## DM545/DM871 Linear and Integer Programming

# Lecture 9 IP Modeling Formulations, Relaxations

Marco Chiarandini

Department of Mathematics & Computer Science University of Southern Denmark

## Outline

1. Formulations
Uncapacited Facility Location
Alternative Formulations

2. Relaxations

## Outline

#### 1. Formulations

Uncapacited Facility Location Alternative Formulations

2. Relaxations

4

## Outline

1. Formulations

Uncapacited Facility Location

Alternative Formulations

2. Relaxations

5

# **Uncapacited Facility Location (UFL)**

#### Given:

- depots  $N = \{1, \ldots, n\}$
- clients  $M = \{1, ..., m\}$
- f<sub>i</sub> fixed cost to use depot j
- transport cost for all orders cij

**Variables:**  $y_j = \begin{cases} 1 & \text{if depot opened} \\ 0 & \text{otherwise} \end{cases}$ 

**Task:** Which depots to open and which depots serve which client

 $\mathbf{x}_{ij}$  fraction of demand of i satisfied by j

#### Objective:

$$\min \sum_{i \in M} \sum_{j \in N} c_{ij} x_{ij} + \sum_{j \in N} f_j y_j$$

#### Constraints:

$$\sum_{j=1}^{n} x_{ij} = 1$$

$$\sum_{i=1}^{n} x_{ij} \le my_{i}$$

$$\forall i = 1, \ldots, m$$

$$\forall j \in N$$

## Outline

1. Formulations

Uncapacited Facility Location

Alternative Formulations

2. Relaxations

## Good and Ideal Formulations

#### Definition (Formulation)

A polyhedron  $P \subseteq \mathbb{R}^{n+p}$  is a formulation for a set  $X \subseteq \mathbb{Z}^n \times \mathbb{R}^p$  if and only if  $X = P \cap (\mathbb{Z}^n \times \mathbb{R}^p)$ 

That is, if it does not leave out any of the solutions of the feasible region X.

There are infinite formulations

#### Definition (Convex Hull)

Given a set  $X \subseteq \mathbb{Z}^n$  the convex hull of X is defined as:

$$\operatorname{conv}(X) = \left\{ \mathbf{x} : \mathbf{x} = \sum_{i=1}^{t} \lambda_i \mathbf{x}^i, \qquad \sum_{i=1}^{t} \lambda_i = 1, \qquad \lambda_i \ge 0, \qquad \text{for } i = 1, \dots, t, \right.$$

$$\left. \text{for all finite subsets } \left\{ \mathbf{x}^1, \dots, \mathbf{x}^t \right\} \text{ of } X \right\}$$

3

#### Proposition

conv(X) is a polyhedron (ie, representable as  $Ax \leq b$ )

#### **Proposition**

Extreme points of conv(X) all lie in X

Hence:

$$\max\{\mathbf{c}^T\mathbf{x}:\mathbf{x}\in X\}\equiv\max\{\mathbf{c}^T\mathbf{x}:\mathbf{x}\in\mathsf{conv}(X)\}$$

However it might require exponential number of inequalities to describe conv(X) What makes a formulation better than another?

$$X \subseteq \text{conv}(X) \subseteq P_2 \subset P_1$$
  
 $P_2$  is better than  $P_1$ 

#### Definition

Given a set  $X \subseteq \mathbb{R}^n$  and two formulations  $P_1$  and  $P_2$  for X,  $P_2$  is a better formulation than  $P_1$  if  $P_2 \subset P_1$ 

#### Example

$$P_1 = \text{UFL with } \sum_{i \in M} x_{ij} \le my_j \quad \forall j \in N$$
  
 $P_2 = \text{UFL with } x_{ii} \le y_i \quad \forall i \in M, j \in N$ 

$$P_2 \subset P_1$$

- $P_2 \subseteq P_1$  because summing  $x_{ii} \leq y_i$  over  $i \in M$  we obtain  $\sum_{i \in M} x_{ii} \leq my_i$
- $P_2 \subset P_1$  because there exists a point in  $P_1$  but not in  $P_2$ :  $m = 6 = 3 \cdot 2 = k \cdot n$

$$x_{10} = 1, x_{20} = 1, x_{30} = 1,$$

$$x_{41} = 1, x_{51} = 1, x_{61} = 1$$

$$\sum_{i} x_{i0} \le 6y_0 \quad y_0 = 1/2$$
$$\sum_{i} x_{i1} \le 6y_1 \quad y_1 = 1/2$$

Outline

1. Formulations
Uncapacited Facility Location
Alternative Formulations

2. Relaxations

## Optimality and Relaxation

$$z = \max\{c(\mathbf{x}) : \mathbf{x} \in X \subseteq \mathbb{Z}^n\}$$
 How can we prove that  $\mathbf{x}^*$  is optimal? 
$$\overline{z} \text{ is UB}$$
 
$$\underline{z} \text{ is LB}$$
 stop when  $\overline{z} - \underline{z} \le \epsilon$ 

- Primal bounds (here lower bounds): every feasible solution gives a primal bound may be easy or hard to find, heuristics
- Dual bounds (here upper bounds): Relaxations

### Optimality gap (SCIP):

- If primal and dual bound have opposite signs, the gap is "Infinity".
- If primal and dual bound have the same sign, the gap is

$$rac{|pb-db|}{\mathsf{min}(|pb|,|db|)}$$

decreases monotonously during the solving process.

#### Proposition

(RP) 
$$z^R = \max\{f(\mathbf{x}) : \mathbf{x} \in T \subseteq \mathbb{R}^n\}$$
 is a relaxation of (IP)  $z = \max\{c(\mathbf{x}) : \mathbf{x} \in X \subseteq \mathbb{R}^n\}$  if :

- (i)  $X \subseteq T$  or
- (ii)  $f(\mathbf{x}) \geq c(\mathbf{x}) \, \forall \mathbf{x} \in X$

#### In other terms:

$$\max_{\mathbf{x} \in T} f(\mathbf{x}) \ge \begin{Bmatrix} \max_{\mathbf{x} \in T} c(\mathbf{x}) \\ \max_{\mathbf{x} \in X} f(\mathbf{x}) \end{Bmatrix} \ge \max_{\mathbf{x} \in X} c(\mathbf{x})$$

- T: candidate solutions;
- $X \subseteq T$  feasible solutions;
- $f(\mathbf{x}) \geq c(\mathbf{x})$

#### Relaxations

#### How to construct relaxations?

1.  $IP : \max\{\mathbf{c}^T\mathbf{x} : \mathbf{x} \in P \cap \mathbb{Z}^n\}, P = \{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} \leq \mathbf{b}\}$   $LP : \max\{\mathbf{c}^T\mathbf{x} : \mathbf{x} \in P\}$ Better formulations give better bounds  $(P_1 \subseteq P_2)$ 

#### **Proposition**

- (i) If a relaxation LP is infeasible, the original problem IP is infeasible.
- (ii) Let  $x^*$  be optimal solution for LP. If  $x^* \in X$  and  $f(x^*) = c(x^*)$  then  $x^*$  is optimal for IP.
- 2. Combinatorial relaxations to easy problems that can be solved rapidly Eg: TSP to Assignment problem Eg: Symmetric TSP to 1-tree

#### 3. Lagrangian relaxation

$$IP: z = \max\{\mathbf{c}^T\mathbf{x} : A\mathbf{x} \le \mathbf{b}, \mathbf{x} \in X \subseteq \mathbb{Z}^n\}$$

$$LR: z(\mathbf{u}) = \max\{\mathbf{c}^T\mathbf{x} + \mathbf{u}(\mathbf{b} - A\mathbf{x}) : \mathbf{x} \in X\}$$

$$z(\mathbf{u}) > z \forall \mathbf{u} > \mathbf{0}$$

#### 4. Duality:

#### Definition

Two problems:

$$z = \max\{c(\mathbf{x}) : \mathbf{x} \in X\}$$
  $w = \min\{w(\mathbf{u}) : \mathbf{u} \in U\}$ 

form a weak-dual pair if  $c(\mathbf{x}) \leq w(\mathbf{u})$  for all  $\mathbf{x} \in X$  and all  $\mathbf{u} \in U$ . When z = w they form a strong-dual pair

#### **Proposition**

 $z = \max\{\mathbf{c}^T\mathbf{x} : A\mathbf{x} \leq \mathbf{b}, \mathbf{x} \in \mathbb{Z}_+^n\}$  and  $w^{LP} = \min\{\mathbf{u}^T\mathbf{b} : A^T\mathbf{u} \geq \mathbf{c}, \mathbf{u} \in \mathbb{R}_+^m\}$  (ie, dual of linear relaxation) form a weak-dual pair.

#### Proposition

Let IP and D be weak-dual pair:

- (i) If D is unbounded, then IP is infeasible
- (ii) If  $\mathbf{x}^* \in X$  and  $\mathbf{u}^* \in U$  satisfy  $c(\mathbf{x}^*) = w(\mathbf{u}^*)$  then  $\mathbf{x}^*$  is optimal for IP and  $\mathbf{u}^*$  is optimal for D.

The advantage is that we do not need to solve an LP like in the LP relaxation to have a bound, any feasible dual solution gives a bound.

## **Examples**

```
Weak pairs:
```

```
Matching: z = \max\{\mathbf{1}^T \mathbf{x} : A\mathbf{x} \leq \mathbf{1}, \mathbf{x} \in \mathbb{Z}_+^m\}
V. Covering: w = \min\{\mathbf{1}^T \mathbf{y} : A^T \mathbf{y} \geq \mathbf{1}, \mathbf{y} \in \mathbb{Z}_+^n\}
```

Proof: consider LP relaxations, then  $z \le z^{LP} = w^{LP} \le w$ . (strong when graphs are bipartite)

#### Weak pairs:

```
S. Packing: z = \max\{\mathbf{1}^T\mathbf{x} : A\mathbf{x} \leq \mathbf{1}, \mathbf{x} \in \mathbb{Z}_+^n\}
S. Covering: w = \min\{\mathbf{1}^T\mathbf{y} : A^T\mathbf{y} \geq \mathbf{1}, \mathbf{y} \in \mathbb{Z}_+^m\}
```