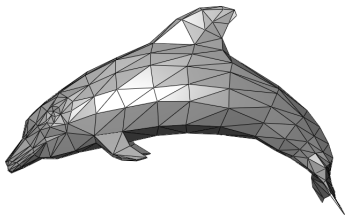


Matematikken bag 3D computergrafik

Rolf Fagerberg
Institut for Matematik og Datalogi, SDU



3D grafik

3D computergrafik bruges bla. til:

- ▶ Computerspil
- ▶ Animerede film
- ▶ Speciel effects i almindelige film
- ▶ Træningssimulatorer (pilot, kaptajn, soldat, ...)
- ▶ Visualisering (data, arkitektur, ...)

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- ▶ Visualisering (data, arkitektur, . . .)

Det er de samme principper for 3D grafik som bruges i alle disse sammenhænge. Disse er dagens emne.

Virtuelle objekter

Vi vil gerne definere objekter i det 3-dimensionelle rum ($\vec{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3$).

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Tre punkter i rummet definerer altid en plan i rummet, samt indhegner et trekantet udsnit af denne.

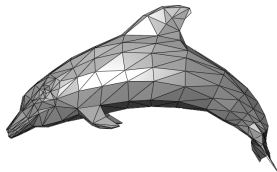
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Så **trekanter** vil være den basale byggesten, som sættes sammen til overflader af de ønskede virtuelle objekter.



Virtuelle objekter

Model = samling af punkter i rummet samt info om hvordan de hænger sammen tre og tre (modellens trekante).

$$\vec{x}_1 = (0.0, 2.0, 3.0)$$

$$\vec{x}_2 = (5.0, 1.0, 4.0)$$

$$\vec{x}_3 = (1.0, 1.0, 1.0)$$

$$\vec{x}_4 = (6.0, 2.0, 7.0)$$

⋮

$$T_1 = (\vec{x}_1, \vec{x}_2, \vec{x}_3)$$

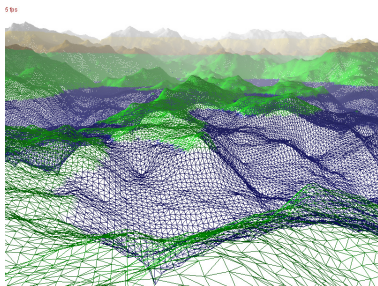
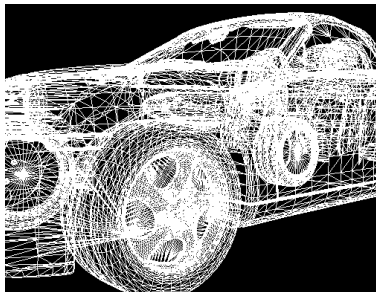
$$T_1 = (\vec{x}_1, \vec{x}_2, \vec{x}_4)$$

$$T_1 = (\vec{x}_5, \vec{x}_2, \vec{x}_4)$$

⋮

Virtuelle objekter

Flere eksempler:

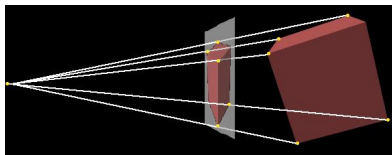
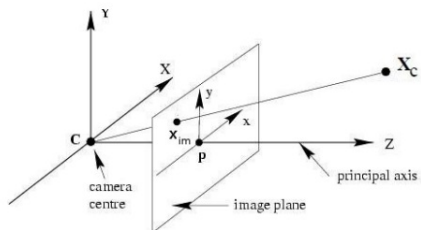


Billeder af virtuelle objekter i 3D

Generering af et billede (“fotografering”) af en scene bestående af virtuelle objekter.

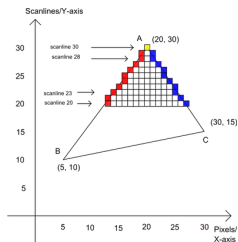
1. Definer modeller som samlinger af trekanter.
2. Flyt modellerne rundt i rummet (*transformation*), dvs. opstil scenen.
3. Flyt alle trekanter i scenen til skærmen (*projektion*) på en måde som simulerer fotografering.
4. Tilføj farver til de pixels på skærmen som dækkes af de projicerede trekanter (*shading*).

Perspektivisk projektion



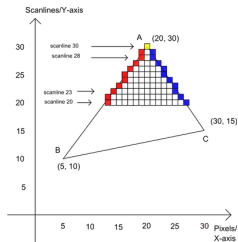
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Shading = tilføj farver til de pixels på skærmen som dækkes af de projicerede trekanter.



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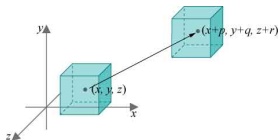


(From Sly Cooper)

Flytte objekter

We har brug for at *flytte/transformere* vores objekter i rummet.

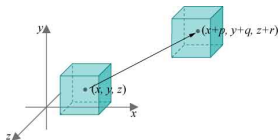
- ▶ En model (kasse, bil, bygning, person, . . .) er defineret i én position (ofte rundt om centrum i koordinatsystemet), men skal bruges i en anden position i scenen.



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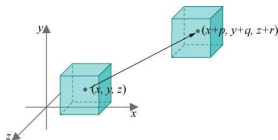


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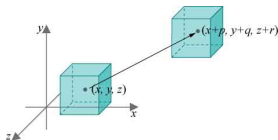


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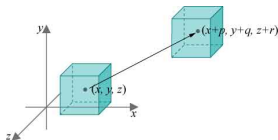


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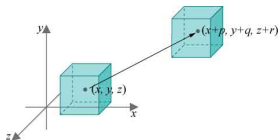
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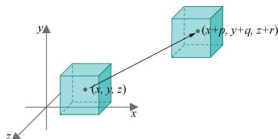
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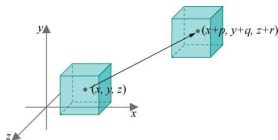
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$$f(x, y, z) = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} \quad \text{f.eks. } f(x, y, z) = \begin{pmatrix} 2xz \\ x + y \\ z + 1 \end{pmatrix}$$

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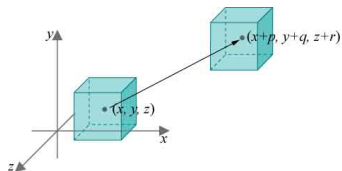
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Opgave: find funktionerne vi skal bruge

Translation

Translation

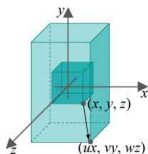


$$f(x, y, z) = \begin{pmatrix} x + 5 \\ y + 3 \\ z + 2 \end{pmatrix}$$

Her er (p, q, r) en fast translationsvektor, punktet (x, y, z) er input til f .

Skalering

Skalering



$$f(x, y, z) = \begin{pmatrix} 2 \cdot x \\ 4 \cdot y \\ 3 \cdot z \end{pmatrix}$$

Her er u , v og w faste skaleringsfaktorer, punktet (x, y, z) er input til f . Ofte er $u = v = w$, dvs. uniform skalering.

Rotation

Modeller skal også kunne drejes:

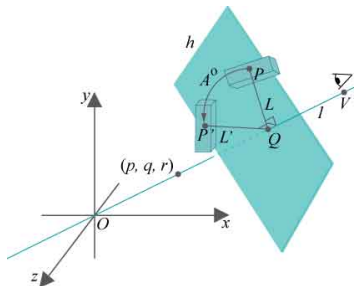


Rotation

Modeller skal også kunne drejes:



Euler [1775]: for enhver orientering af en model findes der en linie l gennem $(0,0,0)$ og en vinkel ϕ , således at denne orientering opnås ved at rotere ϕ grader om l .

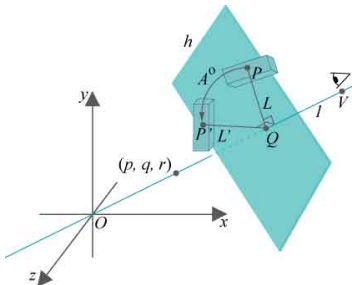


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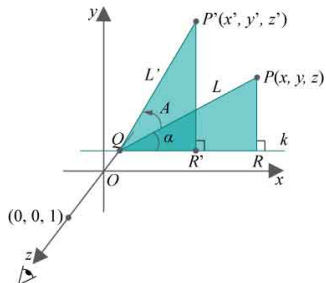
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$$f(x, y, z) = \begin{pmatrix} ? \\ ? \\ ? \end{pmatrix}$$

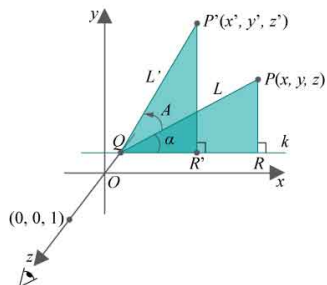
Rotation

Simple tilfælde: Rotation om z-aksen.



Rotation

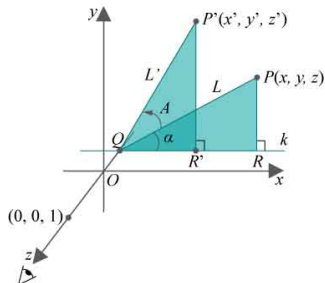
Simplere tilfælde: Rotation om z-aksen.



$$f(x, y, z) = \begin{pmatrix} & & \\ & & \\ & & z \end{pmatrix}$$

Rotation

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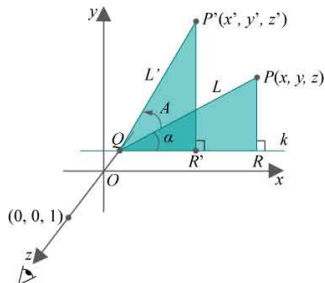


Brug formel for rotation i 2D:

$$f(x, y, z) = \begin{pmatrix} \\ \\ z \end{pmatrix}$$

Rotation

Simple tilfælde: Rotation om z-aksen.



Brug formel for rotation i 2D:

$$f(x, y, z) = \begin{pmatrix} x \cdot \cos \phi - y \cdot \sin \phi \\ x \cdot \sin \phi + y \cdot \cos \phi \\ z \end{pmatrix}$$

Rotation

Tilsvarende: Rotation om x -aksen og y -aksen.

$$f(x, y, z) = \begin{pmatrix} x \\ y \cdot \cos \phi - z \cdot \sin \phi \\ y \cdot \sin \phi + z \cdot \cos \phi \end{pmatrix}$$

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Rotation

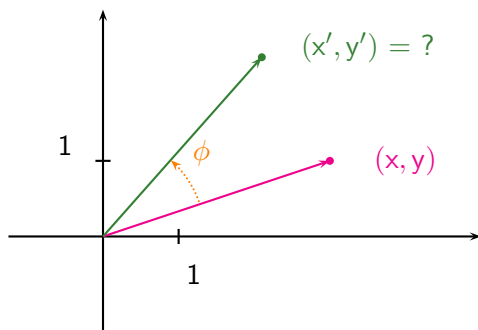
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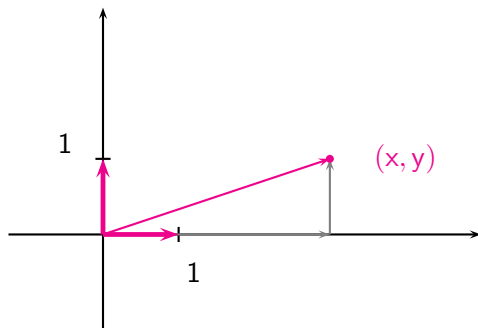
$$f(x, y, z) = \begin{pmatrix} z \cdot \sin \phi + x \cdot \cos \phi \\ y \\ z \cdot \cos \phi - x \cdot \sin \phi \end{pmatrix}$$

Euler: enhver orientering af en model kan opnås ved en rotation om hver koordinatakse (i alt tre rotationer efter hinanden).

Bevis for formel for rotation i 2D

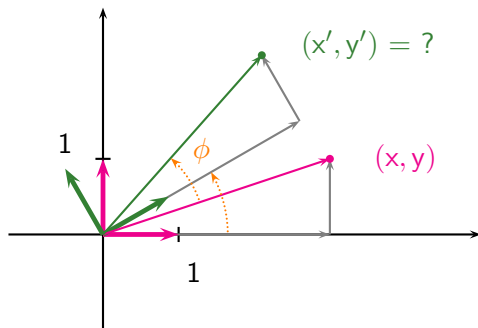


Basis for formel for rotation i 2D



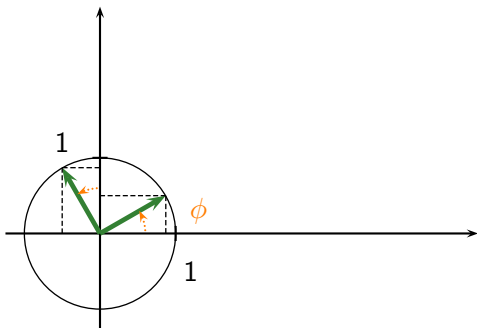
$$\begin{aligned}(x, y) &= x \cdot (1, 0) + y \cdot (0, 1) \\ &= x \cdot \vec{v}_1 + y \cdot \vec{v}_2\end{aligned}$$

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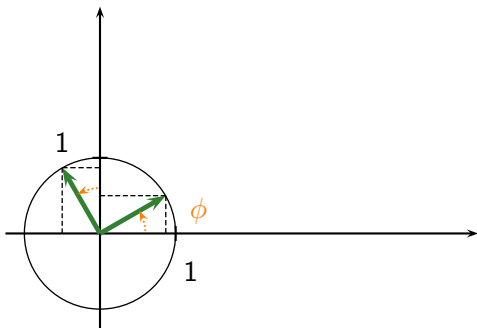


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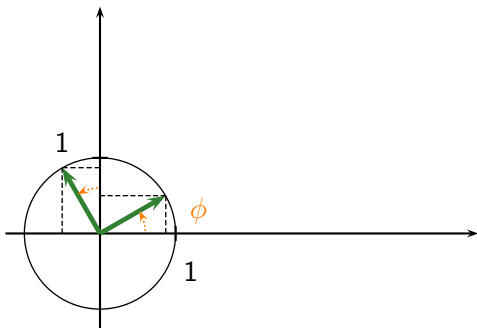


Bevis for formel for rotation i 2D



$$\vec{v}_1 = (\cos(\phi), \sin(\phi))$$

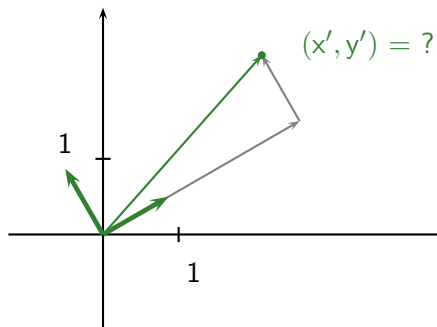
Bevis for formel for rotation i 2D



$$\vec{v}_1 = (\cos(\phi), \sin(\phi))$$

$$\vec{v}_2 = (-\sin(\phi), \cos(\phi))$$

Bevis for formel for rotation i 2D



$$\begin{aligned}(x', y') &= x \cdot \vec{v}'_1 + y \cdot \vec{v}'_2 \\ &= x \cdot (\cos(\phi), \sin(\phi)) + y \cdot (-\sin(\phi), \cos(\phi)) \\ &= (x \cdot \cos(\phi) - y \cdot \sin(\phi), x \cdot \sin(\phi) + y \cdot \cos(\phi))\end{aligned}$$

Mellemspil I

$$2 + 3 + 4 =$$

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$2 + (3 + 4)$ eller $(2 + 3) + 4$?

Mellemspil I

$$2 + 3 + 4 = 9$$

$$2 + (3 + 4) \text{ eller } (2 + 3) + 4?$$

Ligegyldigt, plus er **associativ**:

$$a + (b + c) = (a + b) + c$$

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Mellemspil I

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Ikke ligegyldigt, minus er **ikke** associativ:

$$2 - (3 - 4) = 3$$

$$(2 - 3) - 4 = -5$$

Mellemspil II

Plus, gange, minus... :

tal og tal \rightarrow nyt tal.

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F.eks. vektorer har et plus:

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(vektor + vektor = ny vektor)

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(vektor + vektor = ny vektor)

Har vektorer et gange?

Matricer

Matrix = firkant af tal:

$$\begin{bmatrix} 1 & 3 & 4 & 1 \\ 2 & 5 & 6 & 7 \\ 9 & 1 & 1 & 0 \end{bmatrix}$$

Ovenstående er en 3×4 matrix.

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Andre eksempler:

$$\begin{bmatrix} 1 & 3 \\ 2 & 5 \\ 9 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 5 \\ 8 \end{bmatrix}$$

$$[7 \quad 2 \quad 6 \quad 5]$$

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Andre eksempler:

$$\begin{bmatrix} 1 & 3 \\ 2 & 5 \\ 9 & 1 \end{bmatrix} \quad \begin{bmatrix} 4 \\ 5 \\ 8 \end{bmatrix} \quad [7 \ 2 \ 6 \ 5]$$

Kan vi lave et plus og et gange for matricer?

Matricer

Plus for matricer:

$$\begin{bmatrix} 1 & 6 & 4 \\ 2 & 5 & 7 \\ 9 & 1 & 1 \end{bmatrix} + \begin{bmatrix} 3 & 2 & 1 \\ 4 & 3 & 2 \\ 5 & 4 & 3 \end{bmatrix} = \begin{bmatrix} 1+3 & 6+2 & 4+1 \\ 2+4 & 5+3 & 7+2 \\ 9+5 & 1+4 & 1+3 \end{bmatrix} = \begin{bmatrix} 4 & 8 & 5 \\ 6 & 8 & 9 \\ 14 & 5 & 4 \end{bmatrix}$$

(Matrice + matrice = ny matrice)

Matricer

Gange for matricer:

$$\begin{bmatrix} 1 & 6 & 4 \\ 2 & 5 & 7 \\ 9 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 & 2 & 1 \\ 4 & 3 & 2 \\ 5 & 4 & 3 \end{bmatrix} = \begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix}$$

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$$33 = 2 \cdot 1 + 5 \cdot 2 + 7 \cdot 3$$

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Man kan vise at gange for matricer er **associativt**: $A \cdot (B \cdot C) = (A \cdot B) \cdot C$.

Tilbage til at flytte objekter

Flytte model \Leftrightarrow flytte trekanter \Leftrightarrow flytte hjørnepunkter

Vi skal bruge funktioner $f(x, y, z) = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix}$

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Spørgsmål: kan vores ønskede transformationer (translation, skalering, rotation (projektion)) udtrykkes ved matricer?

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Det vil sige at vi skal beregne

$$E \cdot (D \cdot (C \cdot (B \cdot (A \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}))))$$

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Dette kan spare beregninger: 3D model = mange trekanter = mange punkter. Alle punkter i model skal gennem de samme transformationer. Men $F = (((E \cdot D) \cdot C) \cdot B) \cdot A$ skal kun beregnes én gang.

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- ▶ Rotation vinkel ϕ om z-aksen:

$$f(x, y, z) = \begin{pmatrix} x \cos \phi - y \sin \phi \\ x \sin \phi + y \cos \phi \\ z \end{pmatrix}$$

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- ▶ Translation?

$$f(x, y, z) = \begin{pmatrix} x + p \\ y + q \\ z + r \end{pmatrix} = \begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

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Umuligt. For translation gælder $f(0, 0, 0) = (p, q, r) \neq (0, 0, 0)$, men alle funktioner induceret af matricer har $f(0, 0, 0) = (0, 0, 0)$.

Homogene koordinater

Gå til 4D:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \rightarrow \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

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Og tilbage:

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \rightarrow \begin{pmatrix} x/w \\ y/w \\ z/w \end{pmatrix}$$

Homogene koordinater

Translationer (i 3D) kan nu blive udtrykt ved matricer:

$$\begin{bmatrix} 1 & 0 & 0 & p \\ 0 & 1 & 0 & q \\ 0 & 0 & 1 & r \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x + p \\ y + q \\ z + r \\ 1 \end{pmatrix}$$

Homogene koordinater

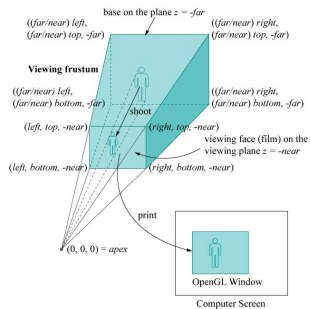
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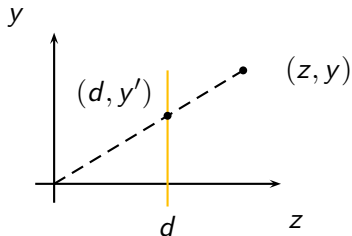
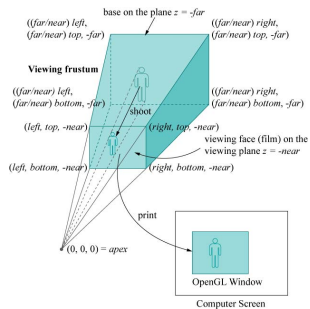
Alle 3x3 matricer er stadig til rådighed (inkl. skalering og rotation):

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} 1x + 2y + 3z \\ 4x + 5y + 6z \\ 7x + 8y + 9z \\ 1 \end{pmatrix}$$

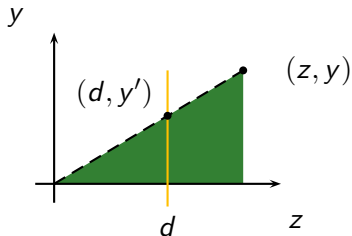
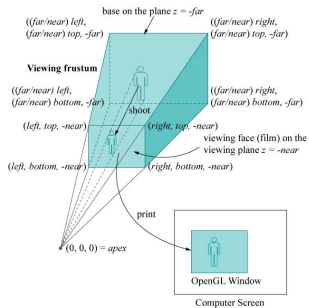
Projektion



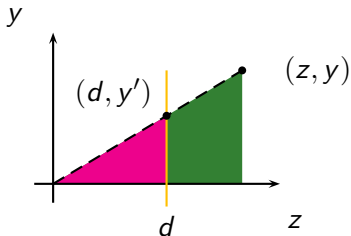
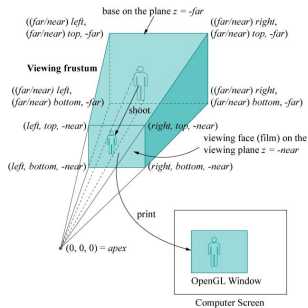
Projektion



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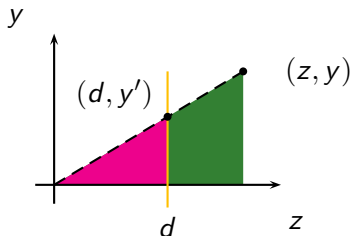
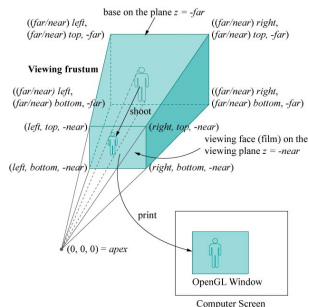
Projektion



Ligedannede trekanter \Rightarrow

$$\frac{y'}{y} = \frac{d}{z} \Leftrightarrow y' = \frac{yd}{z}$$

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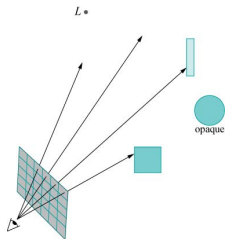
Denne beregning kan udtrykkes ved en 4x4 matrix samt 4D \rightarrow 3D reglen:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{bmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \\ z/d \end{pmatrix} \rightarrow \begin{pmatrix} xd/z \\ yd/z \\ d \end{pmatrix}$$

Shading

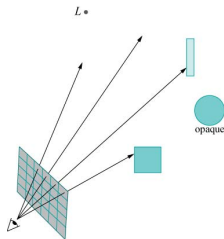
Shading

Shading = find color values at pixels of screen (when rendering a virtual 3D scene).



Shading

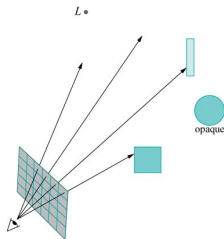
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Core objective: Find color values for intersection of a ray with a triangle.

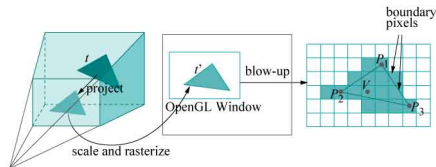
Shading

Core objective: Find color values for point at intersection of a ray with a triangle.

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- ▶ Rendering is triangle-driven (foreach triangle: render).
- ▶ Triangles are simply (triples of) vertices until rasterization phase, where pixels of the triangle are found from pixels of the vertices.



So the actual rays are determined in the rasterization phase.

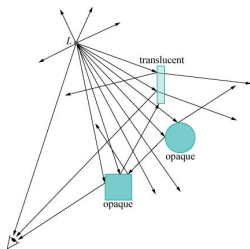
Modeling Light

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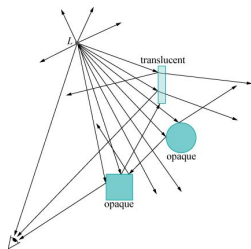
Model physical light (photons)



Modeling Light

Core objective: Find color values for intersection of a ray with a triangle.

Model physical light (photons)



Photons are

- ▶ Emitted from light sources.
- ▶ Reflected, absorbed, re-emitted, transmitted when hitting objects.

Modeling Light

Highly complex physical proces. Zillions of photons.

Can only be modeled to a certain degree mathematically (ongoing research expands on the available models).

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(Figure by Jason Jacobs)

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Realtime rendering additionally has severe time constraints. Framerate $\sim 30/\text{sec}$, screen size $\sim 10^6$ pixels \Rightarrow few GPU cycles available for calculation per ray.

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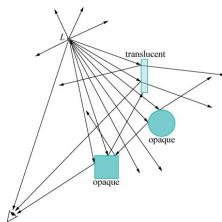
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Offline rendering (movies, visualization) can use more advanced light models (and also other rendering methods needing more time, such as ray tracing and radiosity).

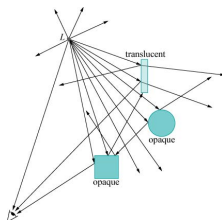
Phong's Lightning Model

A classic, simple model.



Phongs Lightning Model

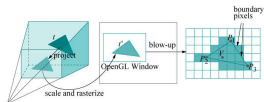
A classic, simple model.



- ▶ Models only opaque objects.
- ▶ Models only **one** level of light/surface interactions.
- ▶ Light/surface interaction is modeled by two simple submodels, **diffuse** and **specular** term.
- ▶ Models indirect light effects **very** crudely (**ambient** term).
- ▶ Light actually generated at surface can be added (emissive term).
- ▶ Occlusion is not modeled (all objects see all lights).

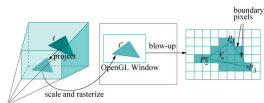
Shading models

So we have information in each vertex. How spread color calculation over entire triangle pixels?



Shading models

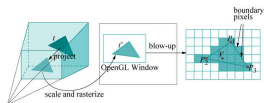
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Shading models

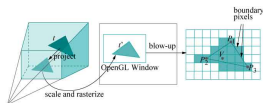
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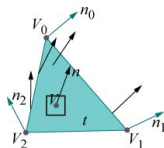
- ▶ **Flat shading:** Color calculated for one point is used for entire triangle.
- ▶ **Smooth shading** (aka. Gouraud shading): Colors calculated for three vertices are interpolated across the entire triangle (individually for each RGB-channel).

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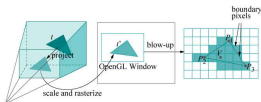


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- ▶ **Phong shading:** Color calculation done for all points of pixels.

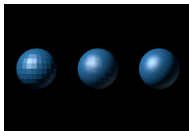
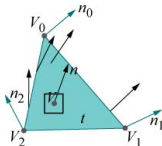


Shading models

So we have information in each vertex. How spread color calculation over entire triangle pixels?

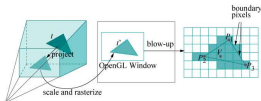


- ▶ **Flat shading:** Color calculated for one point is used for entire triangle.
- ▶ **Smooth shading** (aka. Gouraud shading): Colors calculated for three vertices are interpolated across the entire triangle (individually for each RGB-channel).
- ▶ **Phong shading:** Color calculation done for all points of pixels.

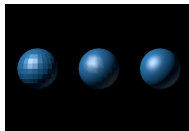
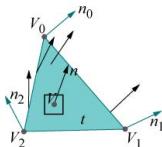


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Calculation time increases down the list.

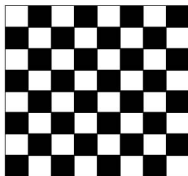
Textures

Texture = 1/2/3D data table.

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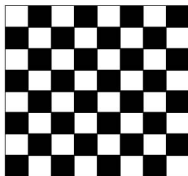
Often: (color values of) 2D picture.



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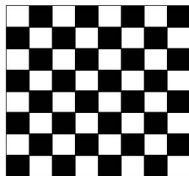


External file, or generated online inside program (animated textures), or rendered (offline or online) scene.

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Often: (color values of) 2D picture.



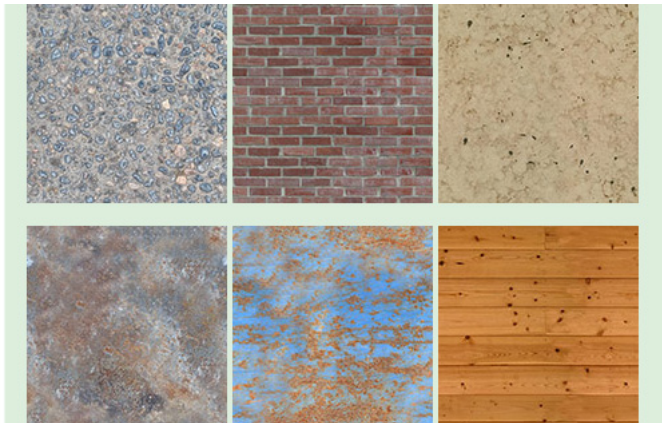
External file, or generated online inside program (animated textures), or rendered (offline or online) scene.

But texture data can be interpreted as anything, e.g. normal vectors, light maps/shadow maps, heightfields,

Use of Textures

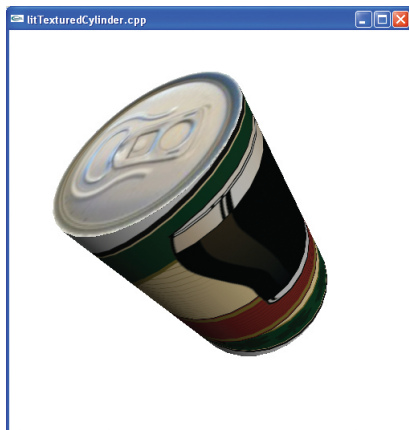
- ▶ Generate detailed graphical content hardly possible with triangles (such as clouds, skyboxes, plain pictures (posters, decals) on surfaces).
- ▶ Create illusion of structure, saving lots of triangles. Can be (low level) part of a level-of-detail scheme.
- ▶ Most of a game's graphical expression is via artwork using textures.
- ▶ Hold special-purpose data for use in rendering process.

Examples



(From All Things Designed)

Examples



Examples

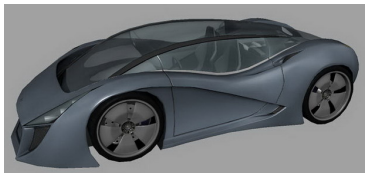
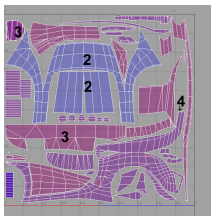
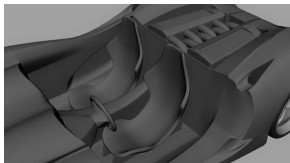
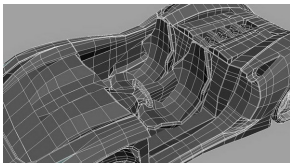


Examples



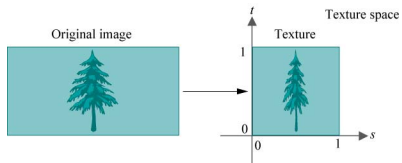
(From Sly Cooper)

Examples



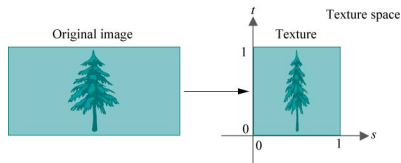
(Figures by Valentin Nadolu)

Texture Coordinates



Texture data get mapped to $[0; 1]^{1,2,3}$ in **texture space**.

Texture Coordinates

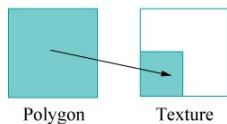


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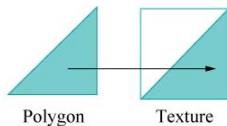
Vertices can be associated with texture coordinates

Texture Coordinates

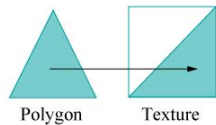
Texture space points can be arbitrary:



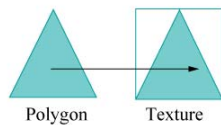
(a)



(b)



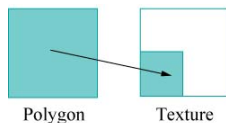
(c)



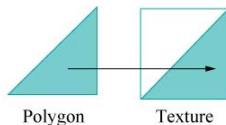
(d)

Texture Coordinates

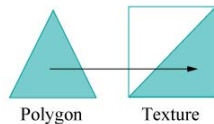
Texture space points can be arbitrary:



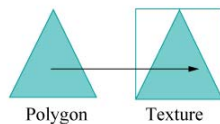
(a)



(b)



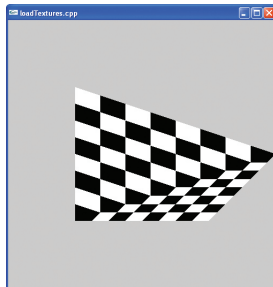
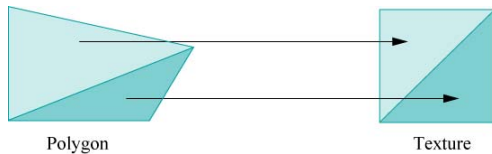
(c)



(d)

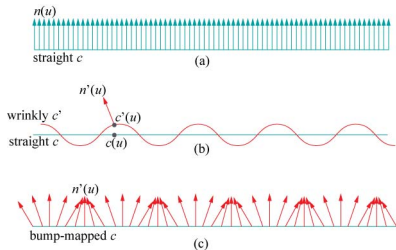
Points internally in triangle are associated with points in texture space using [interpolation](#).

Interpolation Example



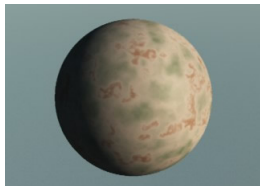
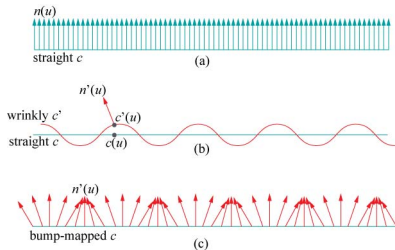
Texture Use: Bumpmapping

Store surface normals (or perturbation of normals) in texture.



Texture Use: Bumpmapping

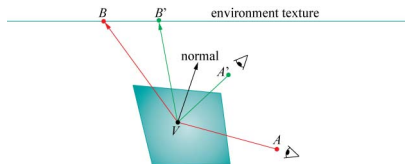
Store surface normals (or perturbation of normals) in texture.



(Figure by www.chromosphere.com)

Texture Use: Environment Mapping

Reflections can see environment. Make part of shading calculation.



Environment Mapping

Easiest with Cube mapping:



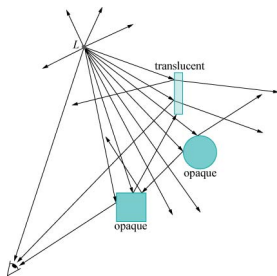
Six single textures. Can each be generated [online](#) by rendering from current center and saving framebuffer as texture.

Alternative Rendering Methods

- ▶ **Standard GPU pipeline** (OpenGL): real-time, but shading based on *local* effects. No shadows in basic pipeline (must be added by ad-hoc methods).
- ▶ **Ray tracing**: *Global* shading model particularly good at specular effects (shiny surfaces). Too computationally expensive to be real-time.
- ▶ **Radiosity**: *Global* shading model particularly good at diffuse effects (matte surfaces, indirect light). Too computationally expensive to be real-time. But well suited for storing results as textures (as diffuse light is not viewpoint dependent).

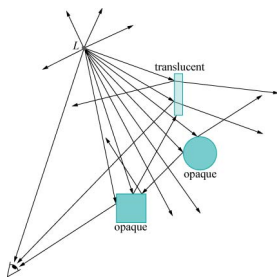
Ray Tracing

Follow photon paths to the eye.



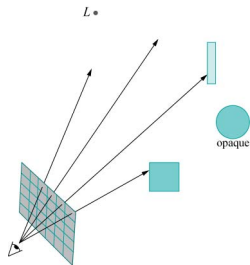
Ray Tracing

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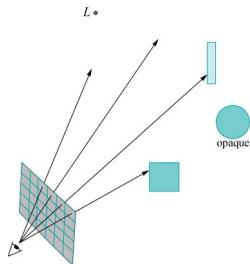
For efficiency, follow these in a **backwards** fashion, from the eye (only spend time on photons actually hitting the eye).

Ray Tracing Level 0



At end of rays: calculate colors by Phongs lighting model.

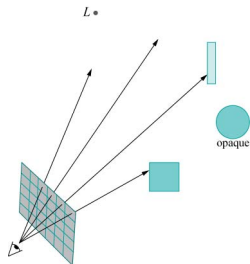
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Same result as standard GPU pipeline.

Ray Tracing Level 0



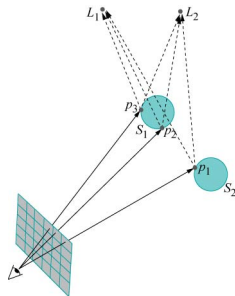
At end of rays: calculate colors by Phongs lighting model.

Same result as standard GPU pipeline.

Requires mechanism for fast determination of intersection points between rays and objects of the scene (e.g., store objects in data structures).

Ray Tracing Level 1

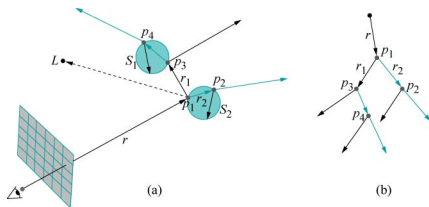
Add occlusion tests to light sources.



Gives shadows.

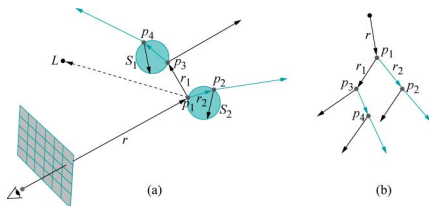
Ray Tracing Level 2+

Add reflection and transmission. Then *recurse*.



Ray Tracing Level 2+

Add reflection and transmission. Then *recurse*.



Note: simulating indirect light transfer between diffuse surfaces requires following **many** (approximating infinitely many) reflective rays from each ray intersection point in the recursive process.

Prohibitively costly. So ray tracing works best for glossy materials.

Ray Tracing Examples



(Figures by Bill Martin, RayScale, Daniel Pohl, NVIDIA)

Radiosity

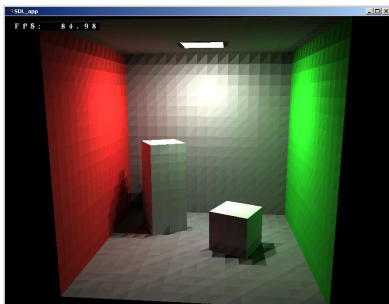
Model indirect light bouncing between purely diffuse (Lambertian) surfaces (of which some are light emitting).



(Figure by Jason Jacobs)

Patches

Start by patch-ifying the surfaces of the scene.



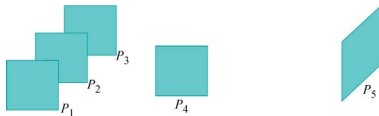
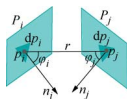
(Figure by Chuck Pheatt)

Entire patch will be considered to have same light value (radiosity/brightness) B_i .

Radiosity: photons emitted per time and per area.

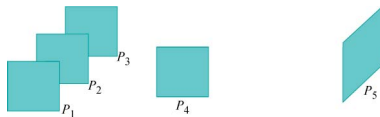
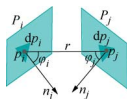
Form Factors

Form factor F_{ij} : measure of light transport between patch i and j .



Form Factors

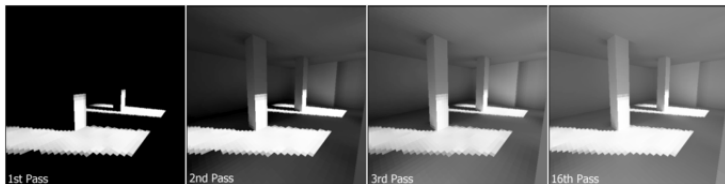
Form factor F_{ij} : measure of light transport between patch i and j .



(Technically: For F_{ij} : sum (integrate) contribution between (infinitesimal small areas around) all points on the two patches P_i and P_j .)

Iterative Process

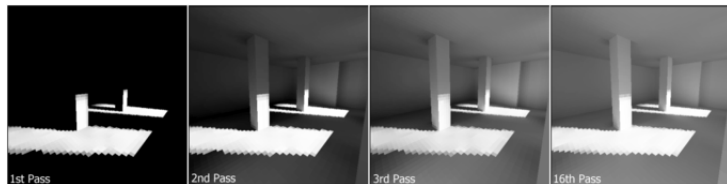
Here is the result of rendering a specific scene with B_1 , B_2 , B_3 , B_{16} .



(Figure by Hugo Elias)

Iterative Process

Here is the result of rendering a specific scene with B_1 , B_2 , B_3 , B_{16} .



(Figure by Hugo Elias)

The patching of the room may be refined based on one run of radiosity, increasing the resolution in areas with large variation in light values (edges of shadows, e.g.), and lowering the resolution in areas with small variation.