### **Lecture 1: Introduction, Processes & Threads**



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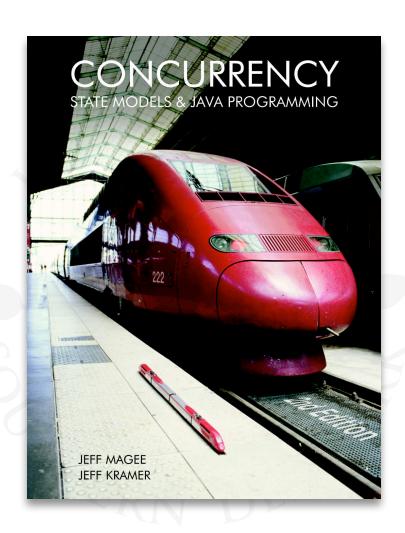
Christian Damsgard Jørgensen (D1) Martin Villumsen (D2)

#### **Textbook**

[M&K] Concurrency: State Models & Java Programs (2nd edition). Jeff Magee & Jeff Kramer. Wiley. 2006, ISBN: 0-470-09355-2

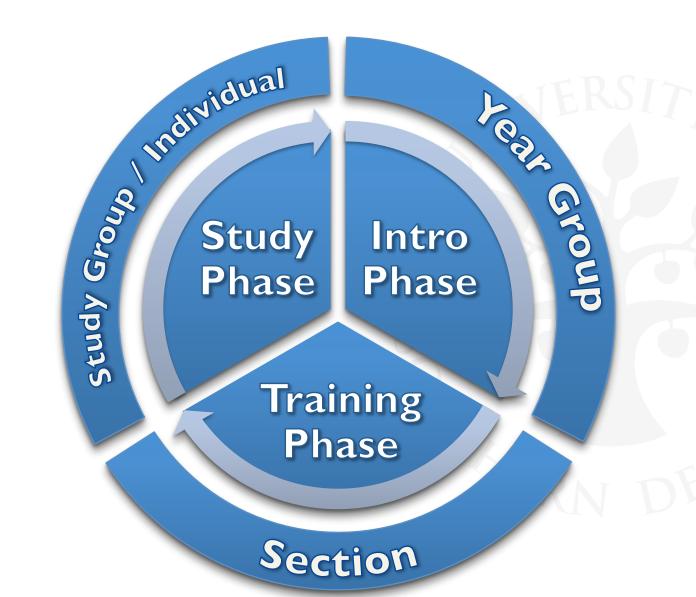
#### **Course Home Page**

http://imada.sdu.dk/~petersk/DM519/



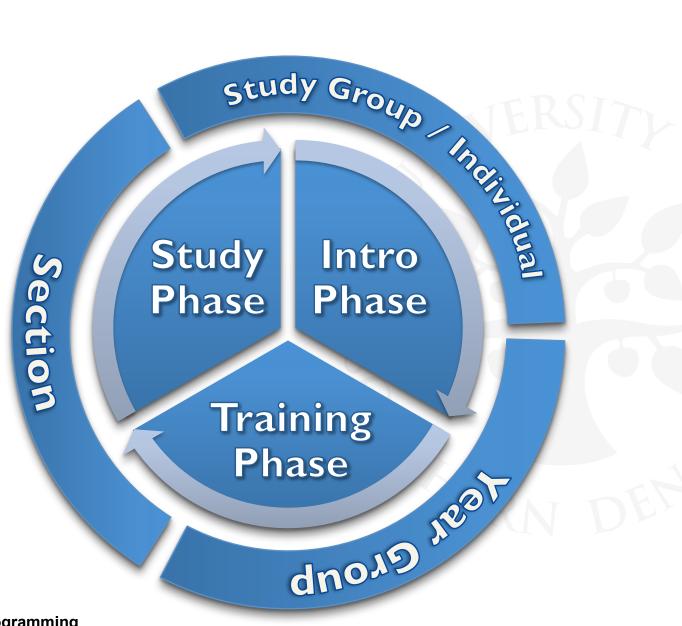
#### The Three Phase Model





## **Rotating the Classroom**





## **Concrete Implications for DM519**



You study the slides and/or book at home!

There will be a short quizz about the topics at the beginning of most lectures.

I will VERY FAST go through the slides, highlighting problem areas identified in the quiz.

The remaining time (>= 50%) will be used for more practical programming with threads in Java sessions.

## What is a Concurrent Program?

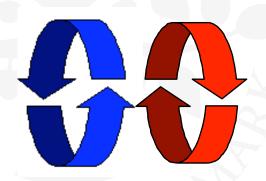


A sequential program has a single thread of control.



## A *concurrent* program has multiple threads of control:

- perform multiple computations in parallel
- control multiple external activities occurring simultaneously.



## **Why Concurrent Programming?**



#### More appropriate program structure

Concurrency reflected in program



#### Performance gain from multiprocessing HW

Parallelism



### Increased application throughput

An I/O call need only block one thread



#### **Increased application responsiveness**

High-priority thread for user requests



## **Concurrency is much Harder**



#### Harder than sequential programming:

- Huge number of possible executions
- Inherently non-deterministic
- Parallelism conceptually harder

#### **Consequences:**

- Programs are harder to write(!)
- Programs are harder to debug(!) (Heisenbugs)
- Errors are not always reproducible(!)
- New kinds of errors possible(!):
  - Deadlock, starvation, priority inversion, interference, ...

## Solution: Model-based Design



## Model: a simplified representation of the real world.

focus on concurrency aspects

#### Design abstract model

#### Decompose model

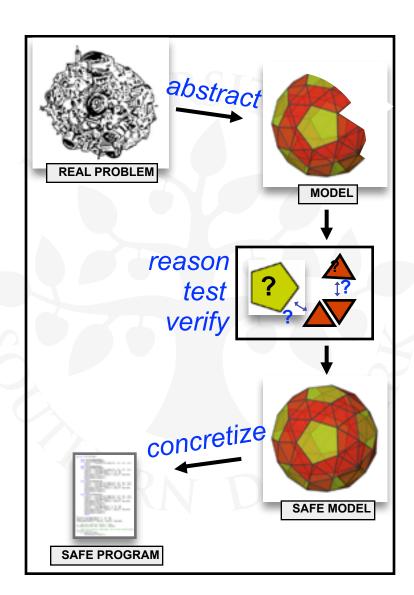
#### Reason/Test/Verify model

individual parts and whole

#### Recompose insights

make model safe

Implement concrete program



## What you will be able to do after the course



Construct models from specifications of concurrency problems

Test, analyze, and compare models' behavior

Define and verify models' safety/liveness properties (using tools)

Implement models in Java

Relate models and implementations

#### How to achieve them?



#### **Lectures**

Theoretical exercises during the discussion sections

Practical exercises in your study groups

#### **Evaluation: Graded project exam**

- mid-quarter deadline for model/design (March 15)
- end-quarter deadline for implementation & report (April 12)

#### **Concurrent Processes**



We structure complex systems as sets of simpler activities, each represented as a (sequential) process

Processes can be concurrent

Designing concurrent software:

- complex and error prone

Concept: process ~ sequences of actions



Model: process ~

Finite State Processes

(FSP)



Practice: process ~

Java thread

## **Modelling Processes**



Models are described using state machines, known as Labelled Transition Systems (LTS)

These are described textually as Finite State Processes (FSP)

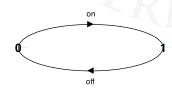
Analysed/Displayed by the LTS Analyser (LTSA)

- ♦ FSP algebraic form
- ♦ LTS graphical form

```
SWITCH = OFF,

OFF = (on -> ON),

ON = (off-> OFF).
```

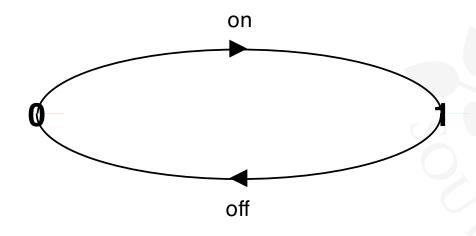


## **Modelling Processes**



A process is modelled by a sequential program.

It is modelled as a **finite state machine** which transits from state to state by executing a sequence of atomic actions.



a light switch

$$on \rightarrow off \rightarrow on \rightarrow off \rightarrow on \rightarrow off \rightarrow \dots$$

a sequence of actions or trace

## FSP - action prefix & recursion

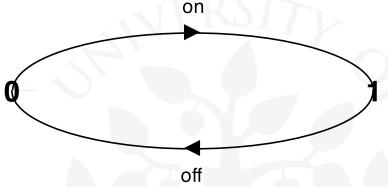


Repetitive behaviour uses recursion:

```
SWITCH = OFF,

OFF = (on -> ON),

ON = (off-> OFF).
```



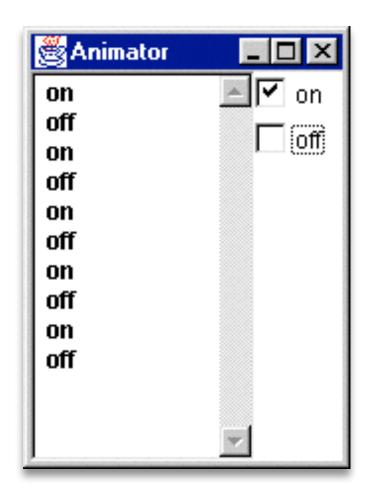
Substituting to get a more succinct definition:

#### Again?:

$$SWITCH = (on->off->SWITCH)$$
.

## **Animation using LTSA**

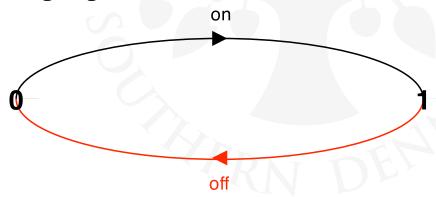




The LTSA animator can be used to produce a **trace**.

Ticked actions are eligible for selection.

In the LTS, the last action is highlighted in red.

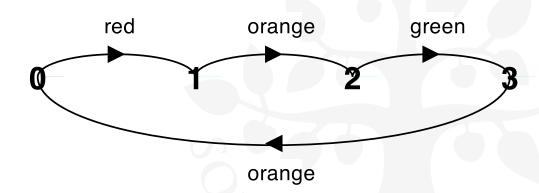


## **FSP** - action prefix



FSP model of a traffic light:

#### LTS?



Trace(s)?

red→orange→green→orange→red→orange→green ...

What would the LTS look like for?:

T = (red->orange->green->orange->STOP).

#### FSP - choice



If x and y are actions then  $(x->P \mid y->Q)$  describes a process which initially engages in either of the actions x or y. After the first action has occurred, the subsequent behavior is described by P if the first action was x; and Q if the first action was y.

Who or what makes the choice?

Is there a difference between input and output actions?

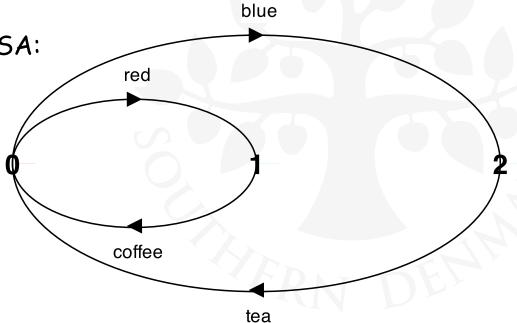
#### **FSP - choice**



FSP model of a drinks machine:

LTS generated using LTSA:

Possible traces?



#### Non-deterministic choice



Process ( $\times$  -> P |  $\times$  -> Q) describes a process which engages in  $\times$  and then **non-deterministically** behaves as either P or Q.

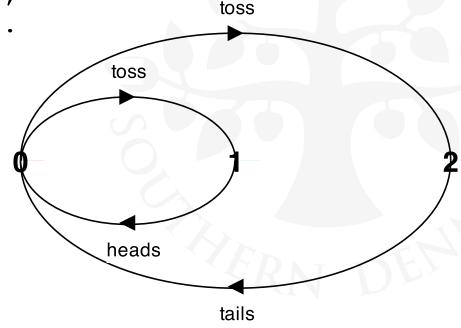
COIN = (toss->HEADS|toss->TAILS),
HEADS= (heads->COIN),

TAILS= (tails->COIN).

Tossing a coin.

LTS?

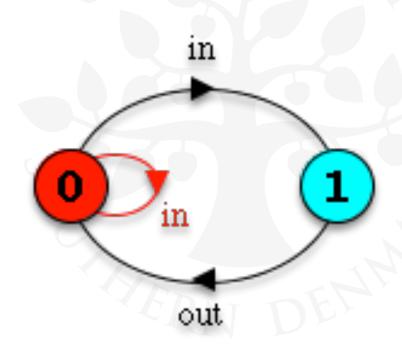
Possible traces?



# Example: Modelling unreliable communication Southern Denmark channel

How do we model an unreliable communication channel which accepts in actions and if a failure occurs produces no output, otherwise performs an out action?

Use non-determinism...:



## FSP - indexed processes and actions



Single slot buffer that inputs a value in the range 0 to 3 and then outputs that value:

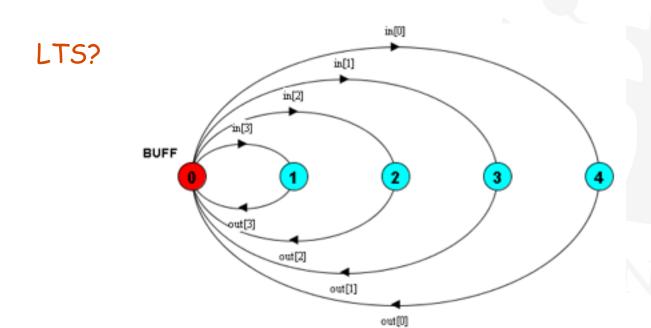
```
BUFF = (in[i:0..3] -> out[i] -> BUFF).
```

Define then Use (as in programming languages)

Could we have made this process w/o using the indices?

## Indices (cont'd)





## FSP - indexed processes and actions (cont'd), FSP - indexed processe



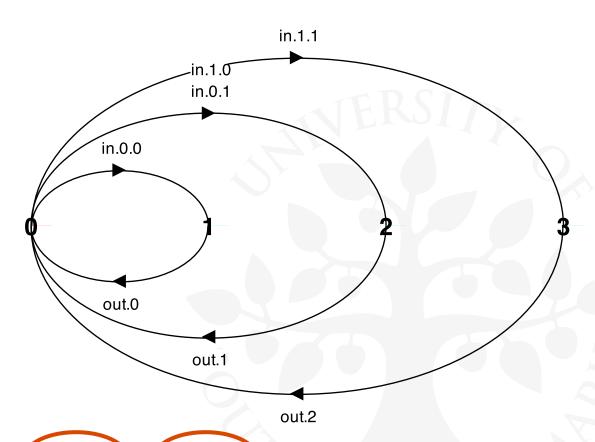
```
BUFF = (in[i:0..3] -> out[i] -> BUFF).
equivalent to
                 = (in[i:0..3]->OUT[i]),
    BUFF
    OUT[i:0..3] = (out[i]->BUFF).
equivalent to
                 = (in[i:0..3]->OUT[i]),
    BUFF
    OUT[j:0..3] = (out[j]->BUFF).
```

#### **FSP - constant & addition**



index expressions to model calculation:

const N = 1



SUM = 
$$(in[a:0..N]/b:0..N]$$
->TOTAL[a+b]),  
TOTAL[s  $0..2*N$ ] =  $(out[s]->SUM)$ .

## FSP - constant & range declaration



index expressions to model calculation:

```
in.1.1
              in.1.0
              in.0.1
in.0.0
out.0
              out.1
                            out.2
```

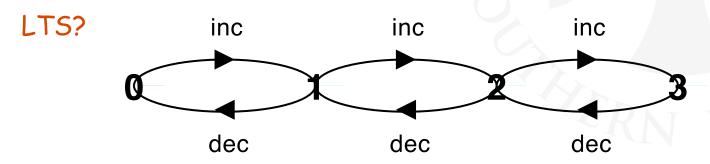
```
\frac{\text{const } N = 1}{\text{range } T = 0..N}
\frac{\text{range } R = 0..2*N
```

```
SUM = (in[a:T][b:T]->TOTAL[a+b]),
TOTAL[s:R] = (out[s]->SUM).
```

## FSP - guarded actions



The choice (when  $B \times -> P \mid y -> Q$ ) means that when the guard B is true then the actions x and y are both eligible to be chosen, otherwise if B is false then the action x cannot be chosen.



Could we have made this process w/o using the guards?

## FSP - guarded actions



A countdown timer which beeps after N ticks, or can be stopped.

```
(N=3) = (start->COUNTDOWN[N]),
COUNTDOWN
COUNTDOWN[i:0..N] =
            (when (i>0) tick->COUNTDOWN[i-1]
            | when (i==0) beep->STOP
            |stop->STOP
                                       stop
                                            stop
                                                stop
                                                     stop
                 start
                          tick
                                   tick
                                            tick
                                                     beep
```

## **FSP - guarded actions**



What is the following FSP process equivalent to?

Answer:

STOP

## **FSP - process alphabets**



The **alphabet** of a process is the set of actions in which it can engage.

Alphabet extension can be used to extend the implicit alphabet of a process:

```
WRITER = (write[1]->write[3]->WRITER)
+{write[0..3]}.
```

Alphabet of WRITER is the set {write[0..3]}

(we make use of alphabet extensions in later chapters)

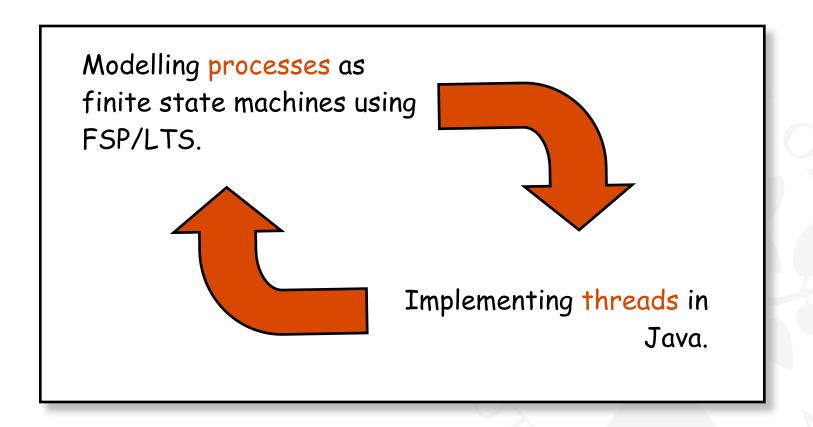


## **Practice**

**Threads in Java** 

## 2.2 Implementing processes



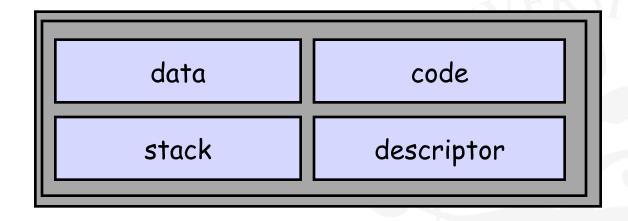


Note: to avoid confusion, we use the term process when referring to the models, and thread when referring to the implementation in Java.

#### **One Process**



Process:



Data: The heap (global, heap allocated data)

Code: The program (bytecode)

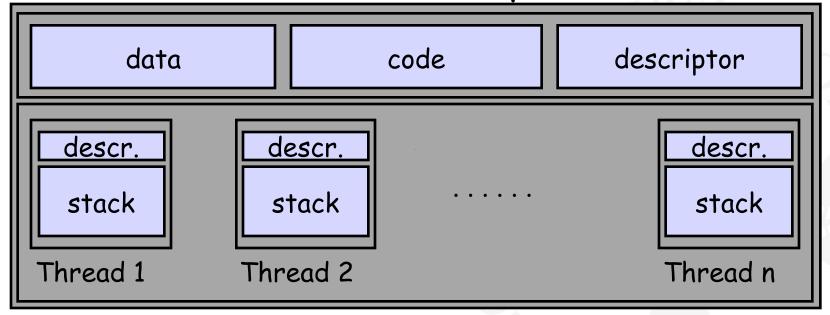
Stack: The stack (local data, call stack)

Descriptor: Program counter, stack pointer, ...

## Implementing processes - the OS view



## A multi-threaded process

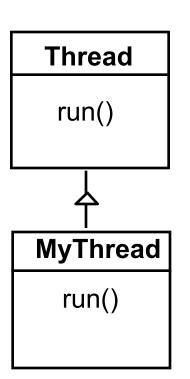


A (heavyweight) process in an operating system is represented by its code, data and the state of the machine registers, given in a descriptor. In order to support multiple (lightweight) threads of control, it has multiple stacks, one for each thread.

#### Threads in Java



A Thread class manages a single sequential thread of control. Threads may be created and deleted dynamically.



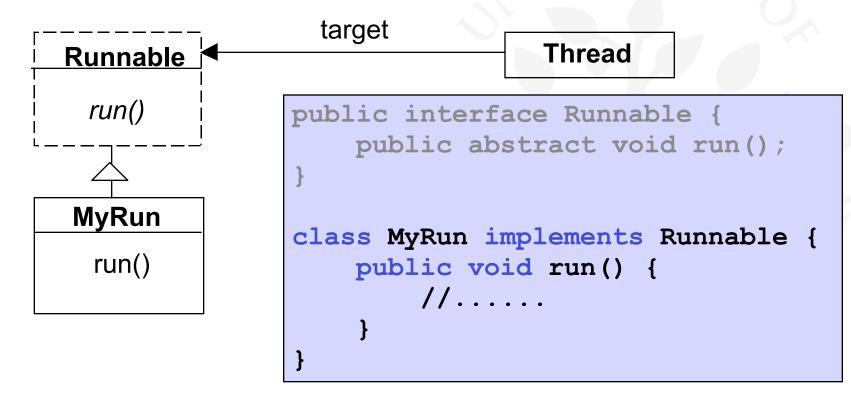
The Thread class executes instructions from its method run(). The actual code executed depends on the implementation provided for run() in a derived class.

```
Thread x = new MyThread();
```

## Threads in Java (cont'd)



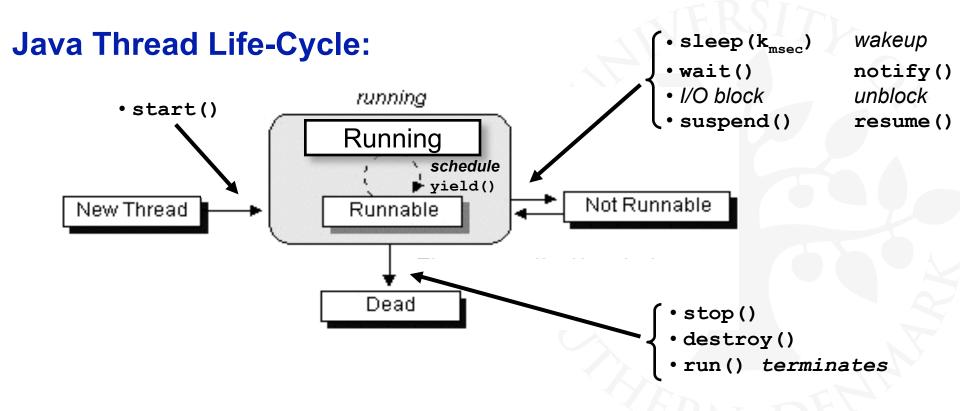
Since Java does not permit multiple inheritance, we often implement the **run()** method in a class not derived from Thread but from the interface Runnable.



```
Thread x = new Thread(new MyRun());
```

## **Thread Life-Cycle**







## **Example: Countdown timer**

**Model <-> Implementation** 

## CountDown timer example



```
const N = 3
COUNTDOWN = (start->COUNTDOWN[N]),
COUNTDOWN[i:0..N] =
            (when (i>0) tick->COUNTDOWN[i-1]
            |when(i==0) beep->STOP
            |stop->STOP
                                        stop
                                             stop
                                                 stop
                                                      stop
                  start
                           tick
                                    tick
                                             tick
                                                      beep
```

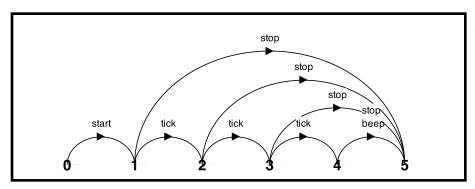
#### Implementation in Java?

#### CountDown class



```
public class CountDown implements Runnable {
    Thread counter;
    int i;
    final static int N = 3;

    public void run() { ... }
    public void start() { ... }
    public void stop() { ... }
    protected void tick() { ... }
    protected void beep() { ... }
}
```



## CountDown class - start(), stop() and run()



```
public void start() {
  counter = new Thread(this);
  i = N; counter.start();
public void stop() {
  counter = null;
public void run() {
  while(true) {
    if (i>0) { tick(); --i; }
    if (i==0) { beep(); return;}
    if (counter == null) return;
```

#### COUNTDOWN Model

```
start -> CountDown[N]
 stop -> STOP
COUNTDOWN[i] process
recursion as a while loop
when(i>0) tick -> CD[i-1]
when (i==0) beep -> STOP
stop->STOP
STOP ~ run() terminates
```

# CountDown class – the output actions: tick() articles beep()

```
protected void tick() {
    <<emit tick sound>>
    try {
        Thread.sleep(1000);
    } catch(InterruptedException iex){
        // ignore (in this toy-example)
protected void beep() {
    <<emit beep sound>>
```

## **Summary**



#### **Concepts**

process - unit of concurrency, execution of a program

#### **Models**

- LTS (Labelled Transition System) to model processes as state machines - sequences of atomic actions
- FSP (Finite State Process) to specify processes using prefix
   "->", choice " | " and recursion

#### **Practice**

- Java threads to implement processes
- Thread lifecycle (created, running, runnable, non-runnable, terminated)

#### **Near Future**



#### **Lecture Friday:**

- M&K: Chapter 3

#### **Discussion Sections & Study Groups**

Details are in Weekly Note 1