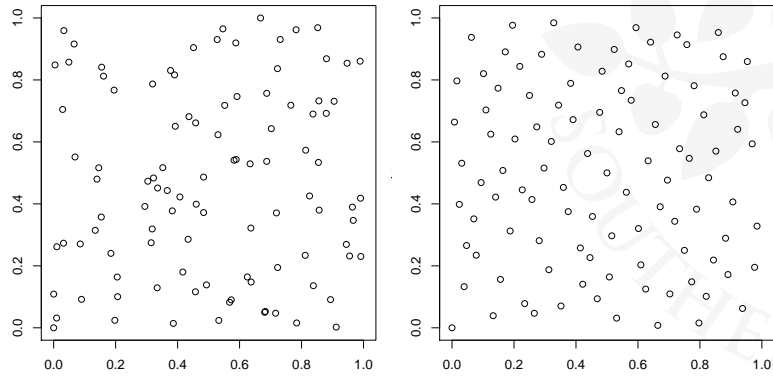
Generation of Initial Solutions

An Example
Heuristics for Continuous Optimization

Point generators:

Left: Uniform random distribution (pseudo random number generator)

Right: Quasi-Monte Carlo method: low discrepancy sequence generator
[Bratley, Fox and Niederreiter, 1994]



(for other methods see *spatial point process from spatial statistics*)