

Clustering in Subspaces of High-Dimensional Data

Talk at the National Institute of Informatics, Tokio, 6.4.2010

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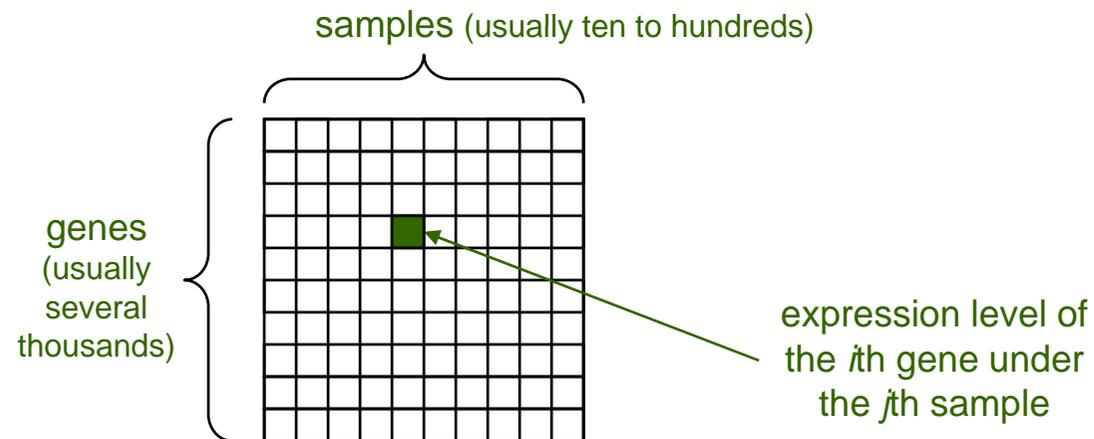
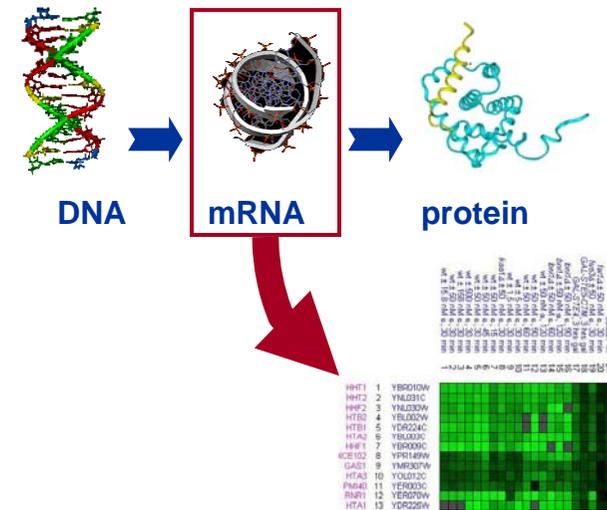
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Outline

1. Sample Applications
2. General Problems and Challenges: the Curse of Dimensionality
3. A First Taxonomy of Approaches
4. Arbitrarily-oriented Subspace Clustering
 1. PCA-Based Approaches
 2. Correlation Clustering Based on the Hough-Transform

Sample Applications

- Gene Expression Analysis
 - Data:
 - Expression level of genes under different samples such as
 - different individuals (patients)
 - different time slots after treatment
 - different tissues
 - different experimental environments
 - Data matrix:

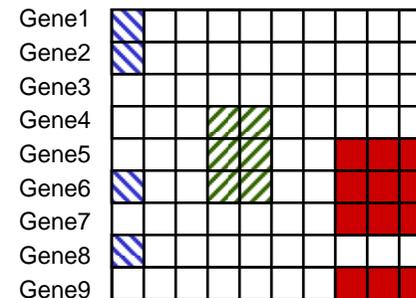


Sample Applications

- Task 1: Cluster the rows (i.e. genes) to find groups of genes with similar expression profiles indicating homogeneous functions

- *Challenge:*

genes usually have
different functions
under varying
(combinations of) conditions



Cluster 1: {G1, G2, G6, G8}

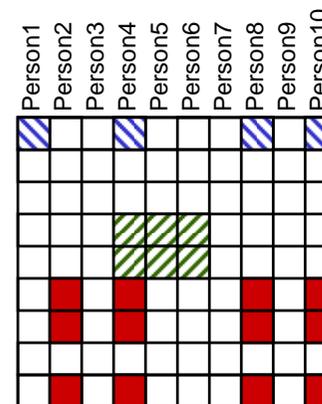
Cluster 2: {G4, G5, G6}

Cluster 3: {G5, G6, G7, G9}

- Task 2: Cluster the columns (e.g. patients) to find groups with similar expression profiles indicating homogeneous phenotypes

- *Challenge:*

different phenotypes
depend on different
(combinations of)
subsets of genes



Cluster 1: {P1, P4, P8, P10}

Cluster 2: {P4, P5, P6}

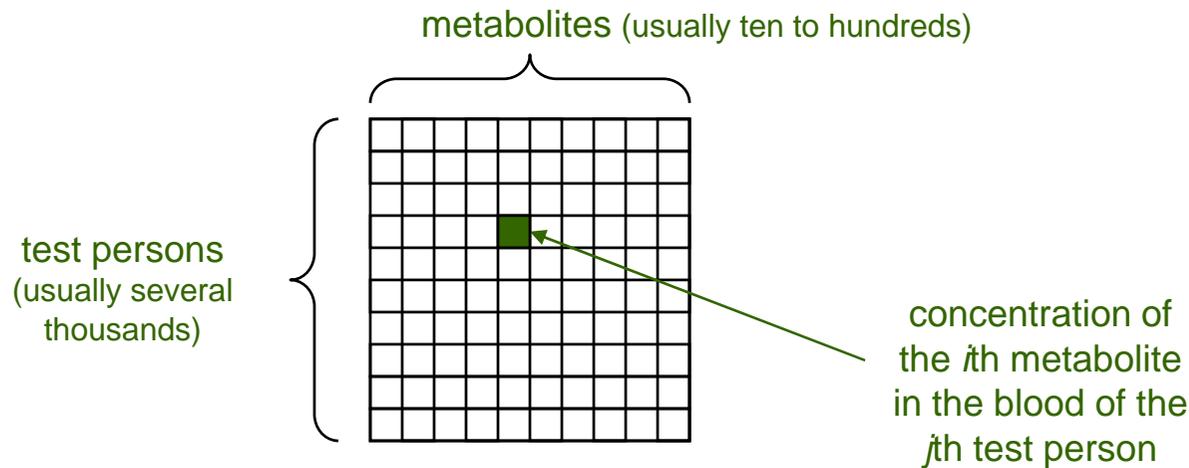
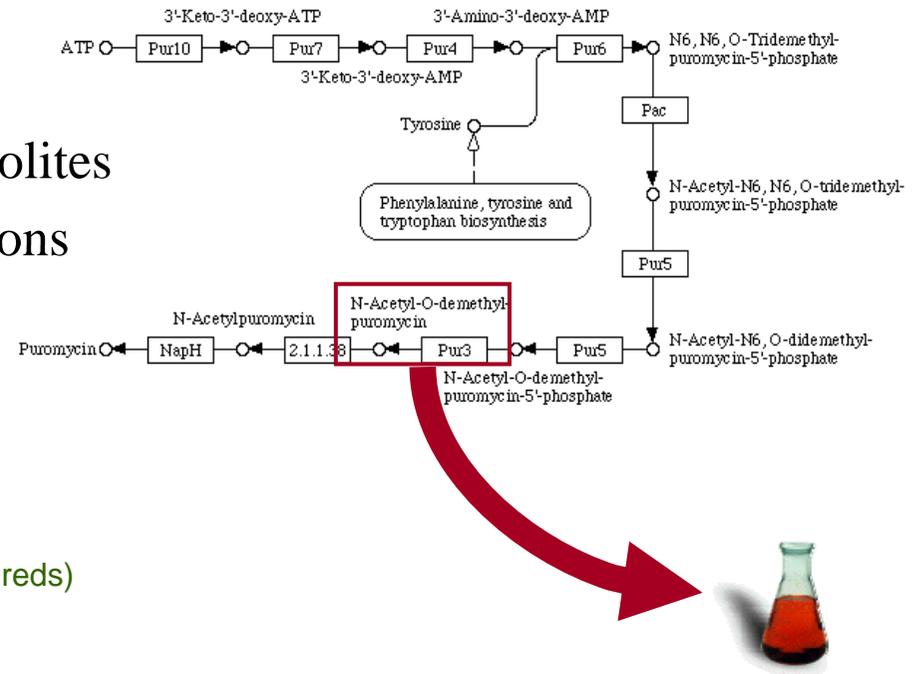
Cluster 3: {P2, P4, P8, P10}

Sample Applications

- Metabolic Screening

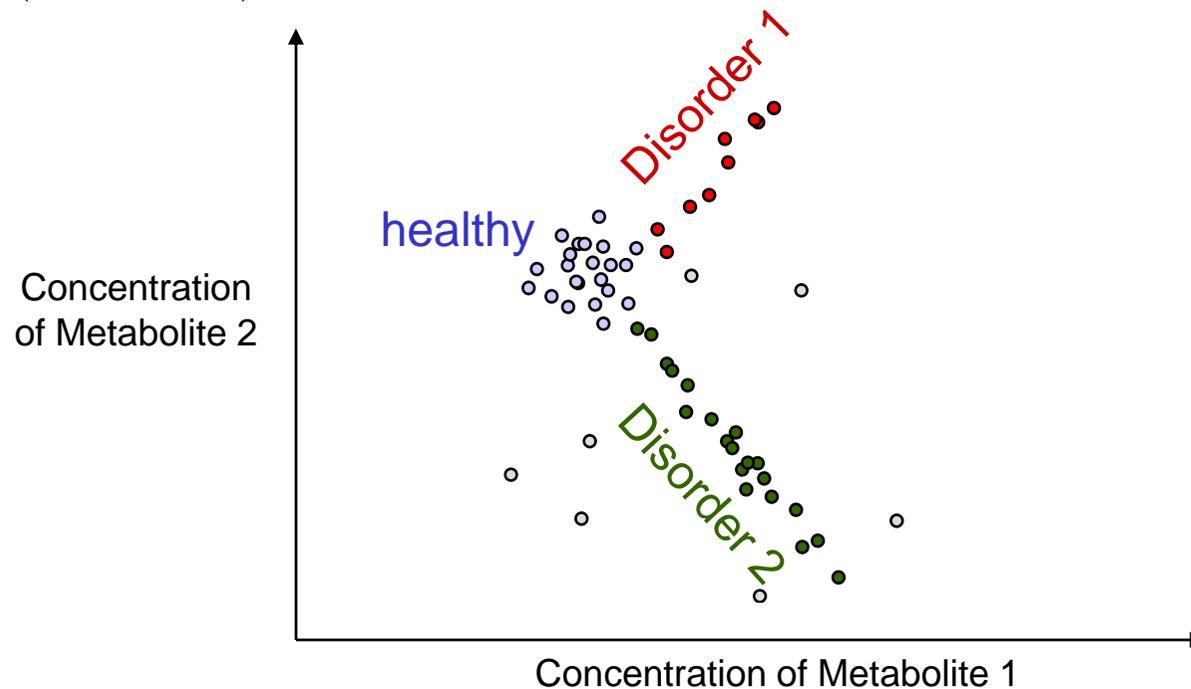
- Data

- Concentration of different metabolites in the blood of different test persons
 - Example: *Bavarian Newborn Screening*
 - Data matrix:



Sample Applications

- Task: Cluster test persons to find groups of individuals with similar correlation among the concentrations of metabolites indicating homogeneous metabolic behavior (e.g. disorder)
 - *Challenge:*
different metabolic disorders appear through different correlations of (subsets of) metabolites



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General Problems & Challenges

The “*curse of dimensionality*”: one buzzword for many problems

- First aspect: *Optimization Problem* (Bellman).

“*[The] curse of dimensionality [... is] a malediction that has plagued the scientists from earliest days.*” [Bel61]

- The difficulty of any global optimization approach increases exponentially with an increasing number of variables (dimensions).
- General relation to clustering: fitting of functions (each function explaining one cluster) becomes more difficult with more degrees of freedom.
- Direct relation to subspace clustering: number of possible subspaces increases dramatically with increasing number of dimensions.

General Problems & Challenges

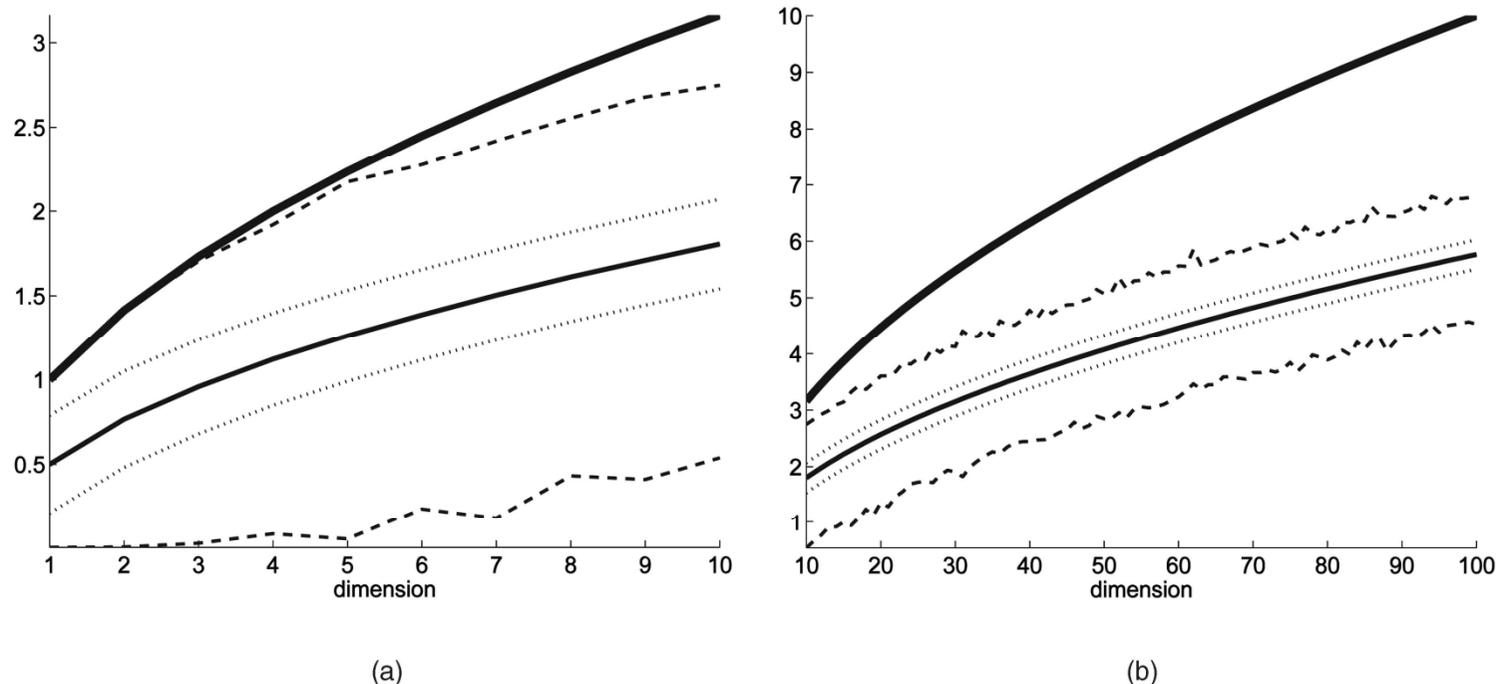
- Second aspect: *Concentration effect of L_p -norms*
 - In [BGRS99,HAK00] it is reported that the ratio of $(D_{\max_d} - D_{\min_d})$ to D_{\min_d} converges to zero with increasing dimensionality d
 - D_{\min_d} = distance to the nearest neighbor in d dimensions
 - D_{\max_d} = distance to the farthest neighbor in d dimensions

Formally:

$$\forall \varepsilon > 0 : \lim_{d \rightarrow \infty} \mathbf{P} \left[\text{dist}_d \left(\frac{D_{\max_d} - D_{\min_d}}{D_{\min_d}}, 0 \right) \leq \varepsilon \right] = 1$$

- This holds true for a wide range of data distributions and distance functions

General Problems & Challenges

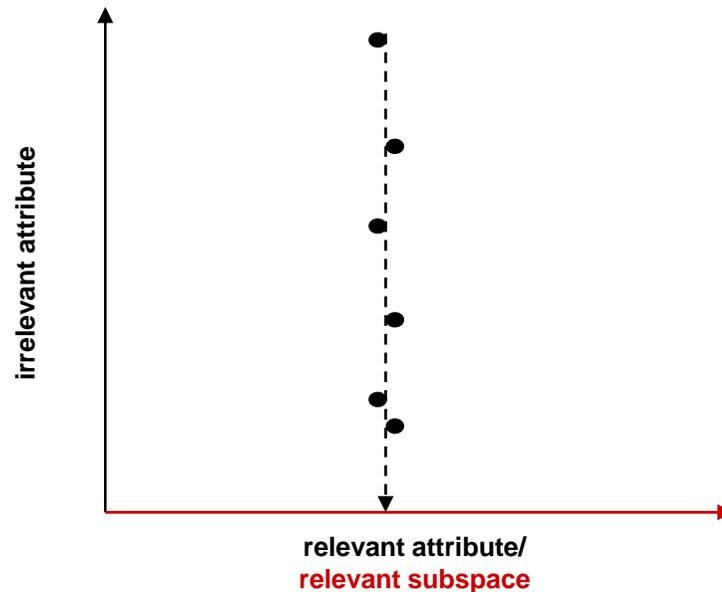


From bottom to top: minimum observed value, average minus standard deviation, average value, average plus standard deviation, maximum observed value, and maximum possible value of the Euclidean norm of a random vector. The expectation grows, but the variance remains constant. A small subinterval of the domain of the norm is reached in practice. (Figure and caption: [FWV07])

- The observations stated in [BGRS99,HAK00] are valid *within* clusters but *not between different* clusters as long as the clusters are well separated [BFG99,FWV07,HKK+10].
- This is *not* the main problem for subspace clustering, although it should be kept in mind for range queries.

General Problems & Challenges

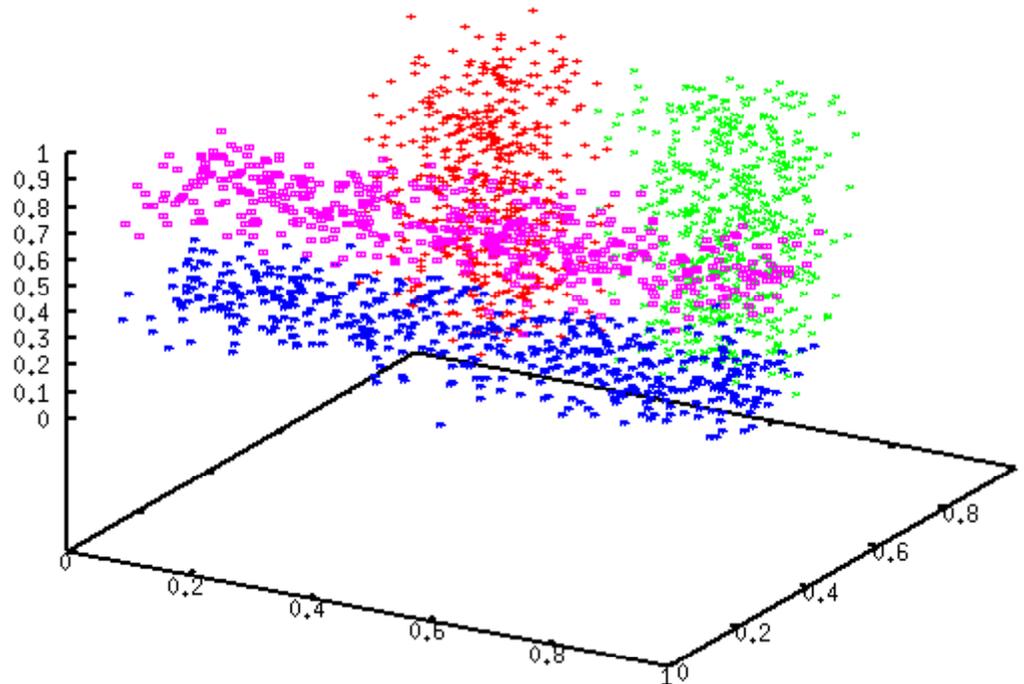
- Third aspect: *Relevant and Irrelevant attributes*
 - A subset of the features may be relevant for clustering
 - Groups of similar (“dense”) points may be identified when considering these features only



- Different subsets of attributes may be relevant for different clusters

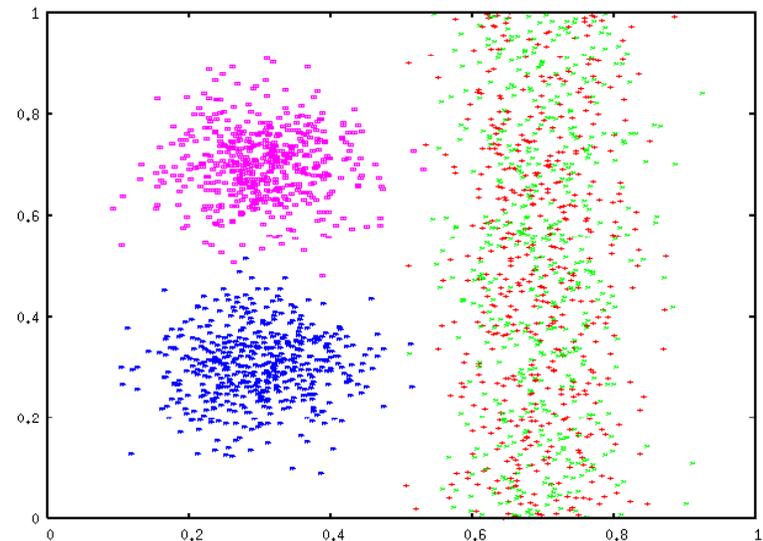
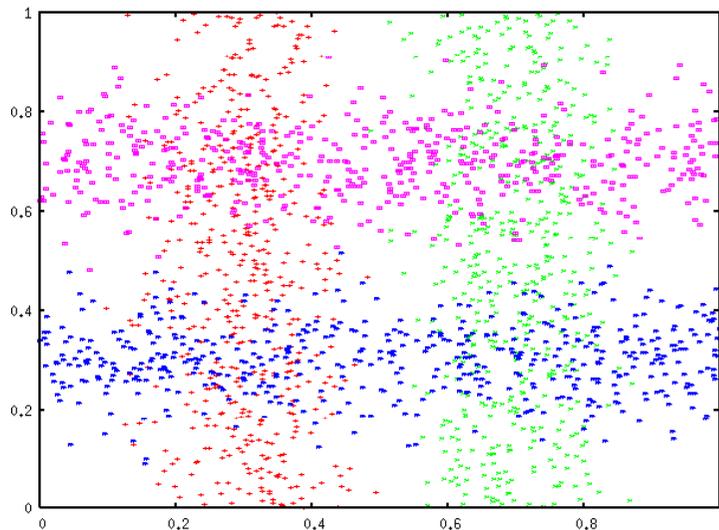
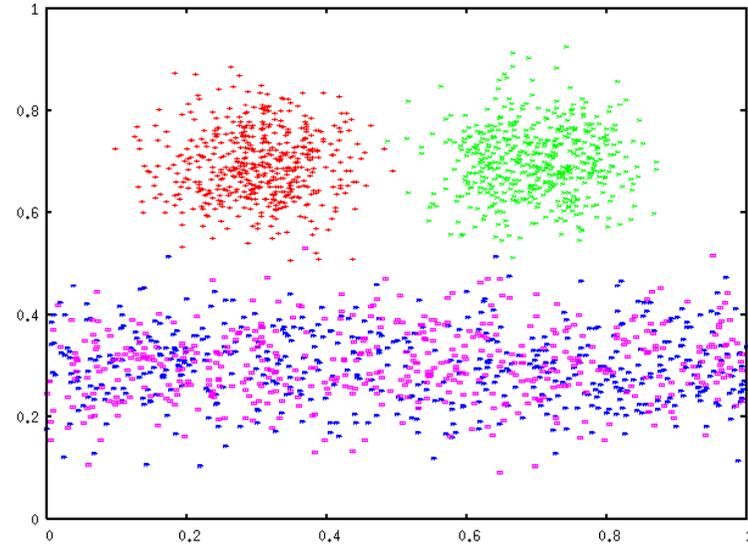
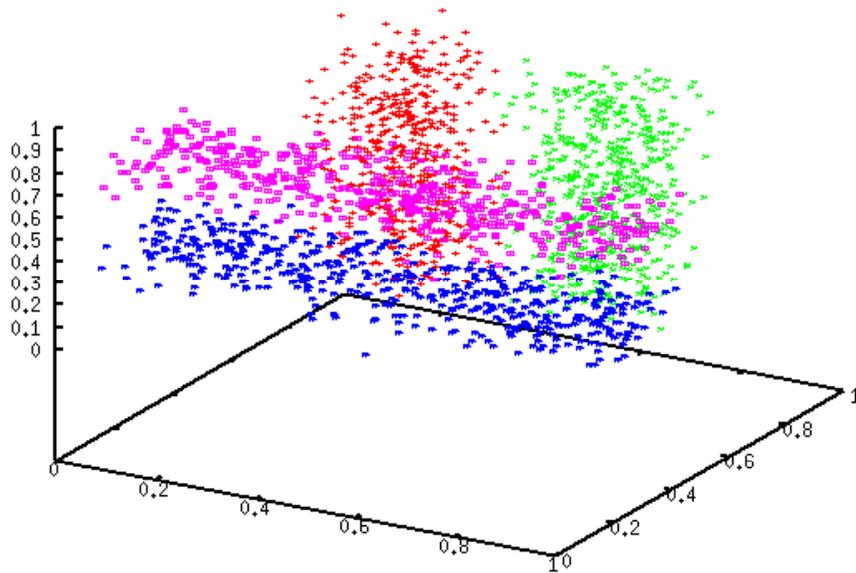
General Problems & Challenges

- Effect on clustering:
 - Usually the distance functions used give equal weight to all dimensions
 - However, not all dimensions are of equal importance
 - Adding irrelevant dimensions ruins any clustering based on a distance function that equally weights all dimensions



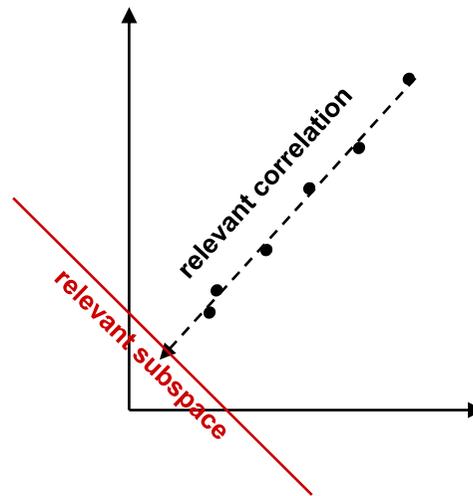
General Problems & Challenges

- again: different attributes are relevant for different clusters



General Problems & Challenges

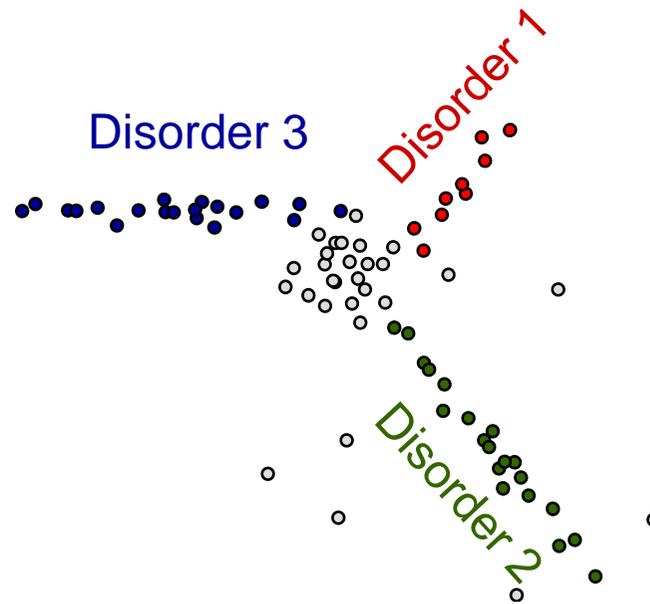
- Fourth aspect: *Correlation among attributes*
 - A subset of features may be correlated
 - Groups of similar (“dense”) points may be identified when considering this correlation of features only



- Different correlations of attributes may be relevant for different clusters

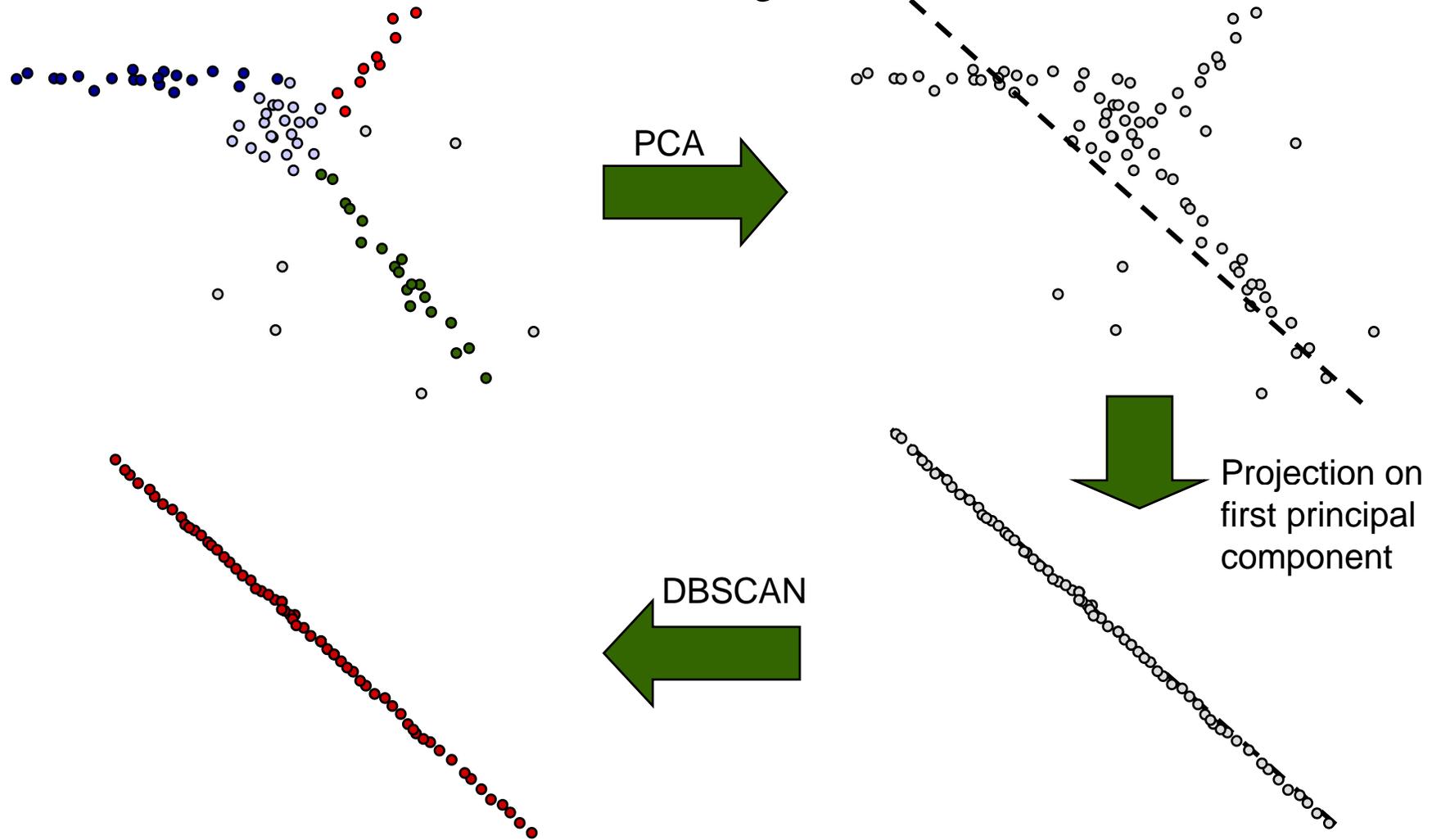
General Problems & Challenges

- Why not feature selection?
 - (Unsupervised) feature selection is global (e.g. PCA)
 - We face a local feature relevance/correlation: some features (or combinations of them) may be relevant for one cluster, but may be irrelevant for a second one



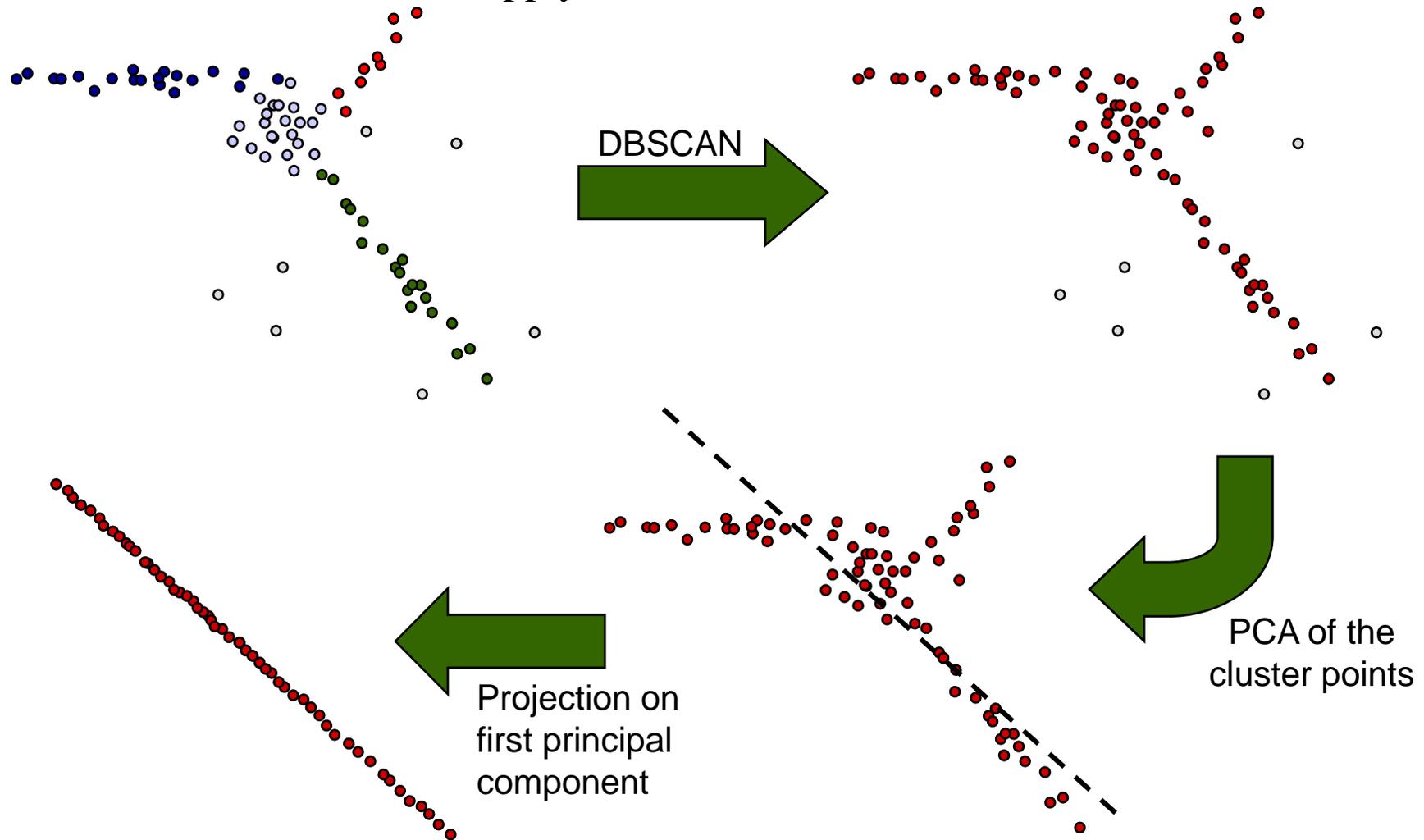
General Problems & Challenges

- Use feature selection before clustering



General Problems & Challenges

- Cluster first and then apply PCA



General Problems & Challenges

- Problem Summary
 - Curse of dimensionality/Feature relevance and correlation
 - Usually, no clusters in the full dimensional space
 - Often, clusters are hidden in subspaces of the data, i.e. only a subset of features is relevant for the clustering
 - E.g. a gene plays a certain role in a subset of experimental conditions
 - Local feature relevance/correlation
 - For each cluster, a different subset of features or a different correlation of features may be relevant
 - E.g. different genes are responsible for different phenotypes
 - Overlapping clusters
 - Clusters may overlap, i.e. an object may be clustered differently in varying subspaces
 - E.g. a gene plays different functional roles depending on the environment

General Problems & Challenges

- General problem setting of clustering high dimensional data

*Search for clusters in
(in general arbitrarily oriented) subspaces
of the original feature space*

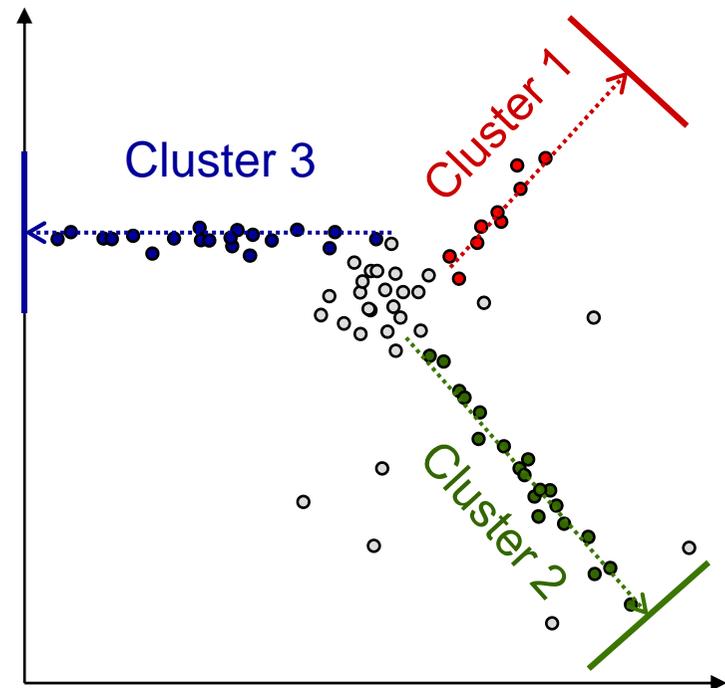
- Challenges:
 - Find the correct subspace of each cluster
 - Search space:
 - all possible arbitrarily oriented subspaces of a feature space
 - infinite
 - Find the correct cluster in each relevant subspace
 - Search space:
 - “Best” partitioning of points (see: minimal cut of the similarity graph)
 - NP-complete [SCH75]

General Problems & Challenges

- Even worse: *Circular Dependency*
 - Both challenges depend on each other
 - In order to determine the correct subspace of a cluster, we need to know (at least some) cluster members
 - In order to determine the correct cluster memberships, we need to know the subspaces of all clusters
 - How to solve the circular dependency problem?
 - Integrate subspace search into the clustering process
 - Thus, we need heuristics to solve
 - the clustering problem
 - the subspace search problem
- simultaneously*

General Problems & Challenges

- Solution: integrate variance / covariance analysis into the clustering process
 - Variance analysis:
 - Find clusters in axis-parallel subspaces
 - Cluster members exhibit low variance along the relevant dimensions
 - Covariance/correlation analysis:
 - Find clusters in arbitrarily oriented subspaces
 - Cluster members exhibit a low covariance w.r.t. a given combination of the relevant dimensions (i.e. a low variance along the dimensions of the arbitrarily oriented subspace corresponding to the given combination of relevant attributes)

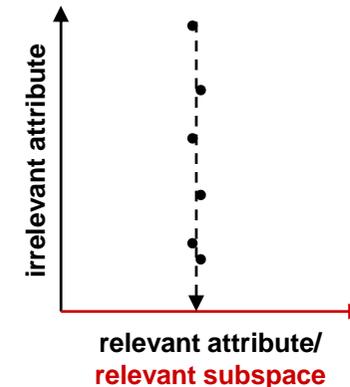


Outline

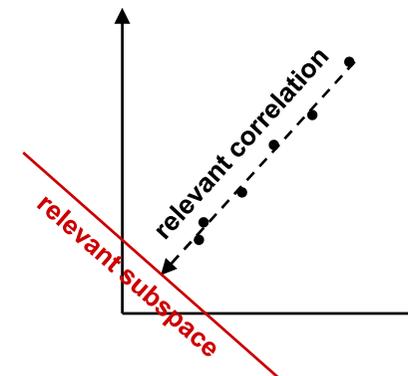
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A First Taxonomy of Approaches

- So far, we can distinguish between
 - Clusters in axis-parallel subspaces
(common assumption to restrict the search space)
Approaches are usually called
 - “subspace clustering algorithms”
 - “projected clustering algorithms”
 - “bi-clustering or co-clustering algorithms”



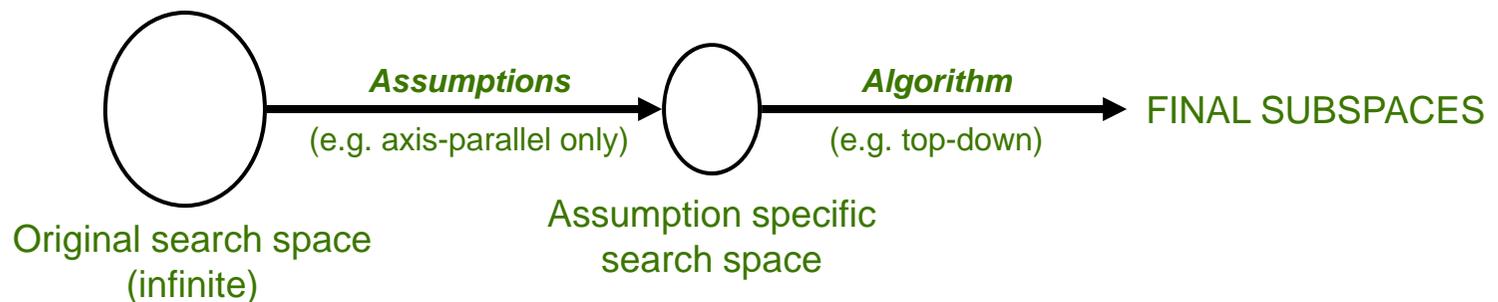
- Clusters in arbitrarily oriented subspaces
Approaches are usually called
 - “bi-clustering or co-clustering algorithms”
 - “pattern-based clustering algorithms”
 - “correlation clustering algorithms”



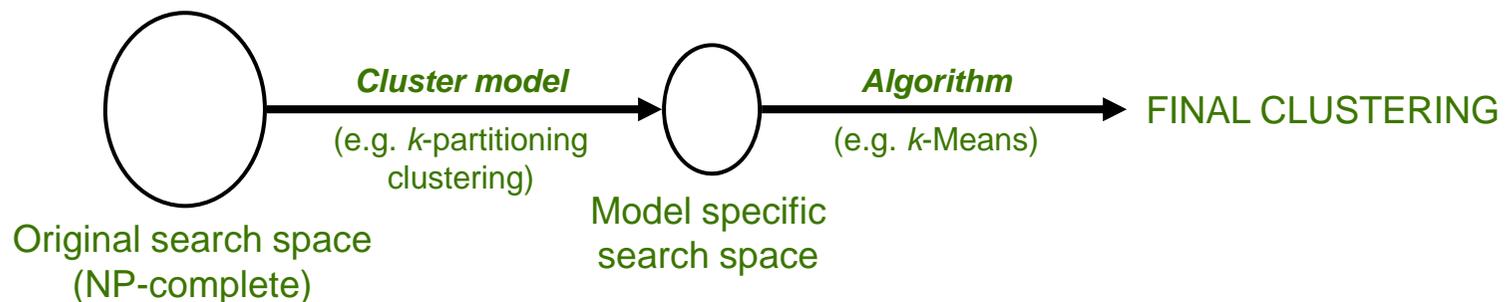
A First Taxonomy of Approaches

- A first big picture
 - We have two problems to solve
 - For both problems we need heuristics that have huge influence on the properties of the algorithms

- *Subspace search*



- *Cluster search*



A First Taxonomy of Approaches

- Restricted on *axis-parallel subspaces* – what are we searching for?
 - Overlapping clusters: points may be grouped differently in different subspaces
=> “*subspace clustering*”
 - Disjoint partitioning: assign points uniquely to clusters (or noise)
=> “*projected clustering*”

Notes:

- The terms **subspace** clustering and **projected** clustering are not (yet) used in a unified or consistent way in the literature
- These two problem definitions are products of the presented algorithms:
 - The first “projected clustering algorithm” integrates a distance function accounting for clusters in subspaces into a “flat” clustering algorithm (k-medoid)
=> DISJOINT PARTITION
 - The first “subspace clustering algorithm” is an application of the APRIORI algorithm => ALL CLUSTERS IN ALL SUBSPACES

A First Taxonomy of Approaches

- Restricted on *axis-parallel subspaces* – how are we searching?
- Basically, there are two different ways to efficiently navigate through the search space of possible subspaces

Bottom-up:

If the cluster criterion implements the downward closure, one can use any bottom-up frequent itemset mining algorithm (e.g. APRIORI [AS94])

Key: downward-closure property OR merging-procedure

Example approaches:

[AGGR98, CFZ99, NGC01, KKK04, KKRW05, MSE06, ABK+07a]

Top-down:

The search starts in the full d -dimensional space and iteratively learns for each point or each cluster the correct subspace

Key: procedure to learn the correct subspace

Example approaches: [APW+99, BKKK04, FM04, WLKL04]

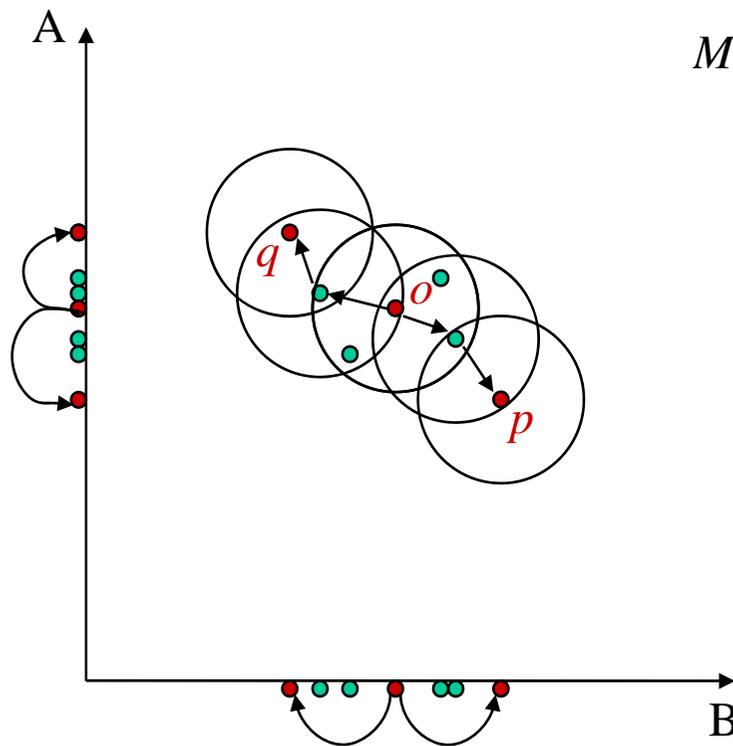
Taxonomy: Bottom-up Algorithms

- Rational:
 - Start with 1-dimensional subspaces and merge them to compute higher dimensional ones
 - Most approaches transfer the problem of subspace search into frequent item set mining
 - The cluster criterion must implement the downward closure property
 - If the criterion holds for any k -dimensional subspace S , then it also holds for any $(k-1)$ -dimensional projection of S
 - Use the reverse implication for pruning:
If the criterion does not hold for a $(k-1)$ -dimensional projection of S , then the criterion also does not hold for S
 - Apply any frequent itemset mining algorithm (e.g. APRIORI)
 - Some approaches use other search heuristics like best-first-search, greedy-search, etc.
 - Better average and worst-case performance
 - No guaranty on the completeness of results

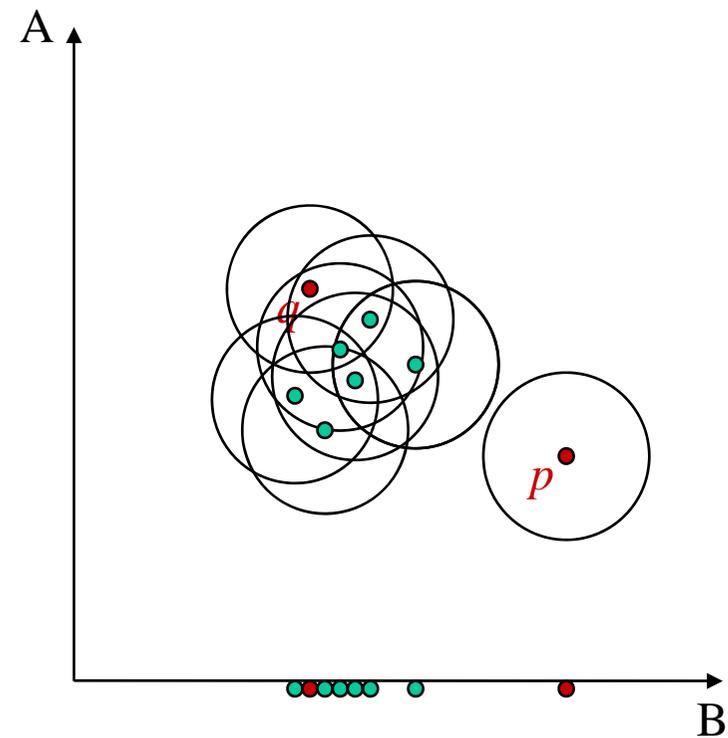
Taxonomy: Bottom-up Algorithms

- Downward-closure property

if C is a dense set of points in subspace S ,
then C is also a dense set of points in any subspace $T \subset S$



p and q density-connected in $\{A,B\}$, $\{A\}$ and $\{B\}$

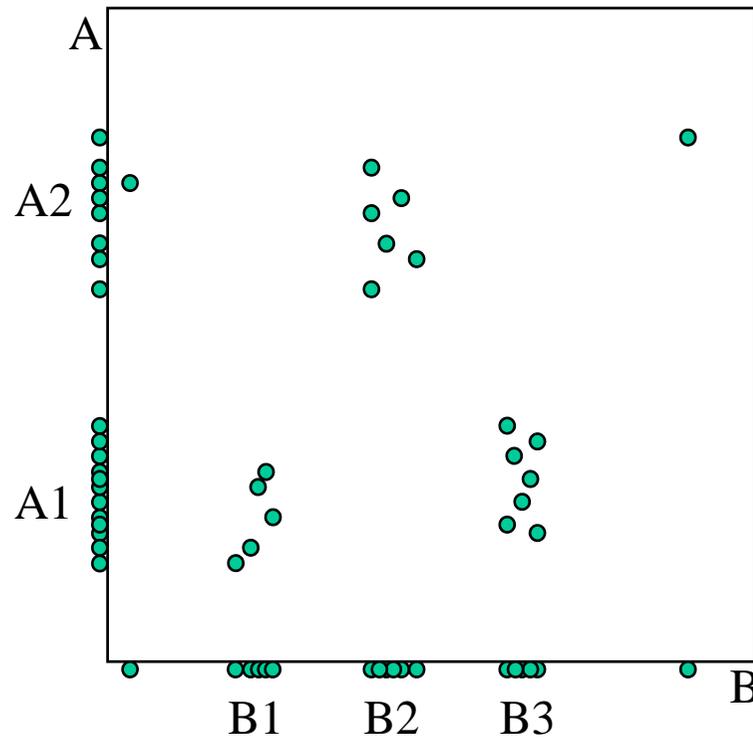


p and q not density-connected in $\{B\}$ and $\{A,B\}$

Taxonomy: Bottom-up Algorithms

- Downward-closure property

the reverse implication does not hold necessarily



Taxonomy: Top-down Algorithms

- The key problem: How should we learn the subspace preference of a cluster or a point?
 - Most approaches rely on a “locality assumption”
 - The subspace is usually learned from the local neighborhood of cluster representatives/cluster members in the entire feature space:
 - Cluster-based approach: the *local neighborhood* of each cluster representative is evaluated in the d -dimensional space to learn the “correct” subspace of the cluster
 - Instance-based approach: the *local neighborhood* of each point is evaluated in the d -dimensional space to learn the “correct” subspace preference of each point
 - *The locality assumption*: the subspace preference can be learned from the *local neighborhood* in the d -dimensional space
 - Other approaches learn the subspace preference of a cluster or a point from *randomly sampled points*

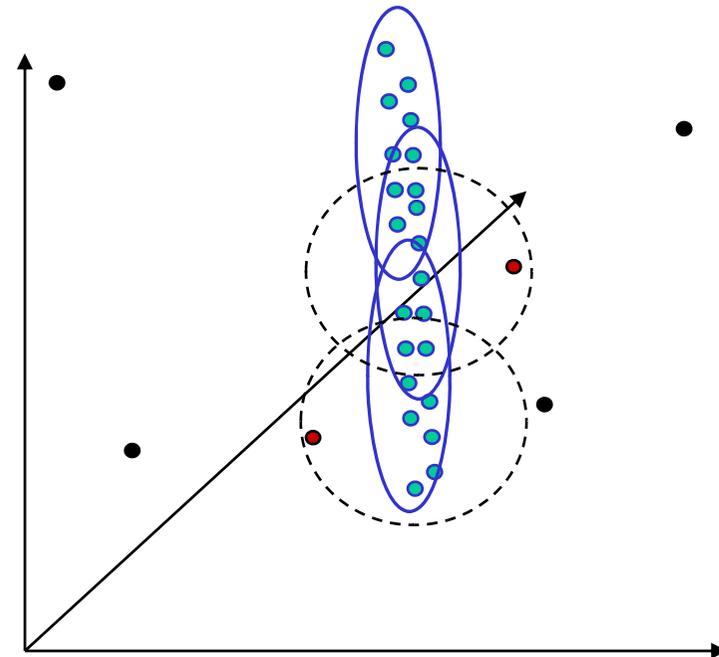
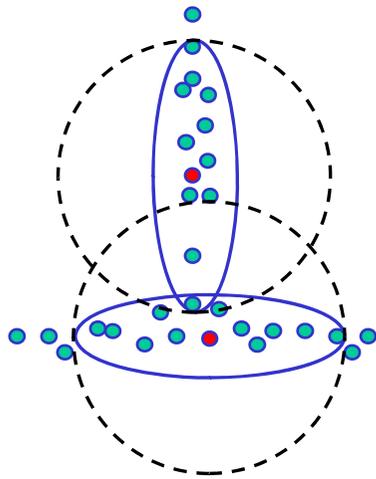
Taxonomy: Top-down Algorithms

- Example:
 - learn weights based on attribute wise variances for a weighted Euclidean distance function

$$dist_p(p, q) = \sqrt{\sum_i w_i \cdot (p_i - q_i)^2} \quad \text{w.r.t. } p$$

- Caveat: ensure symmetry, e.g.

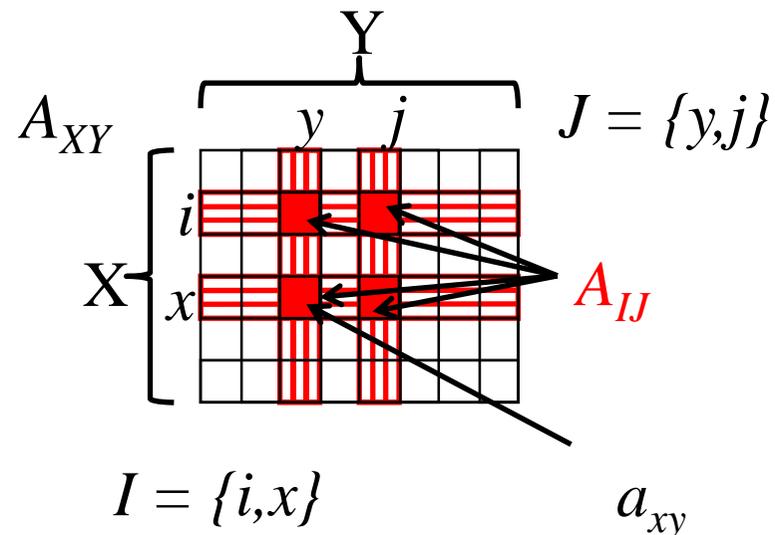
$$dist(p, q) = \max \{ dist_p(p, q), dist_q(q, p) \}$$



A First Taxonomy of Approaches

Pattern-based clustering relies on patterns in the data matrix.

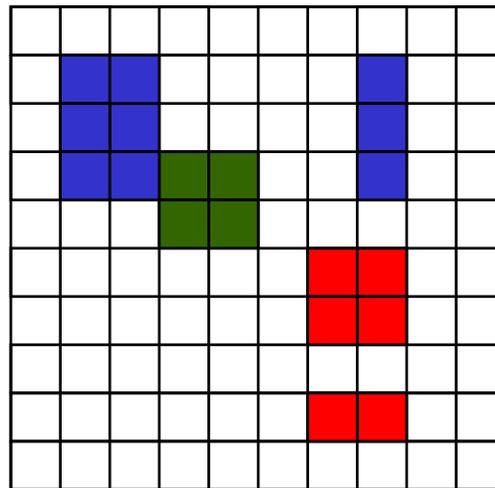
- Simultaneous clustering of rows and columns of the data matrix (hence *biclustering*).
 - Data matrix $A = (X, Y)$ with set of rows X and set of columns Y
 - a_{xy} is the element in row x and column y .
 - submatrix $A_{IJ} = (I, J)$ with subset of rows $I \subseteq X$ and subset of columns $J \subseteq Y$ contains those elements a_{ij} with $i \in I$ und $j \in J$



A First Taxonomy of Approaches

General aim of biclustering approaches:

Find a set of submatrices $\{(I_1, J_1), (I_2, J_2), \dots, (I_k, J_k)\}$ of the matrix $A=(X, Y)$ (with $I_i \subseteq X$ and $J_i \subseteq Y$ for $i = 1, \dots, k$) where each submatrix (= bicluster) meets a given homogeneity criterion.



Sounds similar to subspace clustering but:
the *homogeneity criterion* is completely *different*!

A First Taxonomy of Approaches

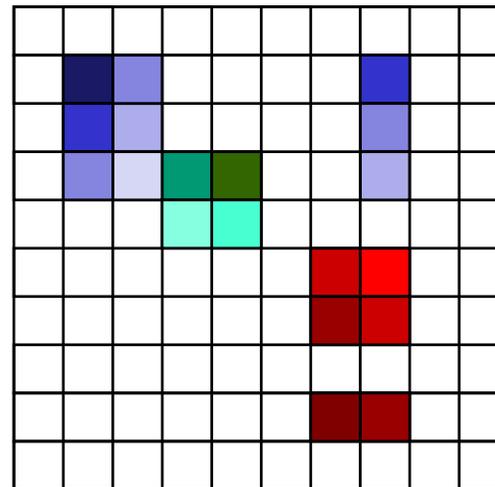
most common model (following Cheng & Church [CC00]):

biclusters with coherent values

- based on a particular form of covariance between rows and columns

$$a_{ij} = \mu + r_i + c_j$$

$$\forall i \in I, j \in J$$

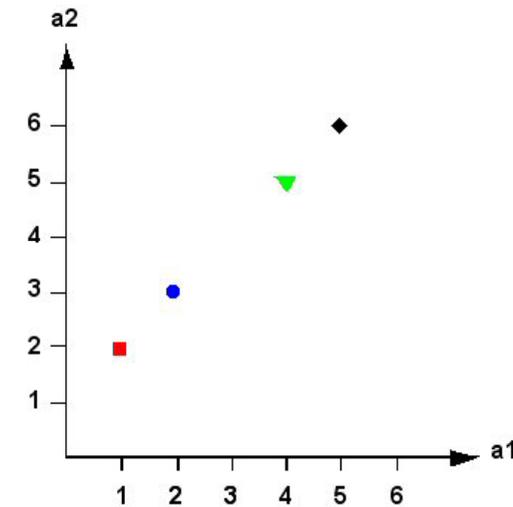
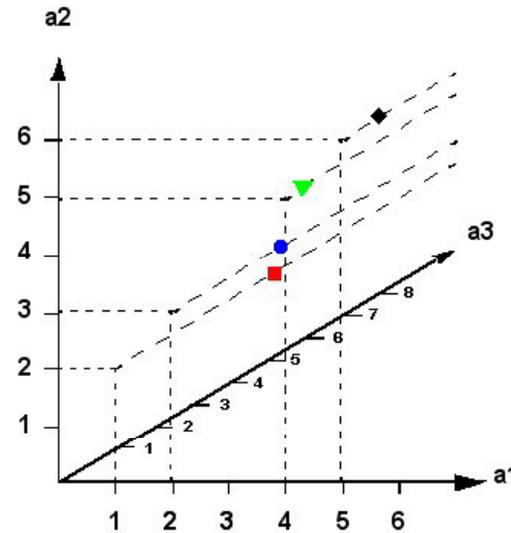


- special cases:
 - $c_j = 0$ for all $j \rightarrow$ constant values on rows
 - $r_i = 0$ for all $i \rightarrow$ constant values on columns

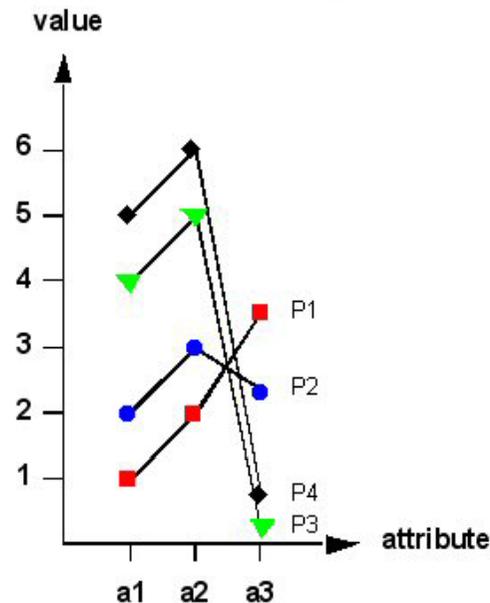
A First Taxonomy of Approaches

- embedding space: sparse hyperplane parallel to axes of irrelevant attributes

	a1	a2	a3
P1	1	2	3.5
P2	2	3	2.3
P3	4	5	0.2
P4	5	6	0.7

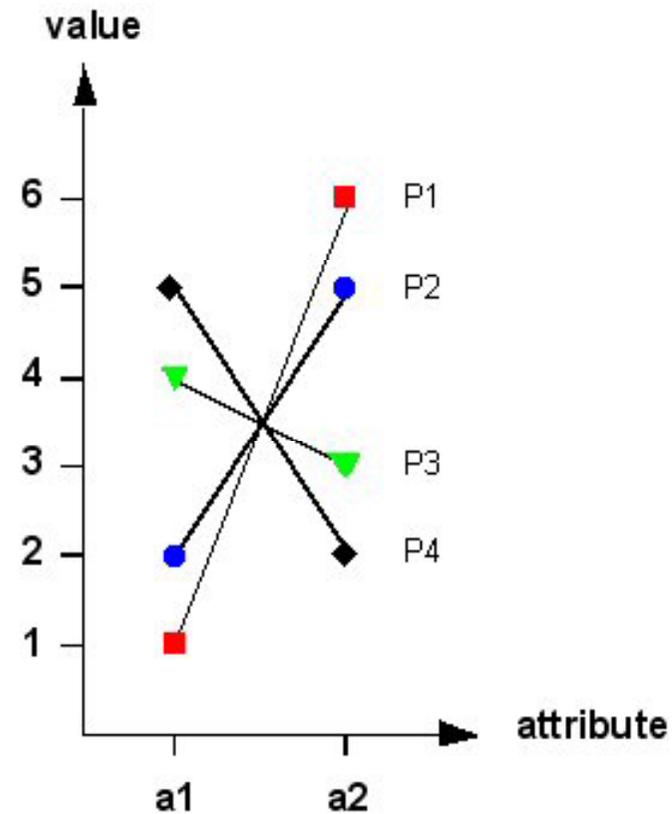
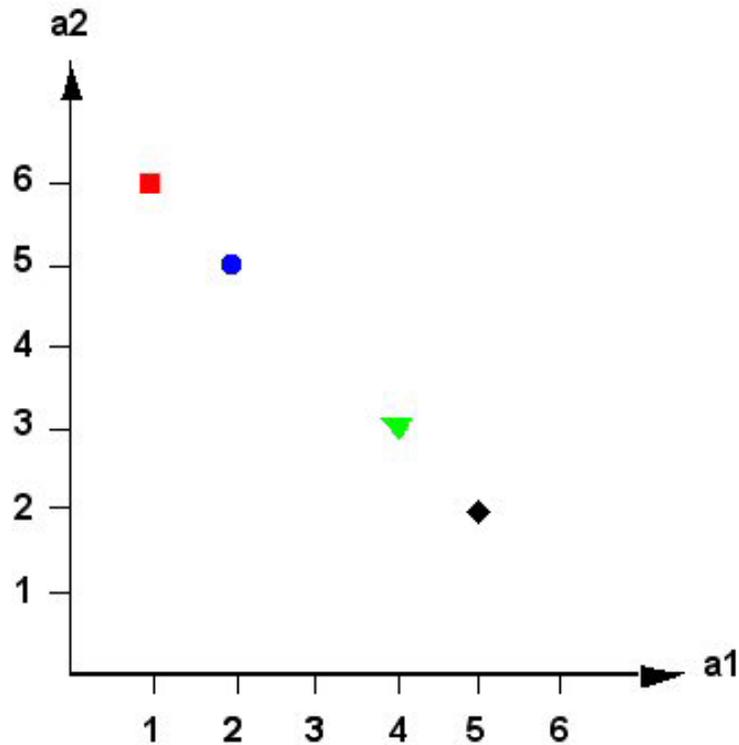


- subspace: increasing one-dimensional line
- pattern (parallel coordinates-plot): parallel lines



A First Taxonomy of Approaches

- Pattern-based approaches find simple positive correlations
- negative correlations: no additive pattern

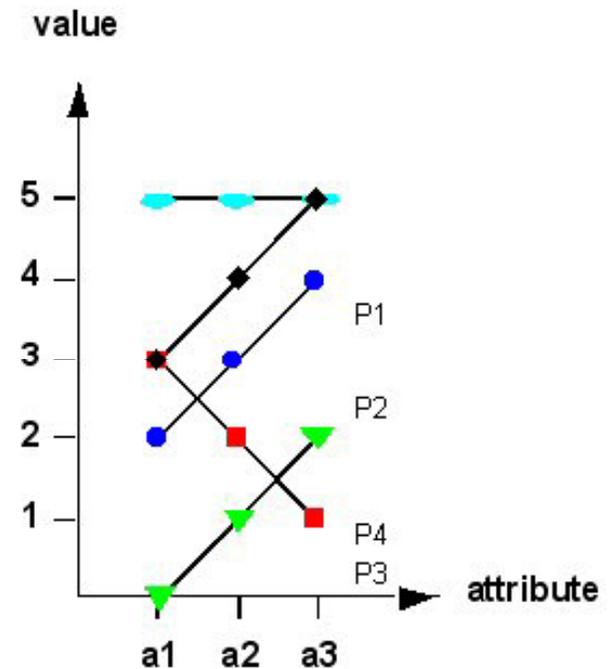
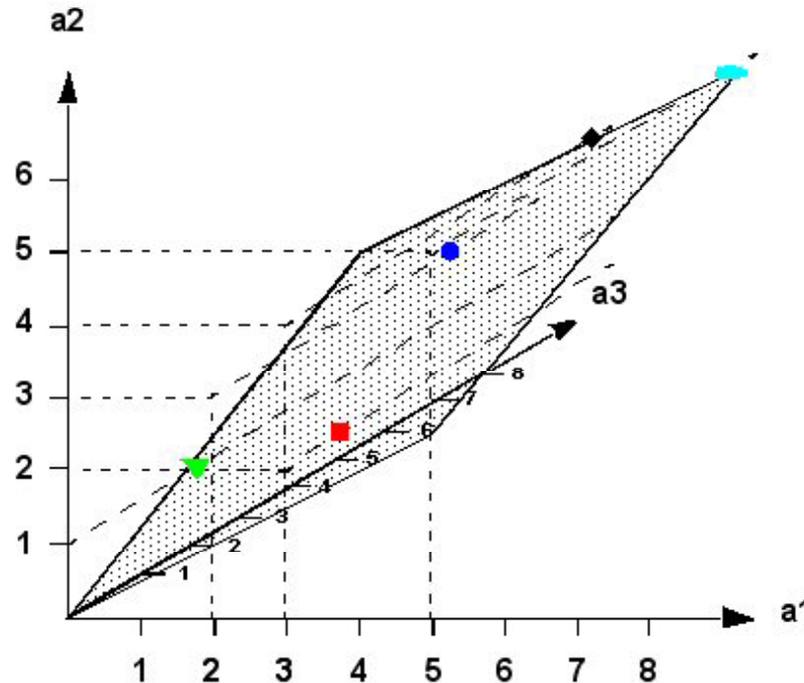


A First Taxonomy of Approaches

- more complex correlations: out of scope of pattern-based approaches

$$a1 - 2 \cdot a2 + a3 = 0$$

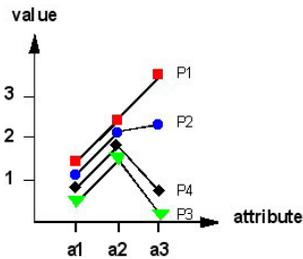
	a1	a2	a3
P1	3	2	1
P2	2	3	4
P3	0	1	2
P4	3	4	5
P5	5	5	6



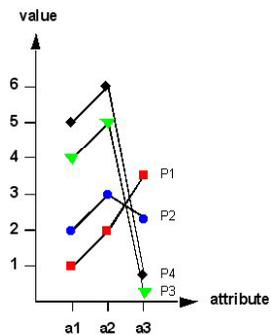
- interesting subspace is arbitrarily oriented, related to complex correlations among attributes \rightarrow *Correlation Clustering*

A First Taxonomy of Approaches

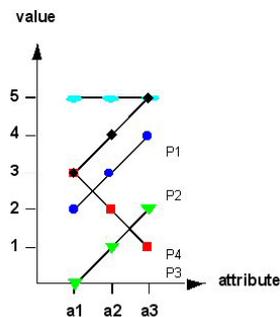
Matrix-Pattern



Constant values in columns, change of values only on rows



From constant values in rows and columns (no change of values) to arbitrary change of values in common direction



No particular pattern

Problem

Subspace / Projected Clustering

Pattern-based / Bi-Clustering

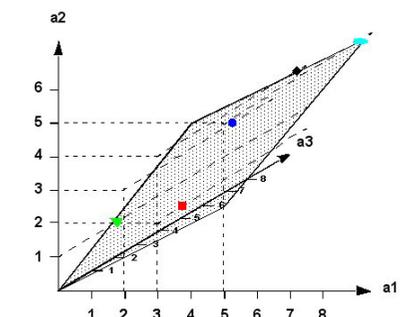
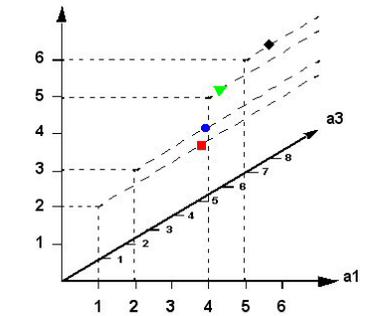
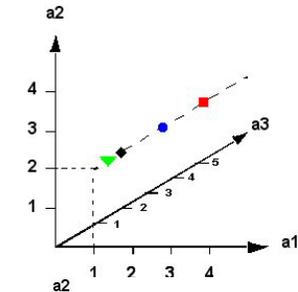
Correlation Clustering

Spatial Pattern

Axis-parallel hyperplanes

Special cases of axis-parallel to special cases of arbitrarily oriented hyperplanes

Arbitrarily oriented hyperplanes



A First Taxonomy of Approaches

- Note: this taxonomy considers only the subspace search space
- the clustering search space is equally important
- other important aspects for classifying existing approaches are e.g.
 - The underlying cluster model that usually involves
 - Input parameters
 - Assumptions on number, size, and shape of clusters
 - Noise (outlier) robustness
 - Determinism
 - Independence w.r.t. the order of objects/attributes
 - Assumptions on overlap/non-overlap of clusters/subspaces
 - Efficiency

Extensive survey: [KKZ09]

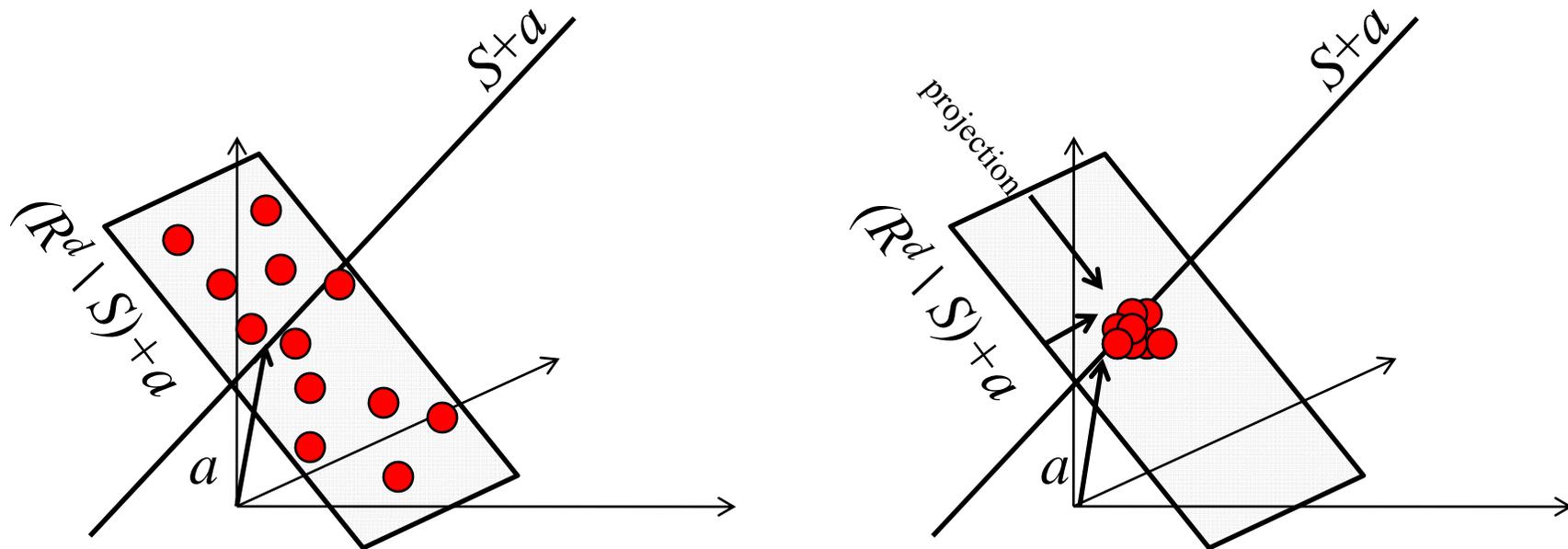
<http://doi.acm.org/10.1145/1497577.1497578>

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PCA-based Approaches

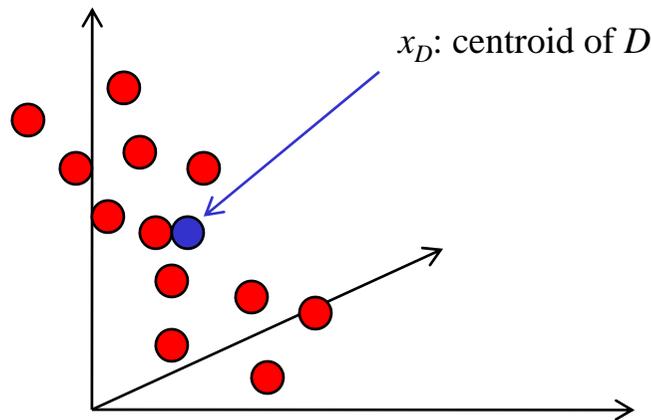
- Pattern-based approaches find pairwise positive correlations
- More general approach: oriented clustering aka. generalized subspace/projected clustering aka. correlation clustering
- Assumption: any cluster is located in an arbitrarily oriented affine subspace $S+a$ of R^d



PCA-based Approaches

- Directions of high/low variance: PCA (local application)
- locality assumption: local selection of points sufficiently reflects the hyperplane accommodating the points
- general approach: build covariance matrix Σ_D for a selection D of points (e.g. k nearest neighbors of a point)

$$\Sigma_D = \frac{1}{|D|} \sum_{x \in D} (x - x_D)(x - x_D)^T$$



properties of Σ_D :

- $d \times d$
- symmetric
- positive semidefinite
- $\sigma_{D_{ij}}$ (value at row i , column j) = covariance between dimensions i and j
- $\sigma_{D_{ii}}$ = variance in i th dimension

PCA-based Approaches

model for correlation clusters [ABK+06]:

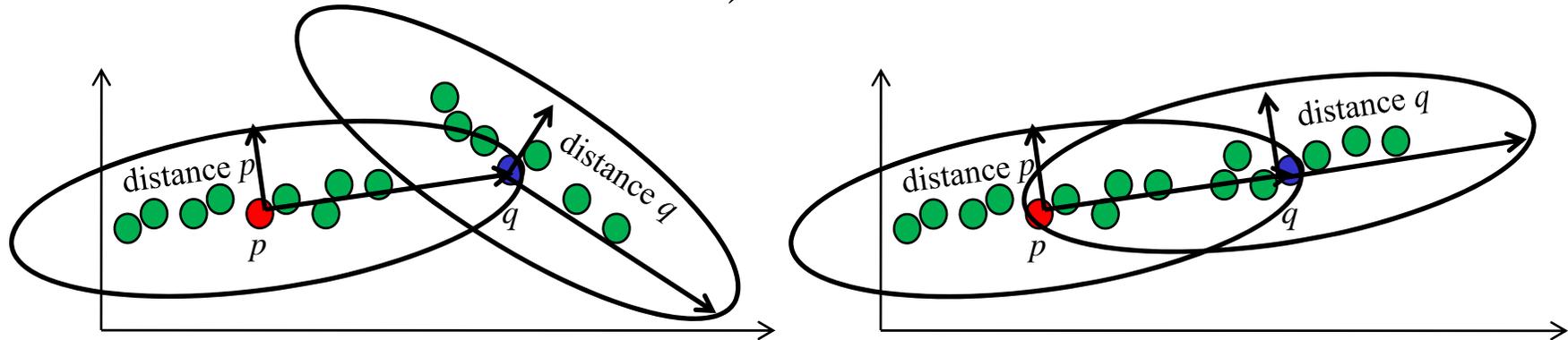
- λ -dimensional hyperplane accommodating the points of a correlation cluster $C \subset R^d$ is defined by an equation system of $d-\lambda$ equations for d variables (based on the small eigenvalues \hat{V}_C) and the affinity (e.g. the mean point x_C of all cluster members):

$$\hat{V}_C^T x = \hat{V}_C^T x_C$$

- equation system approximately fulfilled for all points $x \in C$
- quantitative model for the cluster allowing for probabilistic prediction (classification)
- Note: correlations are observable, linear dependencies are merely an assumption to explain the observations – predictive model allows for evaluation of assumptions and experimental refinements

PCA-based Approaches

- Examples of PCA based correlation clustering:
[AY00, BKKZ04, ABK+07c, ABK+07b]
- Learning the distance top-down (similar to axis-parallel, but covariance instead of variance):



- E.g., p and q are correlation-neighbors if

$$\max \left\{ \begin{array}{l} \sqrt{(p - q) \cdot V_p \cdot E'_p \cdot V_p^T \cdot (p - q)^T}, \\ \sqrt{(q - p) \cdot V_q \cdot E'_q \cdot V_q^T \cdot (q - p)^T} \end{array} \right\} \leq \varepsilon$$

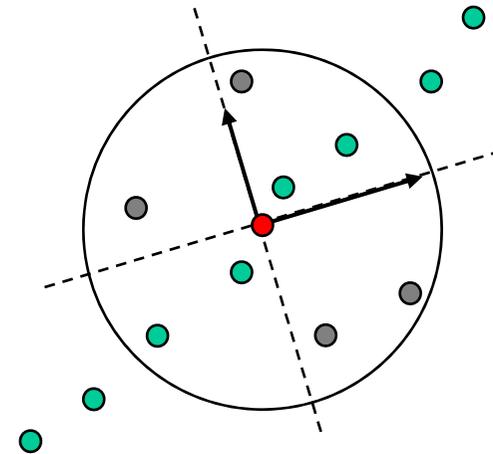
Outline

1. Sample Applications
2. General Problems and Challenges: the Curse of Dimensionality
3. A First Taxonomy of Approaches
4. Arbitrarily-oriented Subspace Clustering
 1. PCA-Based Approaches
 2. Correlation Clustering Based on the Hough-Transform

Correlation Clustering Based on the Hough-Transform

different correlation primitive: Hough-transform

- problems of PCA based approaches: locality assumption
 - characteristic neighborhood?
 - PCA sensitive for outliers in local neighborhoods
 - choice of λ ?
 - “locality assumption” questionable in view of the “curse of dimensionality”

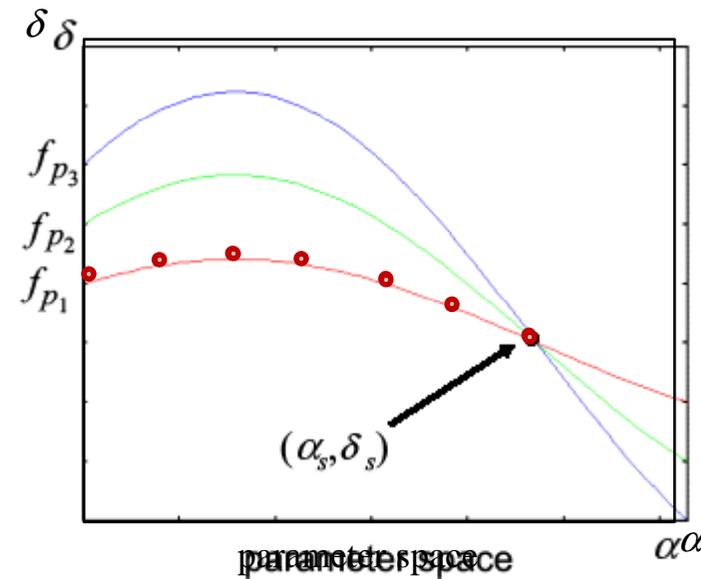
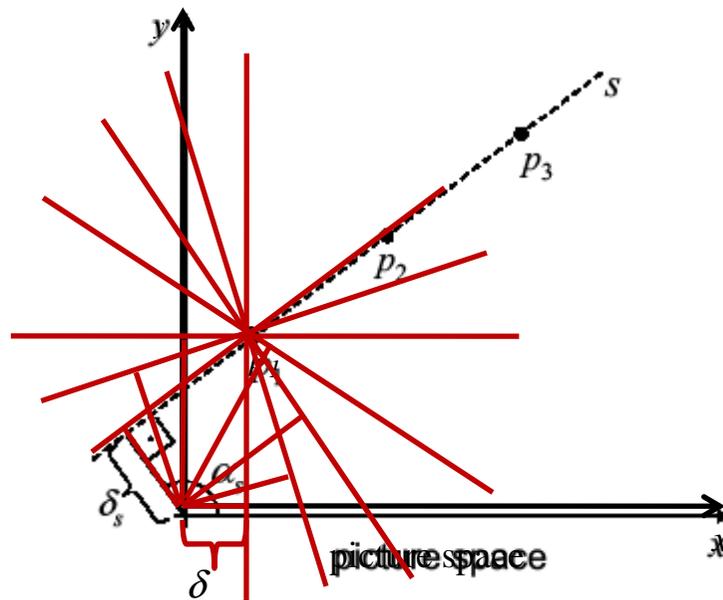


Correlation Clustering Based on the Hough-Transform

- Hough-transform:
 - developed in computer-graphics
 - 2-dimensional (image processing)
- CASH: **C**lustering in **A**rbitrary **S**ubspaces based on the **H**ough-Transform [ABD+08]
 - generalization to d -dimensional spaces
 - transfer of the clustering to a new space (“Parameter-space” of the Hough-transform)
 - restriction of the search space
(from innumerable infinite to $O(n!)$)
 - common search heuristic for Hough-transform: $O(2^d)$
→ efficient search heuristic

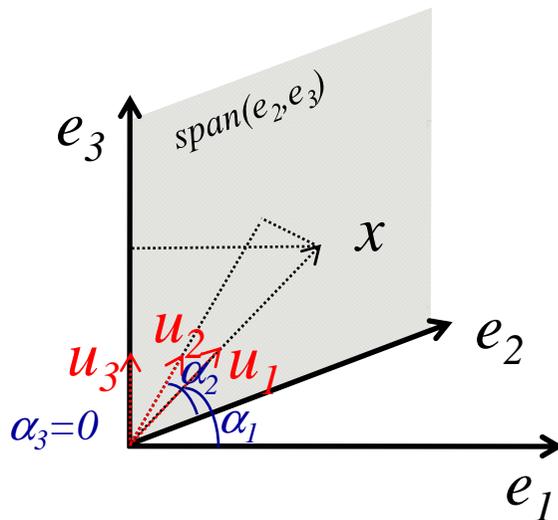
Correlation Clustering Based on the Hough-Transform

- given: $D \subseteq \mathbb{R}^d$
- find linear subspaces accommodating many points
- Idea: map points from data space (picture space) onto functions in parameter space



Correlation Clustering Based on the Hough-Transform

- e_i , $1 \leq i \leq d$: orthonormal-basis
- $x = (x_1, \dots, x_d)^T$: d -dimensional vector onto hypersphere around the origin with radius r
- u_i : unit-vector in direction of projection of x onto subspace $\text{span}(e_i, \dots, e_d)$
- $\alpha_1, \dots, \alpha_{d-1}$: α_i angle between u_i and e_i

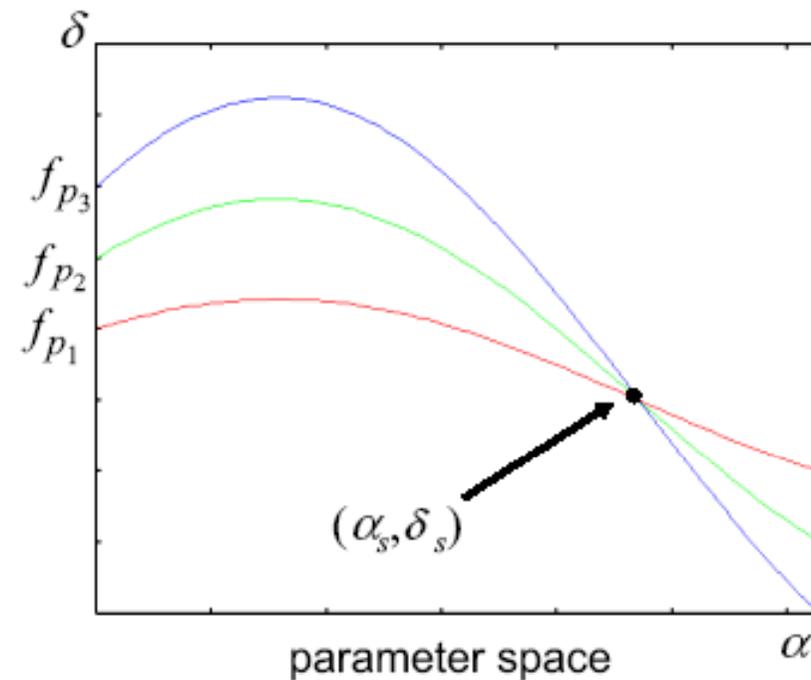
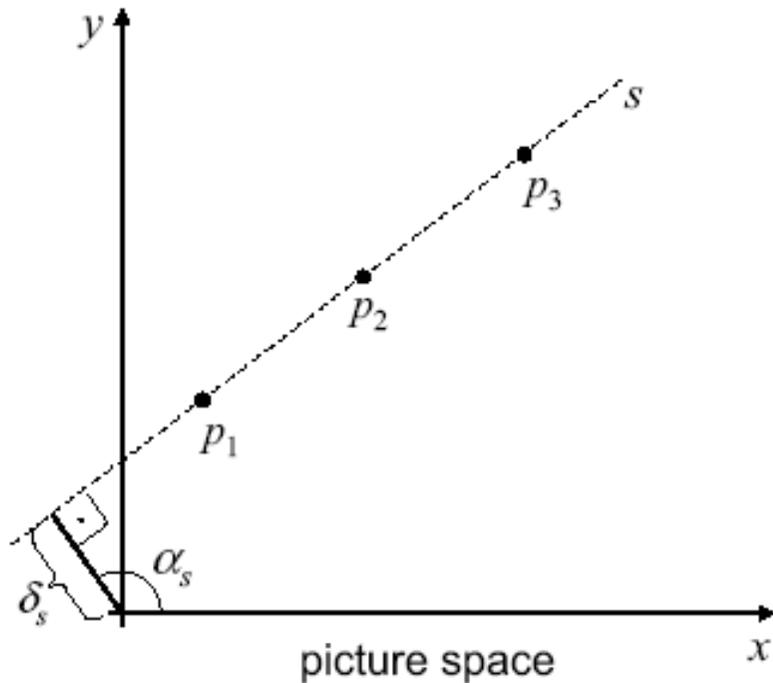


$$x_i = r \cdot \left(\prod_{j=1}^{i-1} \sin(\alpha_j) \right) \cdot \cos(\alpha_i)$$

Correlation Clustering Based on the Hough-Transform

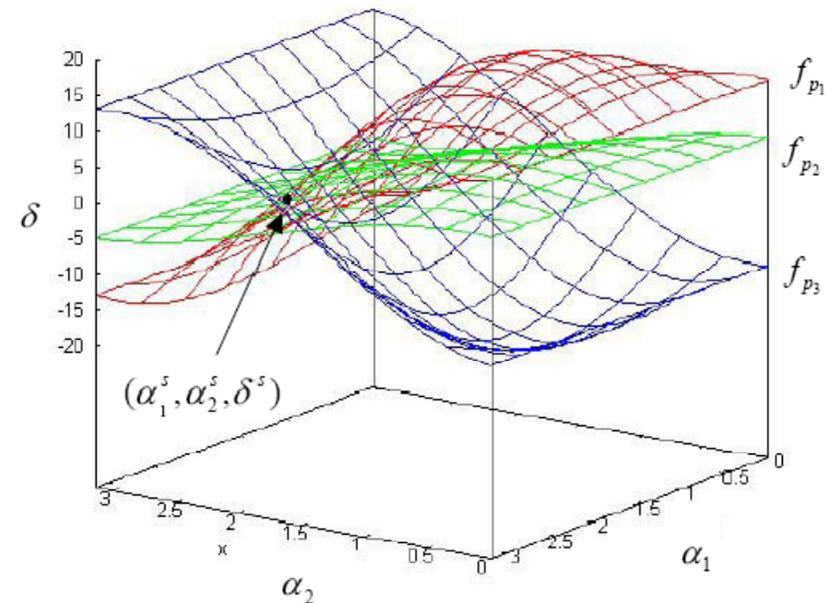
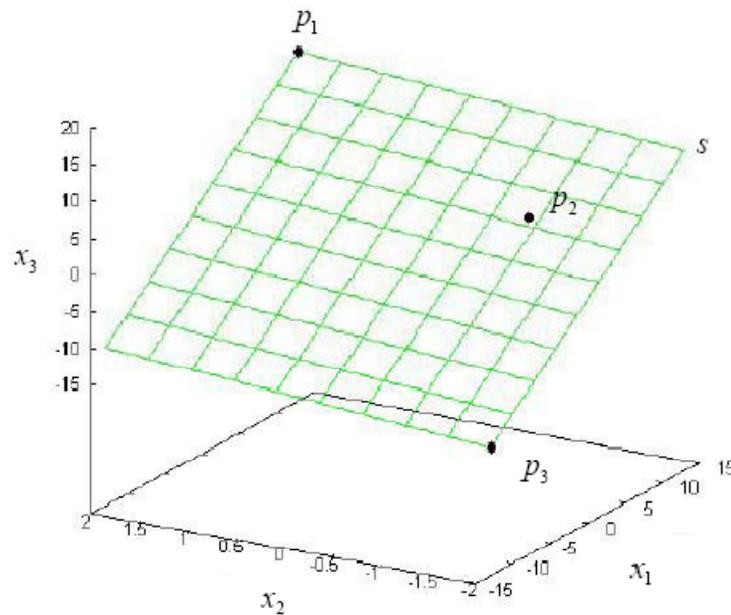
Length δ of the normal vector $\delta \cdot \vec{n}$ with $\|\vec{n}\| = 1$ and angles $\alpha_1, \dots, \alpha_{d-1}$ for the line through point p :

$$f_p(\alpha_1, \dots, \alpha_{d-1}) = \langle p, n \rangle = \sum_{i=1}^d p_i \cdot \left(\prod_{j=1}^{i-1} \sin(\alpha_j) \right) \cdot \cos(\alpha_i)$$



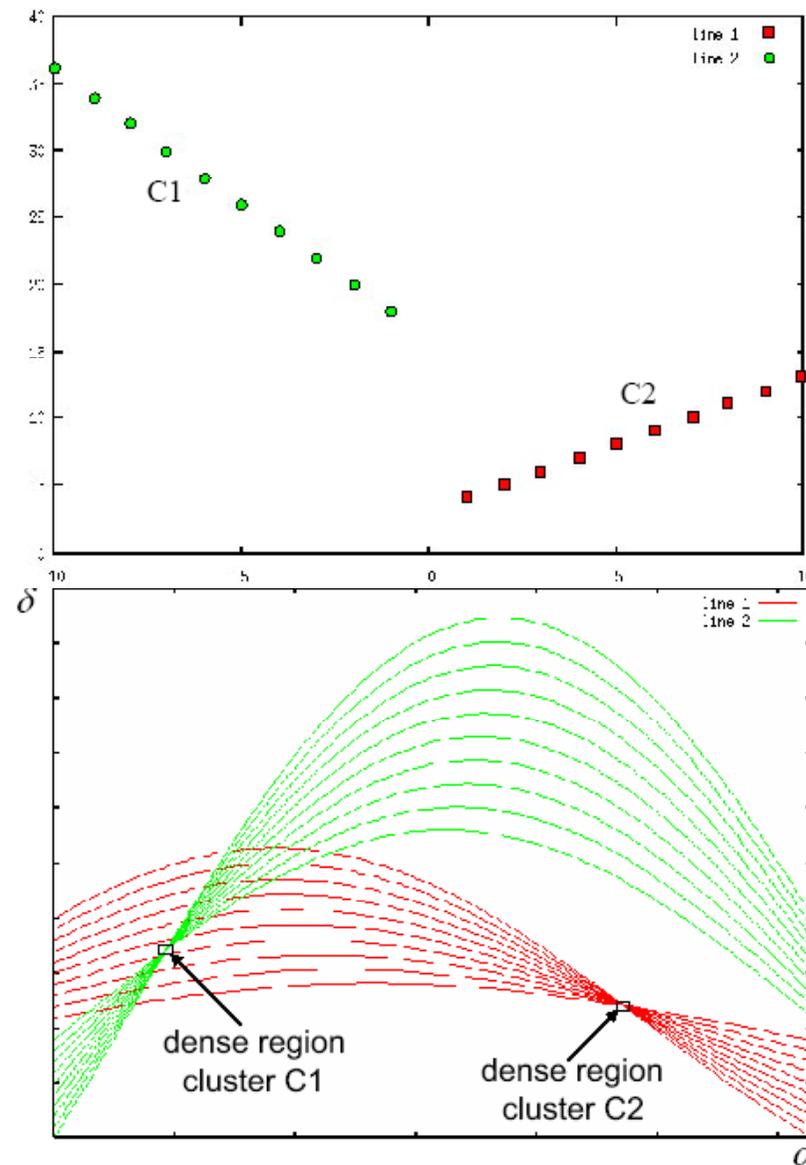
Correlation Clustering Based on the Hough-Transform

- Properties of the transformation
 - Point in the data space = sinusoidal curve in parameter space
 - Point in parameter space = hyper-plane in data space
 - Points on a common hyper-plane in data space = sinusoidal curves through a common point in parameter space
 - Intersections of sinusoidal curves in parameter space = hyper-plane through the corresponding points in data space



Correlation Clustering Based on the Hough-Transform

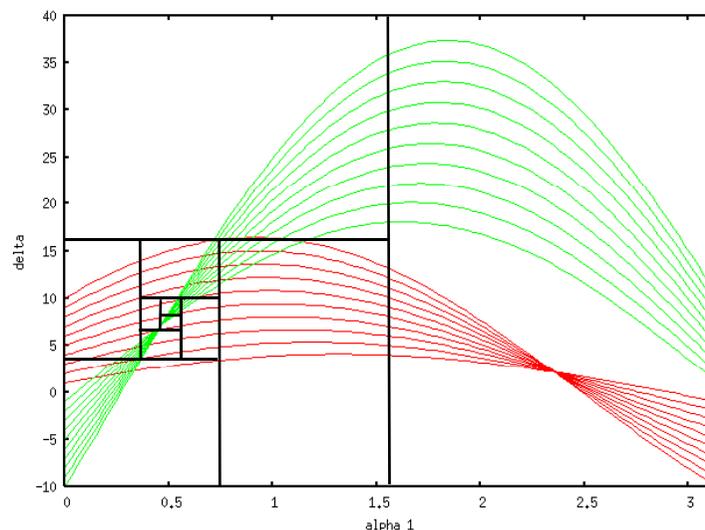
- dense regions in parameter space \Leftrightarrow linear structures in data space (hyperplanes with $\lambda \leq d-1$)
- exact solution: find all intersection points
 - infeasible
 - to exact
- approximative solution: grid-based clustering in parameter space
 - \rightarrow find grid cells intersected by at least m sinusoids
 - search space bounded but in $O(r^d)$
 - pure clusters require large value for r (grid solution)



Correlation Clustering Based on the Hough-Transform

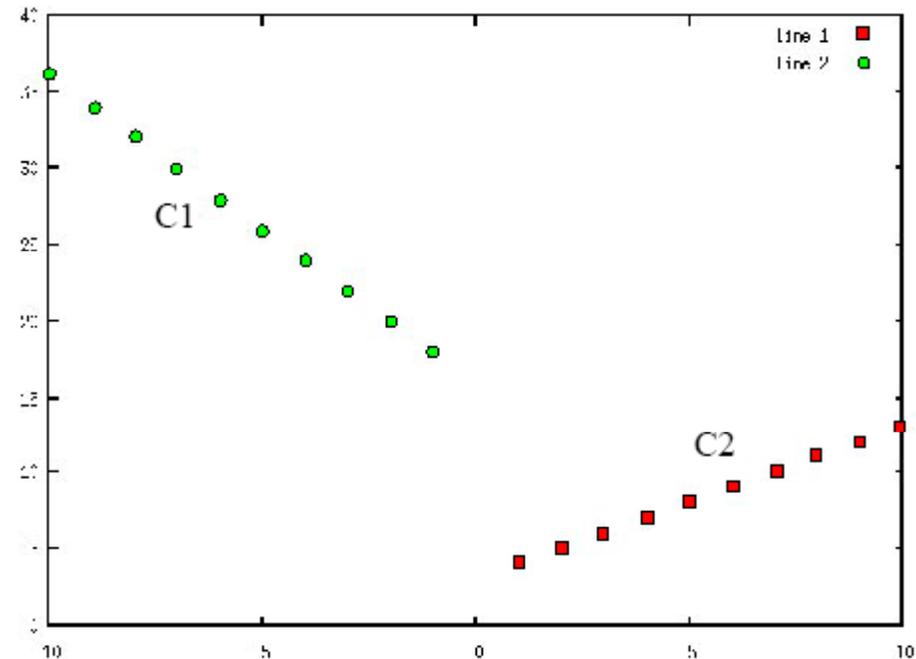
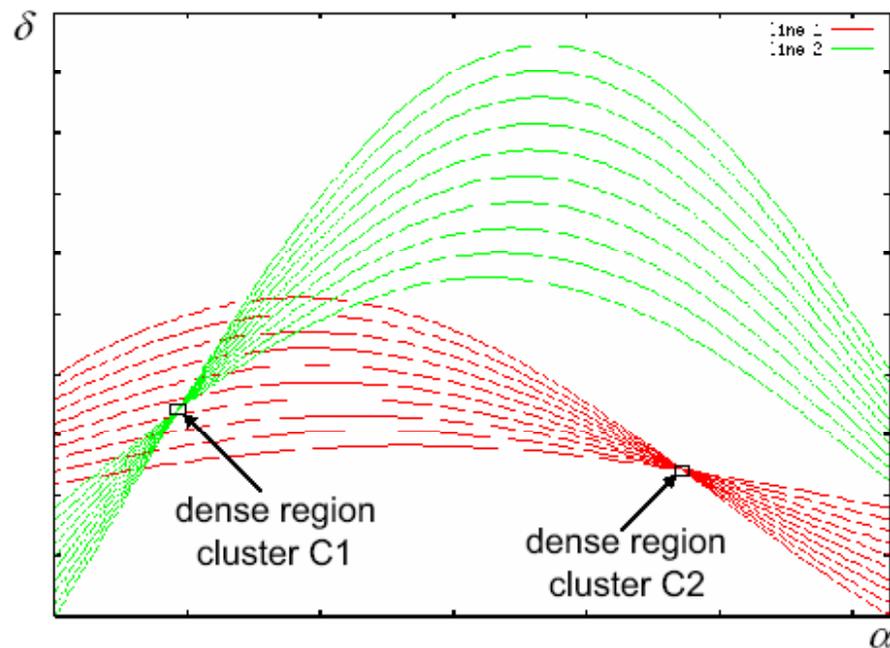
efficient search heuristic for dense regions in parameter space

- construct a grid by recursively splitting the parameter space (best-first-search)
- identify dense grid cells as intersected by many parametrization functions
- dense grid cell represents $(d-1)$ -dimensional linear structure
- transform corresponding data objects in corresponding $(d-1)$ -dimensional space and repeat the search recursively



Correlation Clustering Based on the Hough-Transform

- grid cell representing less than m points can be excluded
→ early pruning of a search path
- grid cell intersected by at least m sinusoids after s recursive splits represents a correlation cluster (with $\lambda \leq d-1$)
 - remove points of the cluster (and corr. sinusoids) from remaining cells



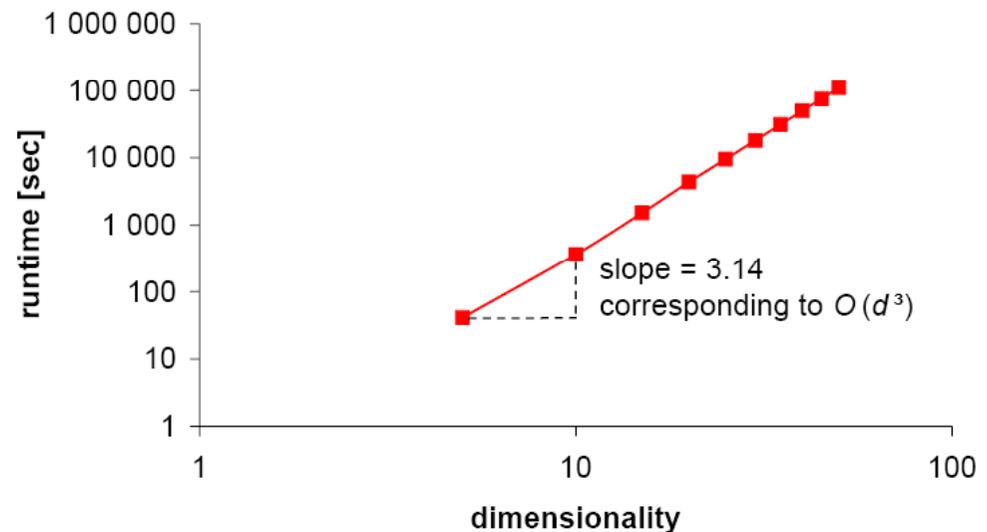
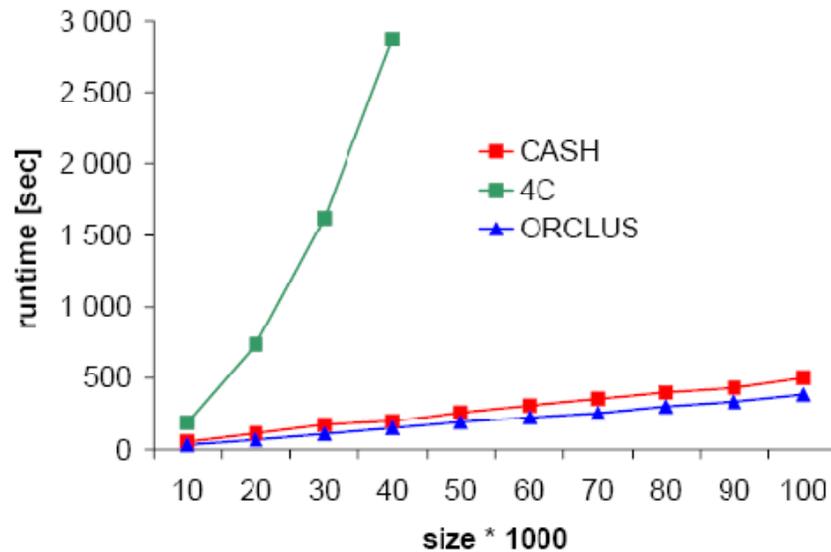
Correlation Clustering Based on the Hough-Transform

properties:

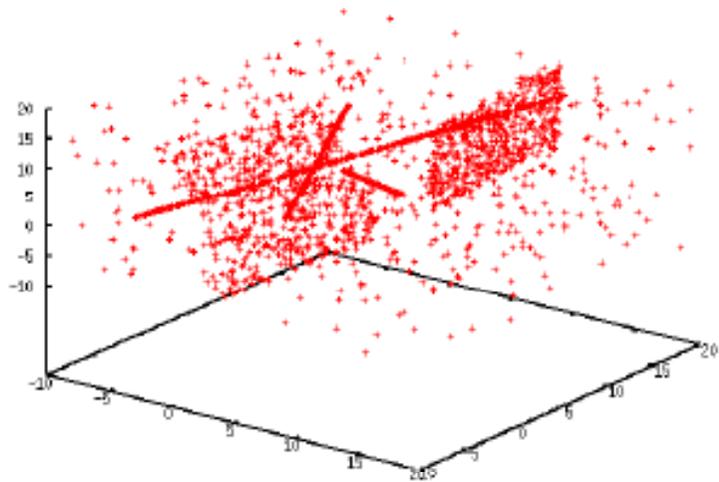
- finds arbitrary number of clusters
- requires specification of depth of search (number of splits per axis)
- requires minimum density threshold for a grid cell
- Note: this minimum density does not relate to the locality assumption: CASH is a global approach to correlation clustering

Correlation Clustering Based on the Hough-Transform

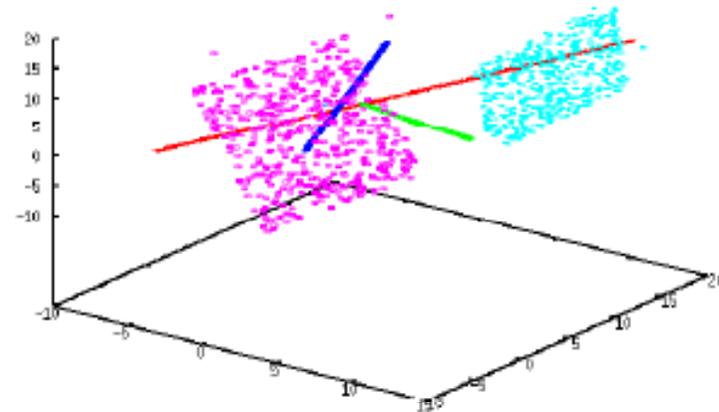
- search heuristic: linear in number of points, but $\sim O(d^3)$
depth of search s , number c of pursued paths (ideally: c cluster):
 - priority search: $O(s \cdot c)$
 - determination of curves intersecting a cell: $O(n \cdot d^3)$
 - overall: $O(s \cdot c \cdot n \cdot d^3)$
(note: PCA generally in $O(d^3)$)



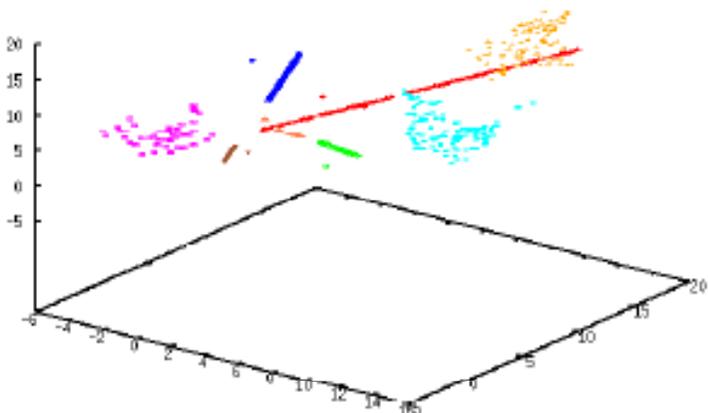
Correlation Clustering Based on the Hough-Transform



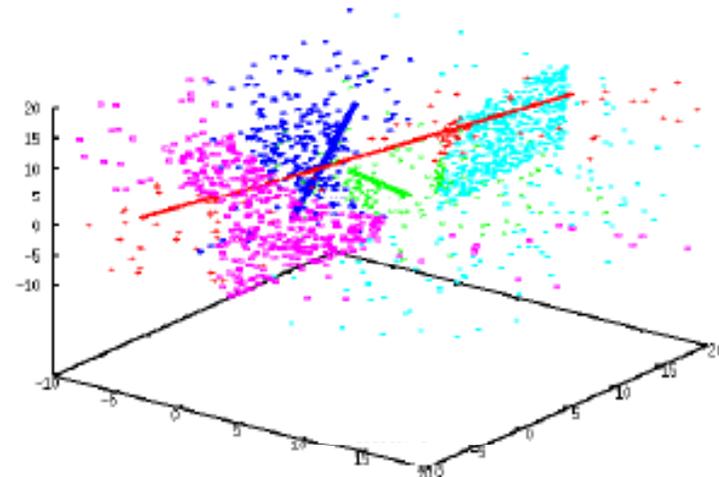
(a) Data set



(b) CASH: Cluster 1-5



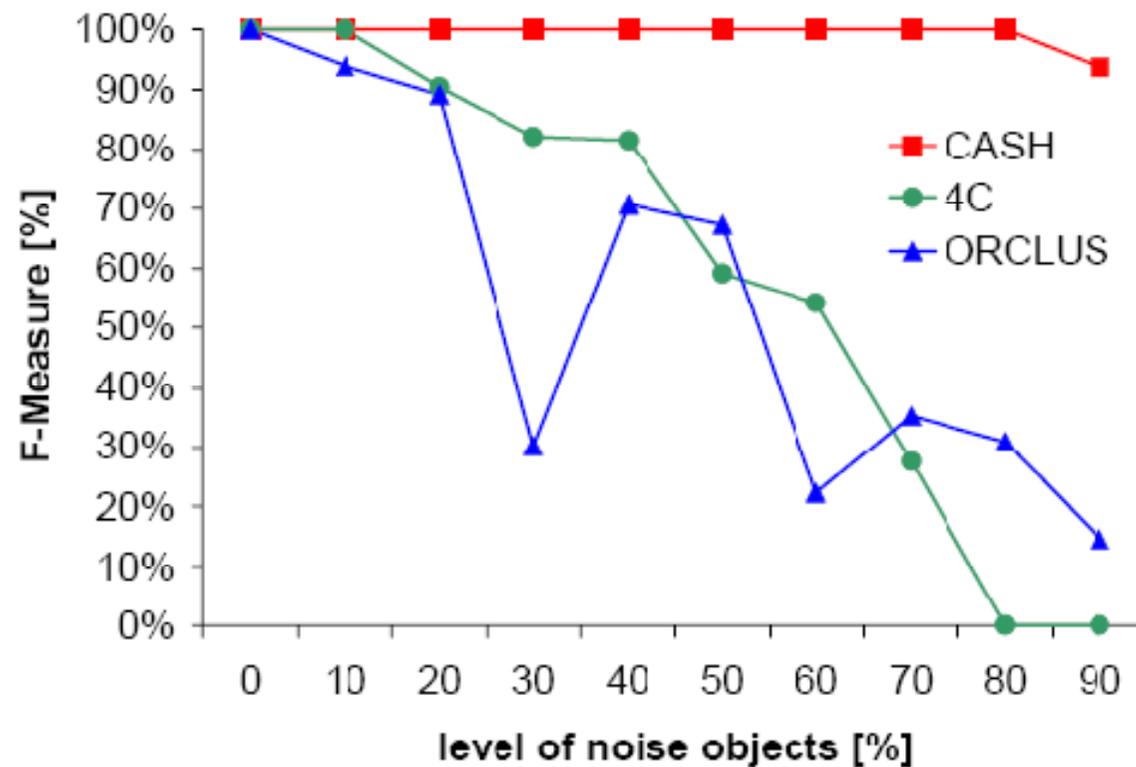
(c) 4C: Cluster 1-8



(d) ORCLUS: Cluster 1-5

Correlation Clustering Based on the Hough-Transform

- stability with increasing number of noise objects



Summary and Perspectives

- PCA: mature technique, allows construction of a broad range of similarity measures for local correlation of attributes
- drawback: all approaches suffer from locality assumption
- successfully employing PCA in correlation clustering in “really” high-dimensional data requires more effort henceforth
- new approach based on Hough-transform:
 - does not rely on locality assumption
 - but worst case again complete enumeration

Summary and Perspectives

- some preliminary approaches base on concept of self-similarity (intrinsic dimensionality, fractal dimension):
[BC00,PTTF02,GHPT05]
- interesting idea, provides quite a different basis to grasp correlations in addition to PCA
- drawback: self-similarity assumes locality of patterns even by definition

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