

DM545

Linear and Integer Programming

Lecture 6

Sensitivity Analysis and Farkas Lemma

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Outline

1. Geometric Interpretation

2. Sensitivity Analysis

3. Farkas Lemma

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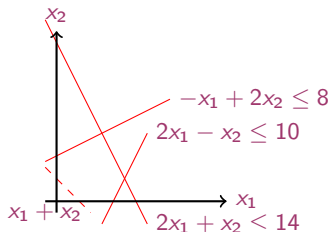
1. Geometric Interpretation

2. Sensitivity Analysis

3. Farkas Lemma

Geometric Interpretation

$$\begin{aligned} \max \quad & x_1 + x_2 \\ & 2x_1 + x_2 \leq 14 \\ & -x_1 + 2x_2 \leq 8 \\ & 2x_1 - x_2 \leq 10 \\ & x_1, x_2 \geq 0 \end{aligned}$$



Opt $x^* = (4, 6)$, $z^* = 10$. To prove this we need to prove that $y^* = (3/5, 1/5, 0)$ is a feasible solution of D :

$$\begin{aligned} \min \quad & 14y_1 + 8y_2 + 10y_3 = w \\ & 2y_1 - y_2 + 2y_3 \geq 1 \\ & y_1 + 2y_2 - y_3 \geq 1 \\ & y_1, y_2, y_3 \geq 0 \end{aligned}$$

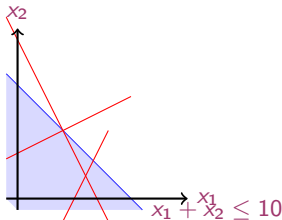
and that $w^* = 10$

$$\begin{array}{r} 3 \\ 5 \\ \hline 5 \end{array} \cdot 2x_1 + x_2 \leq 14$$

$$\begin{array}{r} 1 \\ 5 \\ \hline 5 \end{array} \cdot -x_1 + 2x_2 \leq 8$$

$$x_1 + x_2 \leq 10$$

the feasibility region of P is a subset of
the half plane $x_1 + x_2 \leq 10$



$(2v - w)x_1 + (v + 2w)x_2 \leq 14v + 8w$ set of half planes that contain the
feasibility region of P and pass through [4, 6]

$$2v - w \geq 1$$

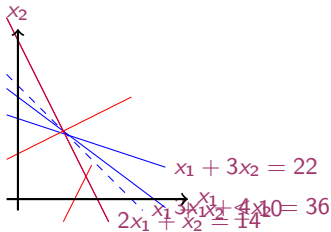
$$v + 2w \geq 1$$

Example of boundary lines among
those allowed:

$$v = 1, w = 0 \implies 2x_1 + x_2 = 14$$

$$v = 1, w = 1 \implies x_1 + 3x_2 = 22$$

$$v = 2, w = 1 \implies 3x_1 + 4x_2 = 36$$



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Sensitivity Analysis

aka Postoptimality Analysis

Instead of solving each modified problems from scratch, exploit results obtained from solving the original problem.

$$\max\{c^T x \mid Ax = b, l \leq x \leq u\} \quad (*)$$

(I) changes to coefficients of objective function:

$$\max\{\tilde{c}^T x \mid Ax = b, l \leq x \leq u\} \quad (\text{primal})$$

x^* of (*) remains feasible hence we can restart the simplex from x^*

(II) changes to RHS terms: $\max\{c^T x \mid Ax = \tilde{b}, l \leq x \leq u\}$ (dual)

x^* optimal feasible solution of (*)

basic sol \bar{x} of (II): $\bar{x}_N = x_N^*$, $A_B \bar{x}_B = \tilde{b} - A_N \bar{x}_N$

\bar{x} is dual feasible and we can start the dual simplex from there. If \tilde{b} differs from b only slightly it may be we are already optimal.

(III) introduce a new variable:

(primal)

$$\begin{aligned} \max \quad & \sum_{j=1}^6 c_j x_j \\ & \sum_{j=1}^6 a_{ij} x_j = b_i, \quad i = 1, \dots, 3 \\ & l_j \leq x_j \leq u_j, \quad j = 1, \dots, 6 \\ & [x_1^*, \dots, x_6^*] \text{ feasible} \end{aligned}$$

$$\begin{aligned} \max \quad & \sum_{j=1}^7 c_j x_j \\ & \sum_{j=1}^7 a_{ij} x_j = b_i, \quad i = 1, \dots, 3 \\ & l_j \leq x_j \leq u_j, \quad j = 1, \dots, 7 \\ & [x_1^*, \dots, x_6^*, 0] \text{ feasible} \end{aligned}$$

(IV) introduce a new constraint:

(dual)

$$\begin{aligned} & \sum_{j=1}^6 a_{4j} x_j = b_4 \\ & \sum_{j=1}^6 a_{5j} x_j = b_5 \\ & l_j \leq x_j \leq u_j \quad j = 7, 8 \end{aligned}$$

$$\begin{aligned} & [x_1^*, \dots, x_6^*] \text{ optimal} \\ & [x_1^*, \dots, x_6^*, x_7^*, x_8^*] \text{ feasible} \\ & x_7^* = b_4 - \sum_{j=1}^6 a_{4j} x_j^* \\ & x_8^* = b_5 - \sum_{j=1}^6 a_{5j} x_j^* \end{aligned}$$

Examples

(I) Variation of reduced costs:

$$\begin{aligned}
 \max \quad & 6x_1 + 8x_2 \\
 & 5x_1 + 10x_2 \leq 60 \\
 & 4x_1 + 4x_2 \leq 40 \\
 & x_1, x_2 \geq 0
 \end{aligned}$$

$$\begin{array}{c|cccccc}
 & x_1 & x_2 & x_3 & x_4 & -z & b \\
 \hline
 x_3 & 5 & 10 & 1 & 0 & 0 & 60 \\
 x_4 & 4 & 4 & 0 & 1 & 0 & 40 \\
 \hline
 & 6 & 8 & 0 & 0 & 1 & 0
 \end{array}$$

The last tableau gives the possibility to estimate the effect of variations

$$\begin{array}{c|cccccc}
 & x_1 & x_2 & x_3 & x_4 & -z & b \\
 \hline
 x_2 & 0 & 1 & 1/5 & -1/4 & 0 & 2 \\
 x_1 & 1 & 0 & -1/5 & 1/2 & 0 & 8 \\
 \hline
 & 0 & 0 & -2/5 & -1 & 1 & -64
 \end{array}$$

For a variable in basis the perturbation goes unchanged in the red. costs. Eg:

$$\max(6 + \delta)x_1 + 8x_2 \implies \bar{c}_1 = -\frac{2}{5} \cdot 5 - 1 \cdot 4 + 1(6 + \delta) = \delta$$

then need to bring in canonical form and hence δ changes the obj value. For a variable not in basis, if it changes the sign of the reduced cost \implies worth bringing in basis \implies the δ term propagates to other columns

(II) Changes in RHS terms

	x_1	x_2	x_3	x_4	$-z$	b
x_3	5	10	1	0	0	$60 + \delta$
x_4	4	4	0	1	0	$40 + \epsilon$
	6	8	0	0	1	0

	x_1	x_2	x_3	x_4	$-z$	b
x_2	0	1	$1/5$	$-1/4$	0	$2 + 1/5\delta - 1/4\epsilon$
x_1	1	0	$-1/5$	$1/2$	0	$8 - 1/5\delta + 1/2\epsilon$
	0	0	$-2/5$	-1	1	$-64 - 2/5\delta - \epsilon$

(It would be more convenient to augment the second. But let's take $\epsilon = 0$.)

If $60 + \delta \implies$ all RHS terms change and we must check feasibility

Which are the multipliers for the first row? $k_1 = \frac{1}{5}$, $k_2 = -\frac{1}{4}$, $k_3 = 0$

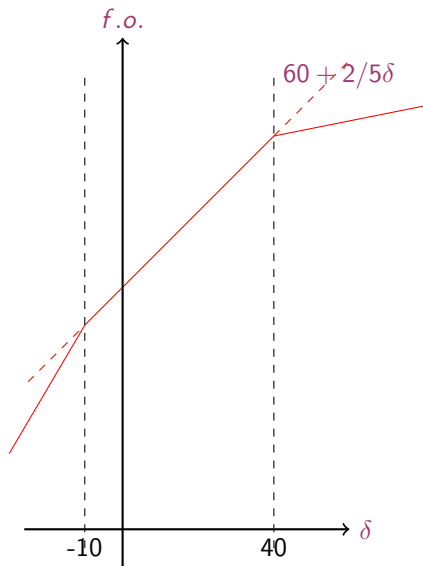
I: $1/5(60 + \delta) - 1/4 \cdot 40 + 0 \cdot 0 = 12 + \delta/5 - 10 = 2 + \delta/5$

II: $-1/5(60 + \delta) + 1/2 \cdot 40 + 0 \cdot 0 = -60/5 + 20 - \delta/5 = 8 - 1/5\delta$

Risk that RHS becomes negative

Eg: if $\delta = -20 \implies$ tableau stays optimal but not feasible \implies apply dual simplex

Graphical Representation



(III) Add a variable

$$\begin{aligned} \max \quad & 5x_0 + 6x_1 + 8x_2 \\ & 6x_0 + 5x_1 + 10x_2 \leq 60 \\ & 8x_0 + 4x_1 + 4x_2 \leq 40 \\ & x_0, x_1, x_2 \geq 0 \end{aligned}$$

Reduced cost of x_0 ? $c_j + \sum \pi_i a_{ij} = +1 \cdot 5 - \frac{2}{5} \cdot 6 + (-1)8 = -\frac{27}{5}$

To make worth entering in basis:

- ▶ increase its cost
- ▶ decrease the amount in constraint II: $-\frac{2}{5} \cdot 6 - a_{20} + 5 > 0$

(IV) Add a constraint

$$\begin{aligned}
 \max \quad & 6x_1 + 8x_2 \\
 & 5x_1 + 10x_2 \leq 60 \\
 & 4x_1 + 4x_2 \leq 40 \\
 & 5x_1 + 6x_2 \leq 50 \\
 & x_1, x_2 \geq 0
 \end{aligned}$$

Final tableau not in canonical form, need to iterate

	x_1	x_2	x_3	x_4	x_5	$-z$	b
x_2	0	1	$1/5$	$-1/4$		0	2
x_1	1	0	$-1/5$	$1/2$		0	8
	0	0	$5/5$	$6/4$	1	0	-2
	0	0	$-2/5$	-1	0	1	-64

(V) change in a technological coefficient:

$$\begin{array}{c|cccc|c}
 & x_1 & x_2 & x_3 & x_4 & -z & b \\
 \hline
 x_3 & 5 & 10 + \delta & 1 & 0 & 0 & 60 \\
 x_4 & 4 & 4 & 0 & 1 & 0 & 40 \\
 \hline
 & 6 & 8 & 0 & 0 & 1 & 0
 \end{array}$$

- ▶ first effect on its column
- ▶ then look at c
- ▶ finally look at b

$$\begin{array}{c|cccc|c}
 & x_1 & x_2 & x_3 & x_4 & -z & b \\
 \hline
 x_2 & 0 & (10 + \delta)1/5 + 4(-1/4) & 1/5 & -1/4 & 0 & 2 \\
 x_1 & 1 & (10 + \delta)(-1/5) + 4(1/2) & -1/5 & 1/2 & 0 & 8 \\
 \hline
 & 0 & -2/5\delta & -2/5 & -1 & 1 & -64
 \end{array}$$

The dominant application of LP is mixed integer linear programming. In this context it is extremely important being able to begin with a model instantiated in one form followed by a sequence of problem modifications (such as row and column additions and deletions and variable fixings) interspersed with resolves

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Strong Duality

Summary of Proof seen earlier in matrix notation:

Assuming that P and D have feasible solutions:

there exists an optimal basis B and an optimal solution \mathbf{x}_B

Dual solution corresponding to B , $\mathbf{y}_B = \mathbf{c}_B^T \mathbf{A}_B^{-1}$, aka multipliers for B

From the simplex:

$$\bar{\mathbf{c}} = \mathbf{c} + \pi \mathbf{A}$$

and at optimality $\mathbf{c}_B = \mathbf{0}$ for basic variables and $\mathbf{c}_{\bar{B}} \geq \mathbf{0}$ for non basic variables

Setting $\mathbf{y}_B = -\pi$ we obtain $\mathbf{y}_B \mathbf{A} \leq \mathbf{c}$ and hence \mathbf{y}_B is feasible for the dual.

What is the value of this dual solution?

$$\mathbf{y}_B^T \mathbf{b} = \mathbf{c}_B^T \mathbf{A}_B^{-1} \mathbf{b} = \mathbf{c}_B^T \mathbf{x}_B = \mathbf{c}^T \mathbf{x}$$

We now look at Farkas Lemma with two objectives:

- ▶ giving another proof of strong duality
- ▶ understanding a certificate of infeasibility

Farkas Lemma

Lemma (Farkas)

Let $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$. Then,

$$\begin{array}{ll} \text{either I.} & \exists x \in \mathbb{R}^n : Ax = b \text{ and } x \geq 0 \\ \text{or II.} & \exists y \in \mathbb{R}^m : y^T A \geq 0^T \text{ and } y^T b < 0 \end{array}$$

Easy to see that both I and II cannot occur together:

$$(0 \leq) \underbrace{(y^T A)}_{\geq 0} \underbrace{x}_{\geq 0} y^T Ax = y^T b \quad (< 0)$$

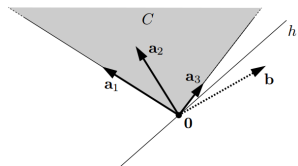
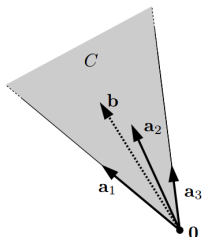
Geometric interpretation of Farkas L.

Linear combination of a_i with nonnegative terms generates a **convex cone**:

$$\{\lambda_1 a_1 + \dots + \lambda_n a_n, \lambda_1, \dots, \lambda_n \geq 0\}$$

polyhedral cone: $C = \{x \mid Ax \leq 0\}$, intersection of many $ax \leq 0$

Convex hull of rays $p_i = \{\lambda_i a_i, \lambda_i \geq 0\}$



Either point b lies in convex cone C
 or \exists hyperplane h passing through point 0 $h = \{x \in \mathbb{R}^m : y^T x = 0\}$
 for $y \in \mathbb{R}^m$ such that all vectors a_1, \dots, a_n (and thus C) lie on one side and b lies (strictly) on the other side (ie, $y^T a_i \geq 0, \forall i = 1 \dots n$ and $y^T b < 0$).

Variants of Farkas Lemma

Corollary

- (i) $\mathbf{Ax} = \mathbf{b}$ has sol $\mathbf{x} \geq \mathbf{0} \iff \forall \mathbf{y} \in \mathbb{R}^m$ with $\mathbf{y}^T \mathbf{A} \geq \mathbf{0}^T, \mathbf{y}^T \mathbf{b} \geq 0$
- (ii) $\mathbf{Ax} \leq \mathbf{b}$ has sol $\mathbf{x} \geq \mathbf{0} \iff \forall \mathbf{y} \geq \mathbf{0}$ with $\mathbf{y}^T \mathbf{A} \geq \mathbf{0}^T, \mathbf{y}^T \mathbf{b} \geq 0$
- (iii) $\mathbf{Ax} \leq \mathbf{0}$ has sol $\mathbf{x} \in \mathbb{R}^n \iff \forall \mathbf{y} \geq \mathbf{0}$ with $\mathbf{y}^T \mathbf{A} = \mathbf{0}^T, \mathbf{y}^T \mathbf{b} \geq 0$

i) \implies ii):

$$\bar{\mathbf{A}} = [\mathbf{A} \mid \mathbf{I}_m]$$

$$\mathbf{Ax} \leq \mathbf{b} \text{ has sol } \mathbf{x} \geq \mathbf{0} \iff \bar{\mathbf{A}}\mathbf{x} = \mathbf{b} \text{ has sol } \mathbf{x} \geq \mathbf{0}$$

By (i):

$$\forall \mathbf{y} \in \mathbb{R}^m$$

$$\mathbf{y}^T \mathbf{b} \geq 0, \mathbf{y}^T \bar{\mathbf{A}} \geq \mathbf{0}$$

$$\mathbf{y}^T \mathbf{A} \geq \mathbf{0}$$

$$\mathbf{y} \geq \mathbf{0}$$

relation with Fourier &
Moutzkin method

	The system $\mathbf{Ax} \leq \mathbf{b}$	The system $\mathbf{Ax} = \mathbf{b}$
has a solution $\mathbf{x} \geq \mathbf{0}$ iff	$\mathbf{y} \geq \mathbf{0}, \mathbf{y}^T \mathbf{A} \geq \mathbf{0}$ $\implies \mathbf{y}^T \mathbf{b} \geq 0$	$\mathbf{y}^T \mathbf{A} \geq \mathbf{0}^T$ $\implies \mathbf{y}^T \mathbf{b} \geq 0$
has a solution $\mathbf{x} \in \mathbb{R}^n$ iff	$\mathbf{y} \geq \mathbf{0}, \mathbf{y}^T \mathbf{A} = \mathbf{0}$ $\implies \mathbf{y}^T \mathbf{b} \geq 0$	$\mathbf{y}^T \mathbf{A} = \mathbf{0}^T$ $\implies \mathbf{y}^T \mathbf{b} = 0$

Strong Duality by Farkas Lemma

Assume P has opt \mathbf{x}^* and find D has opt as well.
Opt value for P:

$$\gamma = \mathbf{c}^T \mathbf{x}^*$$

We know by assumption:

$$\begin{array}{l} \mathbf{Ax} \leq \mathbf{b} \\ \mathbf{c}^T \mathbf{x} \geq \gamma \end{array} \text{ has sol } \mathbf{x} \geq \mathbf{0}$$

$$\text{and } \forall \epsilon > 0 \quad \begin{array}{l} \mathbf{Ax} \leq \mathbf{b} \\ \mathbf{c}^T \mathbf{x} \geq \gamma + \epsilon \end{array} \text{ has no sol } \mathbf{x} \geq \mathbf{0}$$

Let's define:

$$\hat{\mathbf{A}} = \begin{bmatrix} \mathbf{A} \\ -\mathbf{c}^T \end{bmatrix} \quad \hat{\mathbf{b}} = \begin{bmatrix} \mathbf{b} \\ -\gamma - \epsilon \end{bmatrix}$$

and consider $\hat{\mathbf{A}}\mathbf{x} \leq \hat{\mathbf{b}}_0$ and $\hat{\mathbf{A}}\mathbf{x} \leq \hat{\mathbf{b}}_\epsilon$

we apply variant (ii) of Farkas' Lemma:

For $\epsilon \geq 0$, $\hat{\mathbf{A}}\mathbf{x} \leq \hat{\mathbf{b}}_\epsilon$ has no sol $\mathbf{x} \geq \mathbf{0}$ is equivalent to:
there exists $\hat{\mathbf{y}} = (\mathbf{u}, z) \in \mathbb{R}^{m+1}$,

$$\begin{aligned}\hat{\mathbf{y}} &\geq \mathbf{0} \\ \hat{\mathbf{y}}^T \hat{\mathbf{A}} &\geq \mathbf{0} \\ \hat{\mathbf{y}}^T \hat{\mathbf{b}}_\epsilon &< 0\end{aligned}$$

Then

$$\begin{aligned}\mathbf{A}^T \mathbf{u} &\geq \mathbf{0} \\ \mathbf{b}^T \mathbf{u} &< z(\gamma + \epsilon)\end{aligned}$$

Hence, $z > 0$ or $z = 0$ would contradict the separation of cases.

We can set $\mathbf{v} = 1/z\mathbf{u} \geq \mathbf{0}$

$$\begin{aligned}\mathbf{A}^T \mathbf{v} &\geq \mathbf{c} \\ \mathbf{b}^T \mathbf{v} &< \gamma + \epsilon\end{aligned}$$

\mathbf{v} is feasible sol of D with objective value $< \gamma + \epsilon$

For $\epsilon = 0$, $\hat{\mathbf{A}}\mathbf{x} \leq \hat{\mathbf{b}}_0$ has sol $\mathbf{x} \geq \mathbf{0}$ is equivalent to:
there exists $\hat{\mathbf{y}} = (\mathbf{u}, z) \in \mathbb{R}^{m+1}$,

$$\begin{aligned}\hat{\mathbf{y}} &\geq \mathbf{0} \\ \hat{\mathbf{y}}^T \hat{\mathbf{A}} &\geq \mathbf{0} \\ \hat{\mathbf{y}}^T \hat{\mathbf{b}}_0 &\geq 0\end{aligned}$$

Then

$$\begin{aligned}\mathbf{A}^T \mathbf{u} &\geq \mathbf{0} \\ \mathbf{b}^T \mathbf{u} &\geq z\gamma\end{aligned}$$

By weak duality γ is upper bound. Since D bounded and feasible then there exists \mathbf{y}^* :

$$\gamma \leq \mathbf{b}^T \mathbf{y}^* < \gamma + \epsilon \quad \forall \epsilon > 0$$

which implies $\mathbf{b}^T \mathbf{y}^* = \gamma$

Certificate of Infeasibility

Farkas Lemma provides a way to certificate infeasibility.

Given a certificate y^* it is easy to check the conditions (by linear algebra):

$$\begin{aligned}A^T y^* &\geq 0 \\ b y^* &< 0\end{aligned}$$

Why y^* would be a certificate of infeasibility?

Proof: (by contradiction)

Assume, $A^T y^* \geq 0$ and $b y^* < 0$.

Moreover assume $\exists x^*: Ax^* = b, x^* \geq 0$, then:

$$(\geq 0) \quad (y^*)^T Ax^* = (y^*)^T b \quad (< 0)$$

Contradiction

General form:

$$\begin{aligned} \max c^T x \\ A_1 x &= b_1 \\ A_2 x &\leq b_2 \\ A_3 x &\geq b_3 \\ x &\geq 0 \end{aligned}$$

infeasible $\Leftrightarrow \exists y^*$

$$\begin{aligned} b_1^T y_1 + b_2^T y_2 + b_3^T y_3 &> 0 \\ A_1^T y_1 + A_2^T y_2 + A_3^T y_3 &\leq 0 \\ y_2 &\leq 0 \\ y_3 &\geq 0 \end{aligned}$$

Example:

$$\begin{array}{lll} \max c^T x & b_1^T y_1 + b_2^T y_2 > 0 & y_1 + 2y_2 > 0 \\ x_1 \leq 1 & A_1^T y_1 + A_2^T y_2 \leq 0 & y_1 + y_2 \leq 0 \\ x_1 \geq 2 & y_1 \leq 0 & y_1 \leq 0 \\ & y_2 \geq 0 & y_2 \geq 0 \end{array}$$

$y_1 = -1, y_2 = 1$ is a valid certificate.

- ▶ Observe that it is not unique!
- ▶ It can be reported in place of the dual solution because same dimension.
- ▶ To repair infeasibility we should change the primal at least so much as that the certificate of infeasibility is no longer valid.
- ▶ Only constraints with $y_i \neq 0$ in the certificate of infeasibility cause infeasibility

Duality: Summary

- ▶ Derivation:
 1. bounding
 2. multipliers
 3. recipe
 4. Lagrangian (to do)
- ▶ Theory:
 - ▶ Symmetry
 - ▶ Weak duality theorem
 - ▶ Strong duality theorem
 - ▶ Complementary slackness theorem
 - ▶ Farkas Lemma:
Strong duality + Infeasibility certificate
- ▶ Dual Simplex
- ▶ Economic interpretation
- ▶ Geometric Interpretation
- ▶ Sensitivity analysis

Resume

Advantages of considering the dual formulation:

- ▶ proving optimality (although the simplex tableau can already do that)
- ▶ gives a way to check the correctness of results easily
- ▶ alternative solution method (ie, primal simplex on dual)
- ▶ sensitivity analysis
- ▶ solving P or D we solve the other for free
- ▶ certificate of infeasibility